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A method and tool for assessing object-oriented projects and metrics management [☆]

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Abstract

The number of metrics and tools for the assessment/control of object-oriented project is increasing. In the last years, the effort spent in defining new metrics has not been followed by a comparable effort in establishing methods and procedures for their systematic application. To make the investment on project assessment effective, specific methods and tools for product and process control have to be applied and customized on the basis of specific needs. In this paper, the experience of the authors cumulated in interpreting assessment results and defining a tool and a method for the assessment of object-oriented systems is reported. The tool architecture and method for system assessment provide support for: (1) customizing the assessment process to satisfy company needs, project typology, product profile, etc.; (2) visualizing results in an understandable way; (3) suggesting actions for tackling with problems; (4) avoiding unuseful interventions and shortening the assessment analysis; (5) supporting metrics validation and tuning. The tool and method have been defined in years of work in identifying tool features and general guidelines to define a modus operandi with metrics, with a special care to detect analysis and design problems as soon as possible, and for effort estimation and prediction. In this line, a specific assessment tool has been built and used as a research prototype in several projects. © 2000 Elsevier Science Inc. All rights reserved.

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1. Introduction

The object-oriented paradigm (OOP) is considered one of the most interesting paradigms for its promises about reusability, maintainability, capability for programming “in the large”, etc. These features are not automatically obtained by using the OOP, even if an object-oriented methodology supporting all features of the OOP, such as inheritance, polymorphism, aggregation, association, etc., is used. To this end, the introduction of the object-oriented technology must be accompanied by a corresponding effort to establish mechanisms for controlling the development process (Nesi, 1998).

In order to control the development process, metrics for evaluating system features are fundamental. Their validation and interpretation are tasks frequently much more complex than their evaluation. Reference values, views, histograms, and graphs are typically used. However, without the support of a methodology for their adoption and interpretation they are frequently abandoned or misused. In many cases, the relationships among reference values for attended features and the estimated values of metrics may depend on the application domain, the development tool, libraries used, the implementation language, etc. Obviously, each feature must be directly or indirectly measurable and suitable actions for its achievement must be identified.

During system assessment, different views, profiles, and histograms of the same entity/class can be required either from different people involved in the project (project and task managers, developers, etc.) or from the same people in different phases of the development life-cycle or for different purposes. These views must be focussed on highlighting different aspects. Measured values are typically compared against minimum,

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maximum and typical values defined for the development phase under observation on the basis of the product profile required. These have to be defined by the company on the basis of their experience and needs.

The growing attention on the process of software development has created the need to get process-oriented information and to integrate metrics into the software development process. Furthermore, it is also important to create an integrated environment for software development (editing, navigating among classes, measuring, etc.) and to perform project-oriented *tailored* measures, owing to the presence of many differences among projects by the same company. This means that it is important for a company to tune the assessment methodology for different types of projects and languages. This process of tuning is usually performed by adjusting weights, thresholds, and profiles (Henderson-Sellers et al., 1994; Nesi and Querci, 1998).

Some studies with metrics and measurement frameworks for object-oriented systems have been presented in Laranjeira (1990), Meyer (1990), Henderson-Sellers (1991, 1993), Coulangue and Roan (1993), Li and Henry (1993), BritoeAbreu et al. (1995), Nesi and Campanai (1996), Bucci et al. (1998), Fioravanti et al. (1998a,b), Nesi and Querci (1998), and Zuse (1994), where general concepts for the estimation of system size, complexity, and reuse level have been proposed together with many other metrics. Unfortunately, the effort for defining new metrics has not been supported by the implementation of assessment tools and methodologies.

This paper reports the description of a method and tool named TAC++ (tool for the analysis of C++ code and metrics) for the assessment of object-oriented systems. TAC++ is a research tool by means of which several experiments on metric assessment and definition have been performed. TAC++ has been developed for studying the metric behavior during the development process, and it is capable of estimating more than 200 metrics. The method and tool have been derived by the experience in metrics definition and validation, assessment results interpretation, for product assessment in several small- and medium-size industrial and academic object-oriented projects in the last 10 years (Nesi, 1998; Butera et al., 1998; Bellini et al., 1999). Details about the

defined metrics and their validation can be found in Fioravanti et al. (1998a,b), Bucci et al. (1998), and Nesi and Querci (1998).

Table 1 shows the profiles of some real projects in chronological order: TOOMS, a CASE tool to specify, verify, test and assess real-time systems; ICOOMM, a computerized numerical control for milling machines; QV, a library providing a uniform object-oriented support for MOTIF and X; LIOO, a lectern/editor for music scores reused as the basis for project MOODS; ICCOC, ESPRIT HPCN project, a distributed system for integrating CAD/CAM activities on numerical control machines; MOODS, ESPRIT HPCN project, a distributed system of music lecterns for orchestras and music schools; MUPAAC, ESPRIT HPCN project, a distributed system of control based on Ethernet, PCI and CANBUS.

Most of these projects were carried out by using heterogeneous teams, in the sense that they included people from

1. some industries,
2. the University of Florence, and
3. CESVIT (high-tech agency) research center.

Although the project partners were in separate locations, the heterogeneous task/subtask teams were constrained to work in one place to improve the homogeneity of results, i.e., by using the same “quality manual”: reference document that contained all the guidelines for project development according to the defined general criteria.

This experience has also been condensed in an assessment methodology that consists of a *modus operandi* to work with metrics in order to detect analysis and design problems, and for effort estimation and prediction. The approach suggests modalities for interpreting metrics results and for the validation and tuning of metrics. Criticisms about the adoption of specific diagrams explaining their semantics and relationships are also reported. These may be used for providing a clearer picture of the system under assessment. TAC++ tool supports and integrates the assessment methodology including an algorithm to reduce complexity in managing the typically large amount of numerical results and diagrams that are

Table 1

Main figures of some referred projects: NCL, number of system classes; for some of the above projects several versions have been assessed during their development

Project	Operating system	Language	Tools & libs	NCL
TOOMS	UNIX, LINUX	C++	Lex/Yacc, CommonView	204
ICOOMM	Windows NT	C++	MFC	193
QV	UNIX	C++	XLIB, Motif	65
LIOO	DOS-LINUX	C++	Lex/Yacc, XVGAlib	165
ICCOG	Windows NT	C++/Java	MFC, JDK	80
MOODS	LINUX, HPUNIX	C++	Lex/Yacc, XVGAlib	253
MUPAAC	WinNT, WinCE, DSP	C/C++	MFC	180

produced and have to be analyzed during system assessment.

The main contributions of the paper are:

- the architecture and the detailed solutions of TAC++ tool;
- the mechanisms for the identification and the representation of bounds in diagrams, their meaning and analysis;
- the adoption of normalized histograms and related reference distributions;
- the integration between metric estimation, validation and tuning;
- an algorithm for managing the large amount of diagrams and profiles and its validation for shortening the assessment time.

TAC++ and the related methodology provide support for:

1. customizing the assessment process to satisfy company needs, project typology, product profile, etc.;
2. defining new high-level metrics for assessment customization;
3. visualizing results in an understandable way;
4. navigating on system hierarchies and structure;
5. suggesting actions for solving problems;
6. defining and visualizing profiles, histograms, and views;
7. avoiding useless interventions and analysis on the basis of simple bounds;
8. supporting metrics validation and tuning via statistic analysis techniques;
9. reasoning about the evolution of metrics, views, histograms, profiles, etc., along the life-cycle;
10. supporting the user in navigating on the whole information produced during the assessment, controlling project evolution by using reference/threshold values, shortening the assessment process by automating some of its parts;
11. collecting real data such as effort, faults, etc.

The needs of automatically estimating metrics producing visual representations of results for facilitating their interpretation and highlighting their relationships have been the basis for the study and the implementation of TAC++.

This paper is organized as follows. In Section 2, a short overview of the object-oriented metrics mentioned in the rest of the paper is reported.

In order to make this paper more readable, in Appendix A, a glossary of cited metrics is reported in Table 9.

In Section 3, the overview of TAC++ architecture is reported. TAC++ presents two main areas. The first area, discussed in Section 4, includes the estimation, the definition, and the validation and the tuning of metrics. The estimation phase includes the evaluation of code metrics and the collection of data from other sources: documents, time sheets, etc. The second part, discussed

in Section 5, includes the interpretation of results by means of the support of several diagrams and their related reference values and shapes according to rules, criticisms and guidelines. In this part, the adoption of normalized histogram distributions for problem detection is presented. The same section includes an algorithm to semi-automatically perform the system assessment. The above aspects are discussed on the basis of results and examples taken from the above mentioned projects. An example of the algorithm proposed for the semi-automatic assessment is also proposed considering real data. Conclusions are drawn in Section 6.

2. Overview of object-oriented metrics

Before beginning the description of TAC++ tool and methodology, an overview of some of the most significant object-oriented metrics categories is given.

In general, metrics can be direct or indirect. *Direct* metrics should produce a direct measure of parameters under consideration, e.g., the number of the lines of code (LOC) for estimating the program length in terms of LOC. *Indirect* metrics are usually related to high-level features, e.g., the number of system classes can be supposed to be related to the system size by means of a mathematical relationship, while LOC (as indirect metric) is typically related to development effort. Thus, the same measure can be considered as a direct and/or an indirect metric depending on its adoption. Indirect metrics have to be validated for demonstrating their relationships with the corresponding high-level features (reusability, effort, etc.). This process consists in

1. evaluating parameters of metrics (e.g., weights and coefficients),
2. verifying the robustness of the identified model against real cases.

The model can be linear or not, and it must be identified by using both mathematical and statistical techniques, e.g., Zuse (1994), Rousseeuw and Leroy (1987), Nesi and Querci (1998), Schneidwind (1992), Schneidwind (1994), Kemerer and Slaughter (1999), Briand et al. (1998a,b,c, 1999a), Zuse (1998), and Basili et al., 1996.

In Sections 2.1 and 2.2, some selected metrics for effort prediction and estimation, and for quality and system structure assessment, are reported. This presentation of metrics does not pretend to be an exhaustive review about object-oriented metrics since it is only oriented to present those metrics which are useful for discussing assessment methodology and tool in the following sections.

2.1. Effort estimation and prediction metrics

The cost of development is one of the main issues that must be kept under control. To this end, a linear/

non-linear relationship between software complexity/size and effort is commonly assumed. The effort can be expressed in person-months, -days or -hours needed for system development, from requirements analysis to testing or in some cases only for coding. In this way, the problem of effort evaluation is shifted into the problem of complexity or size evaluation. When software complexity evaluation is performed on code, this can be useful for controlling costs and development process efficiency, as well as for evaluating the cost of maintenance, reuse, etc. When software evaluation is performed before system building, metrics are used for predicting costs of development, testing, etc. As pointed out by many authors, traditional metrics for complexity/size estimation, often used for procedural languages, can be difficult to apply for evaluating object-oriented systems (Li and Henry, 1993; Henderson-Sellers et al., 1994; Nesi and Campanai, 1996). Several interesting studies on predicting and evaluating maintainability, reusability, reliability, and effort for development and maintenance have been presented. These relationships have been demonstrated by using validation processes (Kemerer, 1987; Henderson-Sellers, 1996; Briand et al., 1998a,b; Nesi and Querci, 1998; Basili et al., 1996; Kemerer and Slaughter, 1999).

Traditional *code metrics* for complexity/size estimation, often used for procedural languages [McCabe (McCabe, 1976; Henderson-Sellers and Edwards, 1990), *Mc*; Halstead (Halstead, 1977), *Ha*; and the number of LOC] are unsuitable to be directly applied for evaluating object-oriented systems (Henderson-Sellers et al., 1994; Nesi and Querci, 1998). By using the above procedural metrics, data structure and data flow aspects related to method parameters are neglected (Zuse, 1998). More general metrics have been defined in which the external interface of methods is also considered in order to avoid this problem.

Operating with OOP leads to move human resources from the design/code phase to that of analysis (Henderson-Sellers et al., 1994), where class relationships are identified. Following evolutionary models for the development life-cycle (e.g., spiral, fountain, whirlpool, pinball), the distinction among phases is partially lost, e.g., some system parts can be under design when others are still under analysis (Booch, 1996; Nesi, 1998). These aspects must be captured with specific metrics; otherwise, their related costs are immeasurable (e.g., the costs of specialization, the costs of object reuse, etc.).

In order to cope with the above-mentioned drawbacks, specific code metrics for evaluating size and/or complexity of object-oriented systems have been proposed (e.g., Thomas and Jacobson, 1989; Henderson-Sellers, 1991; Li and Henry, 1993; Lorenz and Kidd, 1994; Chidamber and Kemerer, 1994). Some of these metrics are based on well-known functional metrics, such as LOC, McCabe, etc. In Henderson-Sellers (1994)

and Nesi and Campanai (1996), issues regarding the external and internal class complexities have been discussed by proposing several metrics. Early metrics, such as the number of local attributes, the number of local methods or the number of local attributes and methods have been frequently used for evaluating the conformance with the “good” application of the OOP. These are unfortunately too coarse for evaluating in details the development costs (Nesi and Querci, 1998). The above metrics have been generalized and compared in Nesi and Querci (1998), by adding terms and weights opportunely estimated during a validation phase.

At *method-level* classical size and volume metrics can be profitably used. In some cases, specific metrics including also the cohesion of methods are considered, for instance, by taking into account the complexity of method parameters (Nesi and Querci, 1998). On the other hand, these metrics are only marginally more precise in estimating development effort than pure functional metrics, while they are quite useful for estimating effort for reuse.

Class-level metrics have also to take into account class specialization (*is_a*, that means code and structure reuse), and class association and aggregation (*is_part_of* and *is_referred_by*, that mean class/system structure definition and dynamic managing of objects, respectively), to assess all the characteristics of system classes. A fully object-oriented metric for evaluating class complexity/size has to consider also attributes and methods both locally defined and inherited (Nesi and Campanai, 1996; Nesi and Querci, 1998; Fioravanti et al., 1999b). These factors must be considered for evaluating the cost/gain of inheritance adoption, and that of the other relationships. Therefore, the class complexity, CC_m , is regarded as the weighted sum of local and inherited class complexities (recursively, till the roots are reached), where m is a basic metric for evaluating functional/size aspects such as, *Mc*, LOC, *Ha*. This is a generalization of the metrics proposed in Thomas and Jacobson (1989), Henderson-Sellers (1991), and Chidamber and Kemerer (1994):

$$\begin{aligned}
 CC_m = & w_{CACL_m} CACL_m + w_{CMICL_m} CMICL_m \\
 & + w_{CL_m} CL_m + w_{CACI_m} CACI_m \\
 & + w_{CMICI_m} CMICI_m + w_{CI_m} CI_m,
 \end{aligned} \tag{1}$$

where $CACL_m$ is the class attribute complexity local, $CACI_m$ the class attribute complexity inherited, $CMICL_m$ the class method interface complexity of local methods; $CMICI_m$ the class method interface complexity of inherited methods; CL_m class complexity due to local methods; CI_m class complexity due to inherited methods (e.g., complexity reused). In this way, CC_m takes into account both structural (attributes, relationships of *is_part_of* and *is_referred_by*) and functional/behavioral (methods, method “cohesion” by means of $CMICL_m$

and $CMICI_m$) aspects of class. In CC_m , also the internal reuse is considered by means of the evaluation of inherited members. Weights in Eqs. (1) must be evaluated by a regression analysis. In the development effort estimation, w_{CACI} is typically negative, stating that the inheritance leads to save complexity/size and, thus, effort. CC_m can be regarded as the definition of several fully object-oriented metrics based on functional metrics, of McCabe, Halstead and LOC, CC_{Mc} , CC_{Ha} , CC_{LOC} , respectively (Nesi and Querci, 1998; Fioravanti et al., 1999a).

It should be noted that values for CC_m metrics are obtained even if only the class structure (attribute and method interface) is available. This can be very useful for class evaluation and prediction since the early phase of class life-cycle. The weights and the interpretation scale must be adjusted according to the phase of the system life-cycle in which they are evaluated as in (Nesi and Campanai, 1996; Nesi and Querci, 1998; Fioravanti et al., 1999a).

CC_m metric can also be used for the complexity/size prediction since the detailed phase of analysis/early phases of design, i.e., when the methods are not implemented: CI and CL are zero. In that case, CC_m is called CC'_m :

$$CC'_m = w_{CACI'_m} CACI'_m + w_{CMICL'_m} CMICL'_m + w_{CACI'_m} CACI'_m + w_{CMICI'_m} CMICI'_m. \quad (2)$$

A simpler approach is based on counting the number of local attributes and methods (see metric $Size2 = NAL + NML$ defined by Li and Henry (1993)), as the sum of the number of attribute and methods locally defined in the class). On the other hand, the simple counting of class members (attributes and methods) could be in many cases too coarse. For example, when an attribute is an instance of a very complex class its presence often implies a high cost of method development which is not simply considered by increasing NAL of one unit. Moreover, $Size2$ does not take into account the class members inherited (i.e., reuse). For these reasons, in order to improve the metric precision, a more general metric has been defined by considering the sum of the number of class attributes and methods (NAM), both locally defined and inherited (Bucci et al., 1998).

At *system level*, several direct metrics can be defined in order to analyse the system effort, e.g.: NCL, number of classes in the system; NRC number of root classes (specifically C++); system complexity, SC_m (defined as the sum of either CC, WMC or NAM for all system classes), etc. It should be noted that if SC_m is defined in terms of CC_m , it can be estimated since the early phases of class life-cycle by using CC'_m .

Other system level metrics, such as the mean value of CC and the mean value of NAM, are much more ori-

ented to evaluate the general development behavior rather than the actual system effort.

2.2. Metrics for assessing system structure and quality

During system development, several factors should be considered in order to detect the growing of degenerative conditions in the system architecture or in the code. A system may become too expensive to be maintained, too complex to be reusable, too complex to be portable, etc. Most of these features are referred into the typical quality profile defined by the well-known ISO9126 standard series on software quality.

It is commonly believed that the object-oriented technology can be a way to produce more reliable, maintainable, portable, etc., systems. These very important features are not automatically achieved by the OOP adoption. In fact, only a “good” application of the OOP may produce indirect results on some of the quality features (Daly et al., 1995; Basili et al., 1996; Briand et al., 1998a). It is also very difficult to quantify what “good application of the OOP” means. This obviously depends on the context: language, product type (library, embedded system, applications on GUI, etc.), etc. The context also influences the measures obtained on the product and the reference product profile. Some quality features are very difficult to estimate by analyzing system code or documentation, e.g., efficiency, maturity, suitability, accuracy and security; thus, measures based on the results of testing and questionnaires are needed.

To this end, several criteria for controlling class degenerative conditions are typically based on bounds on the number of local or inherited attributes; on the number of local or inherited methods; on the number of the total number of attributes ($NA = NAL + NAI$, local and inherited attributes) or methods ($NM = NML + NMI$, local and inherited methods), etc. (see Table 9 in Appendix A).

Interesting metrics are those related to the inheritance hierarchy analysis. These lead to important assumptions about the quality of the analysis/design phases of the software development process and system maintainability, reusability, extensibility, testability, etc. In the literature, the so-called DIT, depth of inheritance tree, metric has been proposed (Chidamber and Kemerer, 1994). DIT estimates the number of direct superclasses until the root is reached. As can be easily understood, it ranges from 0 to N (where 0 is obtained in the case of root classes). Metric DIT is strongly correlated with maintenance costs (Li and Henry, 1993). This metric is not very suitable for treating the case of multiple inheritance; in fact, in the implementations reported in the literature, for the case of multiple inheritance, DIT metric evaluates the maximum value among the possible paths towards the several roots or the mean value

among the possible values. These measures are in most cases an over-simplification of the real conditions because the complexity of a class obviously depends on all the superclasses. In order to solve this problem, metric NSUP (number of superclasses) has been proposed and compared with DIT in (Bucci et al., 1998).

In order to better analyze the class relevance within the class hierarchy, the number of its direct subclasses is very important to be evaluated. To this end, the so-called NOC, number of children (Chidamber and Kemerer, 1994), metric has been defined. Metric NOC counts the number of children considering only the direct sub-classes. It ranges from 0 to N (where 0 is obtained in the case of a leaf class). Classes with a high number of children must be carefully designed and verified because their code is shared by all the classes that are deeper in the hierarchy. NSUB metric (number of subclasses, Bucci et al., 1998) counts all the subclasses until leaves are reached and, thus, it can be regarded as a more precise measure of class relevance in the system. Therefore, these metrics can be useful for identifying critical classes, and are also strongly correlated with maintenance costs as demonstrated in Li and Henry (1993). Other metrics for assessing system structure can be: NRC, number of root classes; mean value of NM; mean value of NA; mean value of CC, etc.

In general, complexity metrics (like CC, WMC, etc.) are unsuitable for evaluating comprehensibility of the system under assessment (for reuse and/or maintenance). For example, a metric that produces a general view of class understandability is CCGI (class cognitive index; Fioravanti et al., 1998a), which is defined as follows:

$$\begin{aligned} \text{CCGI} &= \frac{\text{ECD}}{\text{CC}} \\ &= \frac{\text{CACI} + \text{CACL} + \text{CMICI} + \text{CMICL}}{\text{CACI} + \text{CACL} + \text{CMICI} + \text{CMICL} + \text{CI} + \text{CL}}, \end{aligned} \quad (3)$$

where ECD is the external class description and is defined as the sum of terms related to class definition of CC metric. With CCGI it is possible to identify classes with low understandability and select classes that can be used as a “black box”. These considerations arise from the definition of the class itself that measures an index (and not a direct value that cannot be easily compared with reference values) showing how much the class is understandable by looking only at its external interface. A high value for CCGI means that ECD (class definition) is very detailed with respect to the class complexity. For example, if a class presents several small methods in its definition, then it is more understandable than a class that, having the same total complexity or size, presents a lower number of members.

In object-oriented systems assessment, it is very important to take into account all the typical relationships that characterize OOP: *is_part_of*, *is_referred_by*, *is_a* as previously stated, but also the coupling among classes/objects. This can be performed by using metrics such as CBO, coupling between objects (Chidamber and Kemerer, 1994). Several other coupling metrics have been reviewed and compared in Briand et al. (1998c, 1999a). Even metrics CC and CCGI contain some terms related to the coupling among object, i.e., CMICI and CMICL. In that case, the coupling is partially considered by means of the parameter complexity of method calling.

In order to evaluate an objective quality profile of the system under assessment, a specific set of metrics is necessary and, therefore, the number of data that have to be managed by the system manager or reviewer may become very large. Therefore, a procedure for the automatic or semi-automatic identification of degenerative conditions according to OOP, quality and company reference profile is mandatory.

3. General architecture of TAC++

The above-mentioned object-oriented metrics and many others have been used for taking under control several projects. The results produced have been compared with those obtained by other researchers (Lorenz and Kidd, 1994; Daly et al., 1995; Briand et al., 1998a,b, 1999b; Bucci et al., 1998; Chidamber et al., 1998; Fioravanti et al., 1998a,b; Nesi and Querci, 1998). In this paper, the detailed description of TAC++ tool is reported. It has been developed to automatically estimate metrics for controlling project evolution. With TAC++, the behavior of several metrics has been studied. This has given the possibility to define a suitable methodology for navigating among the large amount of measures that can be produced during the system assessment. The main technical features of TAC++ can be summarized as follows:

- to navigate on system classes and hierarchy;
- to provide a sufficient number of elementary metrics and the possibility of defining new metrics;
- to allow the validation of metrics in several manner, estimation of weights, identification of bounds;
- to allow the comparison of different metrics;
- to allow the managing of weights, bounds and typical profiles or distributions;
- to allow the differentiation of metrics on the basis of the context;
- to support the collection of real data values in constrained manner;
- to allow the analysis of the principal components of metrics;
- to allow the metric tuning and revalidation;

- to support the mechanism for the continuous improvement of system under development;
- to allow the definition of views, profiles and histograms in several forms;
- to allow the adoption of histograms for detecting unsuitable classes by normalizing them and defining typical distributions.
- to allow the analysis in times of weights, profiles, and histograms;
- to assist the assessment personnel partially automating the assessment process.

TAC++ is a research prototype that has been developed for studying the metric behavior during the development process and for controlling project evolution. It can be used by both developers and sub-system managers. The *measuring context* is considered in the definition of graphs and in allowing the manipulation of different versions of the assessment results. This is defined in terms of:

- *Development context* – system/subsystem structure (GUI, non-GUI; embedded; real-time, etc.), application field (toy, safety critical, etc.); tools and languages for system development (C, C++, Visual C++, GNU, VisualAge, etc.); development team (expert, young, mixture, small, large, to be trained, etc.); adoption of libraries; development methodology; assessment tools; etc.;
- *Life-cycle context* – requirements collection, requirements analysis, general structure analysis, detailed analysis, system design, subsystem design, coding, testing, maintenance (e.g., adaptation, porting), documentation, demonstration, testing, regression testing, number of cycle in the spiral life-cycle, etc.

Typically, in a company only a limited number of development contexts are used since consolidated procedures and tools are employed; these aspects have different influences on different metrics. A certain generalization can be performed by considering even non-strongly similar projects as belonging to the same measuring context. On the other hand, this implies to obtain a wider variance and a wider uncertainty interval. In general, the development context may be different for each subsystem. The life-cycle context has a strong influence on each measure and changes along the product development. Different subsystems may present different life-cycle contexts at the same time instant. An assessment tool has to be capable of defining different metrics set with different weights and reference values on the basis of the measuring context.

Usually, a metric may present a high number of components, but not all the terms may have the same relevance in each life-cycle context. By using statistic tools, it is possible to verify the correlation of the whole metric with respect to the real data, but also the influence of each metric term with respect to the collected effort, maintenance or other real data. Thus, the vali-

ation process may prove or disprove that the terms selected for defining the metrics are related or not to the feature to be estimated by the metric itself. In this way, a process of refinement can be operated in order to identify the metric terms which are more significant than the others for obtaining the indirect measure (Dunteman, 1989; Fioravanti et al., 1999a).

The main features of TAC++ can be divided in two areas (see Fig. 1).

The first includes the estimation, the definition, the validation and the tuning of metrics. During the validation and tuning, reference values and weights are identified. The estimation phase includes the evaluation of code metrics and the collection of data from other sources: documents, time sheets, etc., by means of the *collector*.

The second part includes the interpretation of results by means of the support of several diagrams and their related reference values and shapes according to rules and guidelines. In addition, in order to reduce the complexity and the effort for general system assessment an algorithm to semi-automatically perform the system assessment is discussed. These features are implemented in the so-called assessment assistant.

The following sections report details about the part of the tool TAC++ related to metric estimation, tuning and validation. During the presentation of TAC++ components several guidelines to work with metrics are reported for:

1. metric estimation, validation and tuning;
2. the adoption of thresholds, reference values, diagram selection, application, interpretation for detecting problems from the assessment results.

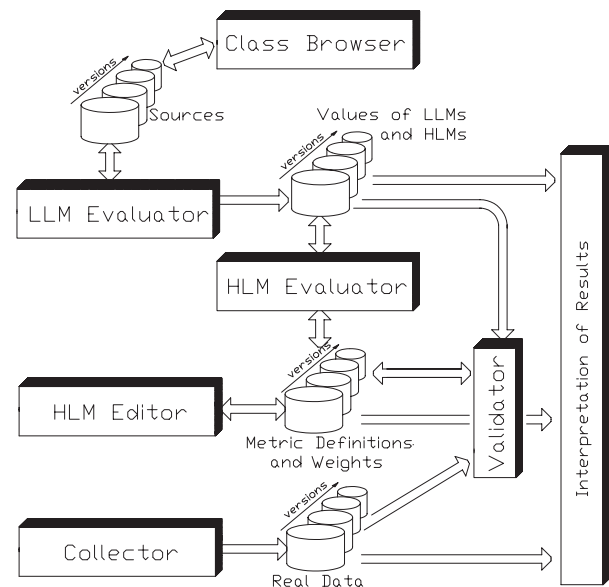


Fig. 1. TAC++ general architecture and components.

These guidelines help the users to work with TAC++ and to navigate on the huge amount of information produced during the assessment. These guidelines can be regarded as a sort of assessment methodology derived by the authors on the basis of their experience in assessing and managing several projects, in which the methodology has been used with a management methodology (Nesi, 1998), and validated against several real projects. It can be used as a basis for taking decisions during the system development. The aspects and components related to the first area are discussed in Section 4, while aspects related to visualization and interpretation of results are reported in Section 5.

4. TAC++: metric estimation, tuning and validation

In Fig. 1, the relationships among the main entities of TAC++ tool for metric definition, estimation, validation and tuning are reported. This part of the TAC++ tool is comprised of several tools for

1. evaluating low level metrics, LLMs, *LLM evaluator*;
2. defining and evaluating high level metrics, HLMs, *HLM evaluator*, *HLM editor*;
3. statistically analyzing data for validating and tuning metrics, *validator*;
4. collecting real data by programmers and subsystem managers, *collector*.

4.1. Low-level metrics and data collector

The estimation of low level metrics, LLMs, is performed on the basis of the system sources considering relationships of *is_a*, *is_part_of*, and *is_referred_by*. LLMs are simple metrics that can be estimated by counting requirements (e.g., functionalities, input/output links) or code features (e.g., tokens, LOC). For this purpose, in the literature several metrics have been proposed as discussed in the previous section, e.g., NA, NM, NAL, NML, NCL, NRC, method LOC, number of protected attributes, etc. In addition to these simple metrics, an abstract description of each class is extracted from the code. The abstract description includes all aspects of class definition and code metrics related to the implementation of methods. In this way, more complex measures can be performed by considering such information.

In this phase, the main interface of the tool is a class browser by means of which the users can navigate on class hierarchies to edit classes and to inspect them (see Fig. 2). The browser shows the list of classes with a concise description of their relationships: the class hierarchy, the list of methods, etc. By selecting a class and an its method, the corresponding method code is directly available in separate editing windows. The hierarchy tree window uses the following notation:

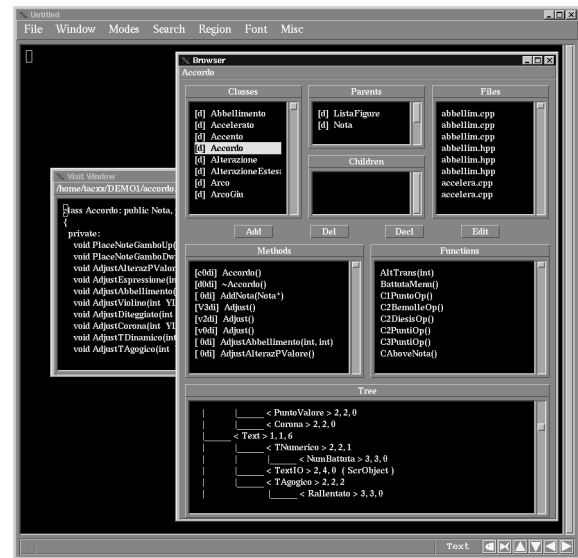


Fig. 2. TAC++ Browser.

$\langle \text{ClassName} \rangle x, y, z[(\text{OtherParents})]$, where *ClassName* is the name of the class under analysis, *x* is level number in the hierarchy tree, *y* the number of super classes (in the case of multiple inheritance the *OtherParents*, which indicate other father classes names, are reported; in that case *y* and *x* can be different), and *z* shows the number of children. The methods window gives information about the method structure according to the following terms: $[X\langle \text{listoffeatures} \rangle] \text{MethodName}$, where *MethodName* is the name of the method, *X* (if present) indicates if the method is a constructor (with *c*), destructor with *d* or virtual definition from parents (methods) with *v*, and first virtual method definition with *V*. The list of features includes: a number *n* for stating the inheritance level number of the method, *d* for locally declared methods, *i* for implemented methods, and ? for not-yet implemented methods.

In order to control the development process, several other measures that cannot be produced from the source codes have to be collected. The typical information collected relates to the effort in terms of hours of work for each class of each project, the storing of defects and the effort for their solution (corrective maintenance), effort for porting, effort for analysis, effort for design, log of testing, effort for documenting, the number of pages produced, etc. This information is stored in a database for its further analysis and for metric validation of tuning. The validation process may lead to unreliable results if the real data are badly collected. For instance, they may be affected by systematic errors, e.g., considering time for class design and coding and not for the system analysis; considering in certain cases the time spent for documenting, and/or in other cases for testing, etc. In order to reduce these problems a formally guided data *Collector* has been implemented. It constrains the

team members to fill a questionnaire each working day for collecting real data. To fill the questionnaire via WWW is faster and light. In our case, a Java application has been implemented, collector.

4.2. High level metrics

Working with metrics for controlling systems' evolution is very important to support the *definition of new metrics* for automating their estimation. The definition of new metrics is typically based on reasoning of good sense, or on the analysis of questionnaires targeted to highlight dependencies among system features and metrics that can be estimated by processing code, data definitions or documentation, e.g., effort of development with complexity, effort for coding with size, effort of maintenance with volume, quality with complexity, quality with cohesion, reusability with interface complexity. (See for example GQM, Basili et al., 1994.)

In TAC++, high-level metrics, HLMs, can be defined and evaluated. For this purpose, a visual HLM editor has been created for defining HLMs. Simple HLMs can be defined according to the following structure comprised of one or more additive terms:

$$\langle \text{NewMetricName} \rangle = W_{R_1} R_1 \frac{W_{U_1} \sum_x U_1}{W_{D_1} \sum_x D_1} + \dots + W_{R_n} R_n \frac{W_{U_n} \sum_x U_n}{W_{D_n} \sum_x D_n}, \quad (4)$$

where

- $\langle \text{NewMetricName} \rangle$ is the name given to the new metric;
- W_{m_i} are weights that can be imposed on the basis of the company experience or estimated via a validation/tuning process (see in the following section); different values of weights have to be estimated and collected according to the *measuring context* on the basis of previous projects;
- x is the context in which the sum is performed – for instance (1) on all class attributes, (2) on all class methods, (3) on all system classes; each sum can be set to operate by using the value of a single metric or imposed to be equal to 1; these metrics can be at class, system or method levels;
- R_i , U_i , D_i are LLMs or already defined HLMs.

For example, the following metrics can be defined with the above structure:

$$\text{MCC} = \frac{\sum_i^{\text{NCL}} \text{CC}_i}{\text{NCL}},$$

$$\text{MPAC} = 100$$

$$\times \frac{\sum_i^{\text{TNM}} \text{NumberOfReferredPrivateAttributes}_i}{\sum_j^{\text{TNM}} \text{NumberOfReferredAttributes}_j},$$

where MCC is the mean value of CC on the system; NCL the number of system classes; MPAC method private attribute cohesion; TNM total number of methods in the system.

Once both LLMs and HLMs are evaluated, the results can be used for assessing the system under control. Please note that, most of the above-mentioned direct metrics can produce draft results even when only the class definition is available, such as in the early analysis (e.g., NAM, *Size2* and CC). This can be very useful for predicting final values of these metrics and, thus, for predicting the final product characteristics.

Both LLMs and HLMs are collected in the same data files. Moreover, the tool is capable of exporting the data in:

1. tabular form for their import on spreadsheets, and
2. HTML format for making them public towards the development group and for browsing the results according to the hierarchical structure of the system.

4.3. Metric validation and measuring context

Metrics must be validated before their use to get results. The goal of the validation process is to demonstrate that the metrics can be suitably used as measures for estimating certain system/process features. The techniques adopted are typically based on statistical methods. The validation process has to produce confidence values (e.g., correlation, variance, uncertainty interval) for the metric in a given *measuring context* (see in the following for its definition).

The validation module is used for validation and tuning of both LLMs and HLMs. On the basis of the definition of metrics, these activities are performed by using mathematical and statistical techniques. The processes of validation and tuning must be supported by the knowledge of real data collected from developers, subsystems managers and project manager accumulated by means of the collector or other mechanisms, such as forms.

The main component of validator is the statistical analyzer. This is based on the well-known progress tool and is capable of estimating metric weights by means of a multilinear robust regression and residual analysis (Rousseeuw and Leroy, 1987), logistic regression and other statistic analyses are performed by using SPSS (principal component analysis, several tests on data, etc.). The statistical analysis is quite far from the programmers' mindset. This is due to the fact that it is the less user-friendly tool of the system, since the results are expressed in a numerical form and a deep knowledge of their meanings is needed. This knowledge is not usually required for a developer, but system managers or system controllers must be capable of interpreting and taking decisions on the basis of statistical analysis. Since the original version of progress tool presented only a textual

interface, a graphic user interface has been developed in TAC++ to make it user-friendly. In this way, the results can be easily interpreted since they are graphically visualized.

TAC++ framework with its most important metrics have been used and validated during the development of several C++ projects (both in academic and industrial contexts; Bucci et al., 1998; Fioravanti et al., 1998a,b, 1999a). Metric validation process has been performed in order to determine which metrics must be evaluated and which components are relevant (Nesi and Querci, 1998), and when metrics give good results for controlling the system's main characteristics.

On the basis of the validation process, metrics can be compared and, thus, chosen in order to adopt the best metrics for the assumed measuring context. Typically, more than one metric is used for estimating the same feature in order to get more robust results. For instance, class definition LOC, *Size2*, for predicting development and test effort since the analysis phase; and CC' , WMC for better predicting test costs during the design and coding phases.

As was shown in the technical literature, many powerful metrics include in their definition weights in order to compensate the different scale factors of the terms involved and for adjusting dimensional issues. These metrics are typically called hybrid metrics (Zuse, 1998). In some cases, the weights are imposed to be unitary, while in other cases they can be fixed on the basis of tables. McCabe cyclomatic complexity is a hybrid metric since is defined as the combination of edges and nodes with unitary weight; information flow metric in Henry and Kafura (1981), CC in this paper, metrics proposed in Thomas and Jacobson (1989) and Henderson-Sellers (1991), are others hybrid measure. Even function points and COCOMO metrics presents numbers that can be considered weights. Suitable values for the weights have been evaluated before their adoption, during a validation phase (see Fig. 1) in order to make effective the metric estimation. Once the weights are estimated, they can also be given in specific tabular forms.

Typically, the validation process is performed by means of statistic analysis techniques: multilinear regression, logistic regressions, etc. (Rousseeuw and Leroy, 1987; Hosmer and Lemeshow, 1989). Examples and theories about the validation process can be recovered in the papers Nesi and Campanai (1996, 1998), Basili (1983), Basili and Hutchens (1983), Basili and Weiss (1984), Basili et al. (1994, 1996), Albrecht and Gaffney (1983), Behrens (1983), Fioravanti et al. (1998b), Schneidwind (1992, 1994), Kemerer (1987), Li and Cheung (1987, 1993), Fagan (1986), Lorenz and Kidd (1994), Low and Jeffery (1990), Shepperd and Ince (1993), Stetter (1984) and Zuse (1994, 1998) depending on the type of information managed.

In some cases, the validation process produces the values of the metric weights. The evaluation of weights is a quite complex and critical task since it is based on the knowledge of real data, e.g., real effort, number of defects detected. For instance, the estimation of weights for the above-mentioned metric CC' (see Eq. (2)) for effort prediction implies the knowledge of the effort. This seems to be a contradiction; in effect, the weights may be estimated on the basis of the data collected during a set of similar past projects. The estimated weights can be used for effort prediction in future projects, providing that *the measuring context is equivalent*. The validation process may lead to unsuitable or unprecise results if the data collected are referred to a different *measuring context*.

For example, metric CC_m is comprised of six terms (see Eq. (1) and Table 2). Intuitively, t -value is an index that establishes the importance of a coefficient for the general model. A coefficient can be considered significant if the absolute value of t -value is greater than 1.96 (since a high number of measures have been used for the regression and, therefore, the statistic curve of student t -test can be approximated by a Gaussian curve). On the basis of t -value, the confidence intervals can be evaluated. P -value can be considered a probability; when its absolute value is lower than 0.05 the corresponding coefficient is significant with a confidence of 95%, (Rousseeuw and Leroy, 1987). Therefore, components CI_m and $CMICI_m$ are the least significant in CC_m metric and could be removed. The reduction of metric components can be used for reducing the estimation effort and, in some cases, for increasing correlation and reliability.

The F -test has been adopted in order to check the validity of the full regression model. In this example the F -test confirms that the regression results are confident. This claim is also confirmed by the high values obtained for R -squared and R -squared adjusted that are both higher than 80%.

Table 2
Results of the multilinear regression analysis for *effort evaluation* of classes by using metrics CC_{LOC} : values of weights and their corresponding confidence values are reported for project LIOO

CC	$m = LOC$			
	w	Standard error	t -value	P -value
CACL	0.003	0.001	2.933	0.004
CACI	-0.039	0.013	-2.911	0.004
CL	0.026	0.002	11.326	0.000
CI	0.001	0.003	0.269	0.789
CMICL	0.185	0.052	3.547	0.000
CMICI	-0.013	0.041	-0.319	0.750
R -squared			0.851	
R -squared adj.			0.832	
F -stat (P -value)			91.137 (0.000)	
Eff-corr.			0.924	

The *R*-squared is not the only measure for validating a good model, also because it is not always available (e.g., in analog model), or does not have the same meaning (e.g., see the meanings in logistic regression), for other validation techniques. Another approach for assessing the predictive power of an effort estimation model is the mean magnitude of relative error (MMRE), where $MRE = 100 \cdot |(realeffort - estimatedeffort) / realeffort|$.

In Table 3, the MMRE for data of Table 2 are reported together with the median magnitude of relative error (MdMRE), the standard deviation of MRE SD_{MRE} , minimum and maximum MRE: MAX_{MRE} and MIN_{MRE} , respectively.

The regression model adopted is tied to the residual analysis, and in particular to the assumption about the distribution of residuals. The residuals should be distributed as an independent normal random variable with zero mean and identical variance. In Fig. 3, the residual distribution compared against a normal(0, 1) is reported. The shape shows how the two distributions are close to each other. The distribution of residuals can be considered normal also because it has a mean value equal to 0; the skewness is 0.255 (a commonly used thumb-rule asserts that the distribution is normal if the skewness is in interval $(-0.5, 0.5)$; and kurtosis is close to 11 (with respect to 3 of a perfect normal) that shows a short-tail distribution. From this analysis, a normal distribution for residual can be assumed. Confirming the validity of the multilinear regression performed.

4.4. Metric tuning

Once the metrics are validated, they can be used for assessing projects for the specific measuring context in which the weights have been evaluated. The same metric

Table 3
Results of the MRE analysis for the data reported in Table 2

MMRE	MdMRE	SD_{MRE}	MAX_{MRE}	MIN_{MRE}
91.462	42.041	136.089	673.742	1.117

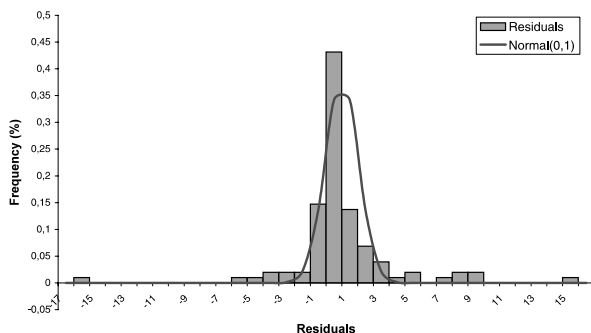


Fig. 3. Residuals distribution compared with a normal(0, 1).

can be used in different measuring contexts with different weights for similar or different purposes.

Moreover, as usually occurs, the measuring context usually changes with time, e.g., *until 1996, ELEXA factory produced controllers for low-price machines, now they are moving to produce high performance machines* (project ICOOMM). Thus, metrics have been continuously revalidated in order to adjust the weights for tracking the evolution of a set of products. For instance, once a project maintained under control with *CC'* metrics has reached its completion, predicted values can be compared with collected data. Causes of differences have to be carefully analyzed. In general, if project results are satisfactory, the collected data can be included into the values used for evaluating the general weights for the given measuring context. Otherwise, corresponding corrective actions have to be introduced.

The set of values used for evaluating the weights must be carefully analyzed in order to correctly tune the model. For instance, the analysis of outliers and the analysis of dependencies of the metric terms can be used.

In Fig. 4, the dot diagram showing the scattering between effort and class complexity is reported. In this graph, the outliers are points located out of the bound lines marking the confident limits (Rousseeuw and Leroy, 1987). The study of the outliers (values marked with letters) has to be associated with a deep analysis of the reasons for which those classes are far from the ideal correlation line (Barnett and Price, 1985; Rousseeuw and Leroy, 1987). This could be discussed together with the metric histograms. Outliers detection in single univariate sample can be easily identified, in a first approximation, because they are very different from the others values of the sample. For more structured data, and especially for regression models the concept of outlier should be modified because it is not simply an extreme value, but it has a more general pattern-disrupting form. The outlier in multilinear regression models can impact largely on the model chosen for explaining data. This fact leads to take into account outliers and robust techniques for their estimation and accommodation (Barnett and Price, 1985).

4.5. Thresholds and reference values

In order to detect the presence of system dysfunctions, the adoption of reference values is quite frequent for discriminating when a metric value describes a problem on system/component. Frequently, systems/components are considered correct if the estimated metric value belongs to the range defined within the maximum and minimum values. In some cases the typical value is also given. For example, a too high NM may mean that the class is too large and, thus, very expensive to be maintained; a too high DIT means that the system presents a deep specialization hierarchy and,

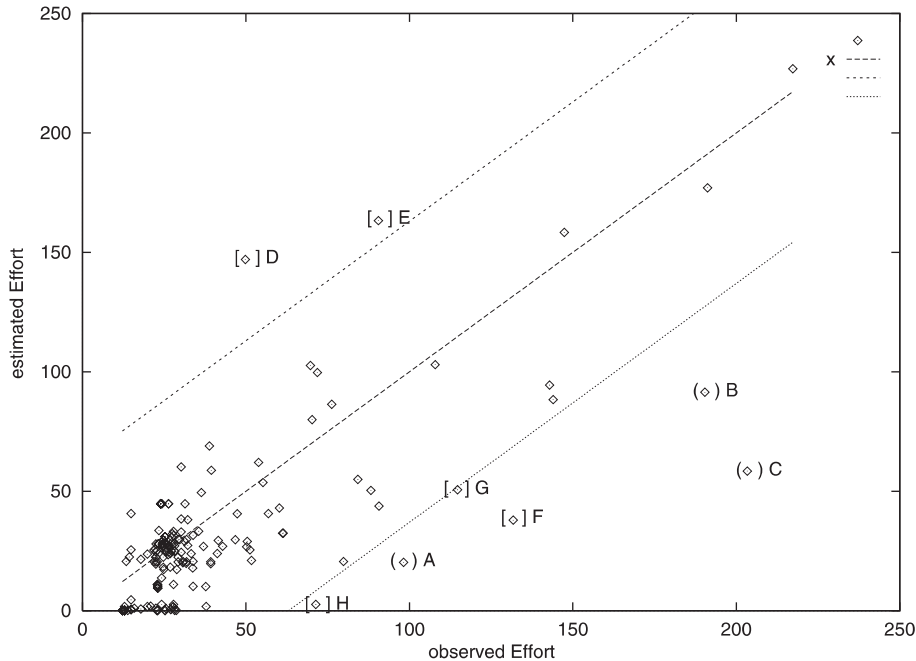


Fig. 4. Scattering diagram for CC (estimated effort) against observed effort (project LIOO).

thus, it is becoming too complex to be reused. The relationship between the metric and feature has to be proven via a validation phase.

The reference values used for detecting problems are typically set on the basis of the experience in several validation processes. In TAC++, their estimation can be performed on the basis of a statistical analysis of the reference projects and by considering the experience on past products. Thus, maximum and minimum values are evaluated for each specific measuring context.

The adoption of reference values is surely very useful for a fast detection of degenerative conditions. This approach is too simple when it is used on system level metrics. For example, assertions like “if the mean value of NM for the whole system is lower than a predefined threshold, the costs of system maintenance will be acceptable” have to be carefully accepted. Thus, getting an out-of-bounds for a specific metric for a certain class does not mean that the class has to be surely revised. Before correcting a problem, we have to be sure to have it. To this end, the results of a set of independent metrics have to be compared before deciding the intervention on a class. For example, a class can be very complex, but if it is reusable, verifiable, testable, well-documented, etc., it is better to solve other problems first, if any.

5. TAC++: results visualization and interpretation

In order to provide a fast and understandable view of the project status, the values obtained for LLMs and HLMs at system, class and method levels have to be

visualized in a set of specific views, profiles and histograms.

Fig. 5 depicts the relationships among the main components of TAC++ tool to manage these aspects: view manager, profile manager, histogram manager and assessment assistant. In Sections 5.1–5.3, the features of these components are described in detail. The views, profiles and histograms are defined and saved according to the measuring contexts for which they have been defined. These graphs can be based on the LLMs, HLMs and data collected by the collector. For this purpose, specific graphic managers have been built. During the presentation of TAC++ components, guidelines to work with interpretation tools about the adoption of thresholds, reference values, diagram selection, application and interpretation for detecting problems from the assessment results are reported. These guidelines help the users to navigate on the large amount of information managed during the assessment.

Different members of the development team may use TAC++ for different purposes. During the development life-cycle the system manager (project manager or control manager) is also supposed to analyze the results produced by evaluating selected metrics and by comparing them with the corresponding company suggested bounds (by means of profiles). The results produced and their related actions for correcting any differences with respect to the milestones planned (described in terms of the same indicators) are normally included in the project documentation. Typical actions for correcting the values of the most important indicators should also be defined in advance.

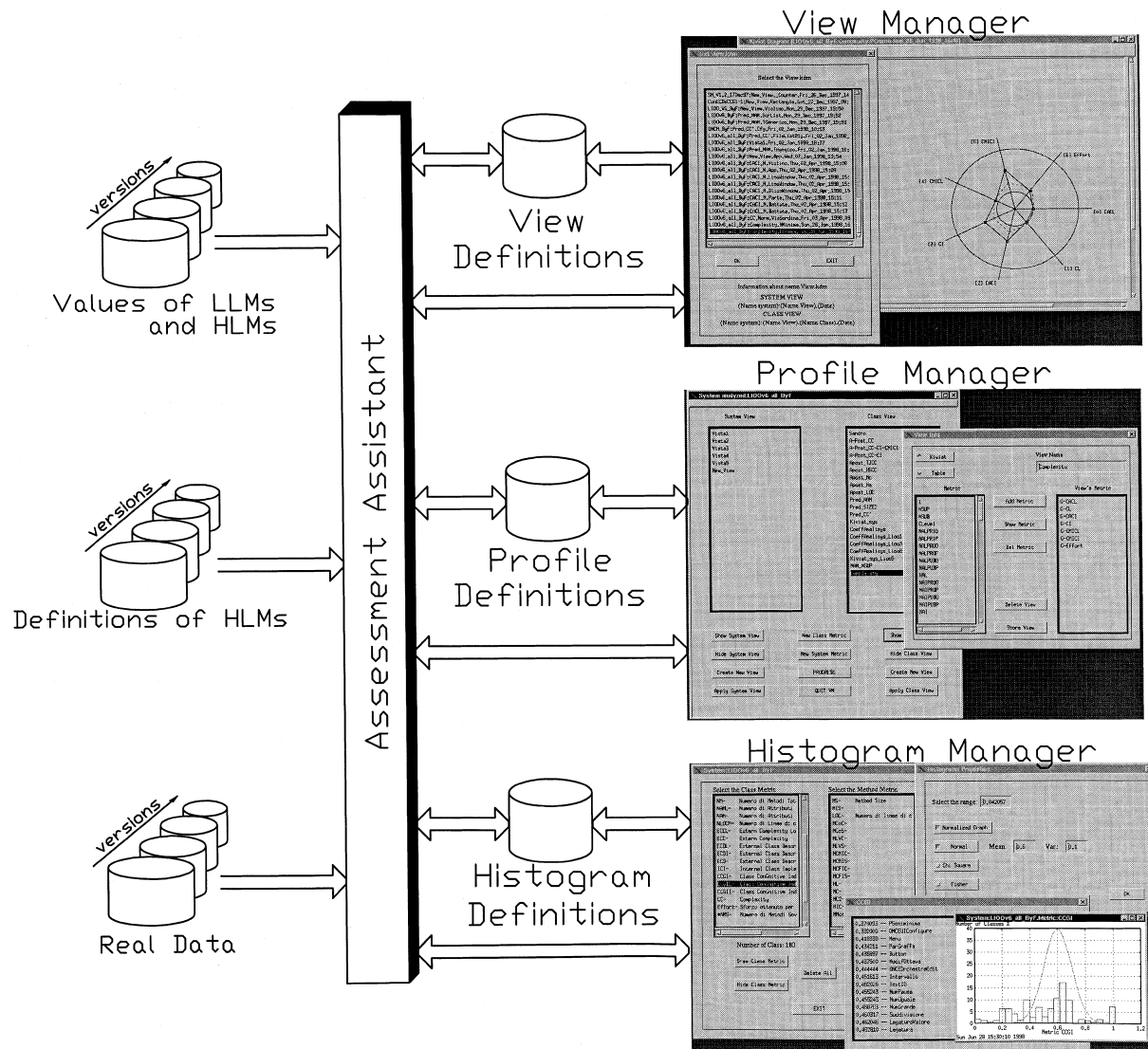


Fig. 5. TAC++: visualization of results and the assessment assistant.

For each measuring context and for each view, profile and histogram, specific textual comments should be added and shown to the user when reference values, profiles and distribution are exceeded. These also have to be collected in a development and management manual of the company. Even these comments need to be maintained and tuned according to the company evolution. The histogram manager can also draw normalized graphs (see Fig. 5) with superimposed statistic curves in order to easily check if the system under assessment is suitable with respect to the quality manual specifications of the company. Typical distributions of histograms can be assumed as reference patterns by the company. A collection of histograms among the various phases of the development life-cycle could aid the system manager to take into account the modifications, from the point of view of quality profile, of each class in the system.

The assessment assistant provides support for system assessment by means of algorithms that reduce the complexity for inspecting the results and, thus, for detecting dysfunctions, and/or performing in automatic manner some processes.

5.1. Views and profiles

Graphic diagrams, typically called views and profiles, are needed for showing the assessment results with respect to typical and/or limit values. Two distinct definitions are given for views and profiles.

A collection of different metrics representing the same or related system/class features can be used and visualized in a single *view* with respect to bounds and typical values. Views are used to have an immediate and robust figure of system features, e.g., quality, effort for

maintenance, effort for reuse, effort per subsystem, effort per work-package. The views can be employed for monitoring aspects of the system during its evolution, at methods, classes, and/or system levels. This is performed on the basis of the life-cycle context for which they are defined.

In the views, the bounds (minimum and maximum acceptable values) can be considered as the limits out of which a further analysis (and may be a correction) should be needed. In a different visualization, minimum and maximum values can be those obtained from the whole system under analysis. In this way, it is quite clear how the class/subsystem under assessment is referred to the whole system. In any case, normalized graphs are used: Kiviat, star, pie, etc. In Fig. 6, four Kiviat diagrams corresponding to four classes of LIOO project are reported. In this case, the maximum values (external circles) are evaluated on the whole system, while the dashed lines report the acceptable values estimated during the validation and imposed on the basis of the experience.

In Fig. 6, the views reported are related to classes marked as outliers in the scattering diagram of Fig. 4. From these figures, it can be noted that most of the class features are out of the typical bounds and that the picture in lower-right corner has, for CI, NMI, CMICI, and NAI, values close to the maximum of the whole system. These metrics assert that the class inherits too much.

In order to unify the actions to be performed for solving problems and for accelerating their understanding, brief comments describing what should be done in the case of out-of-bounds, have to be defined. In order to monitor class quality in project LIOO, we defined a view reporting values of metrics: NA, NM, CC_m , CCGI and NSUP. Other typical examples of views are:

1. a view on class effort prediction – $Size_2$, NAM and CC' ;
2. a view on class effort estimation – CC'_m , CC_m , WMC, CL, CI, NAM and NAML;
3. a view on effort prediction or estimation at system level – SC, TLOC, NCL, NRC and mean DIT;

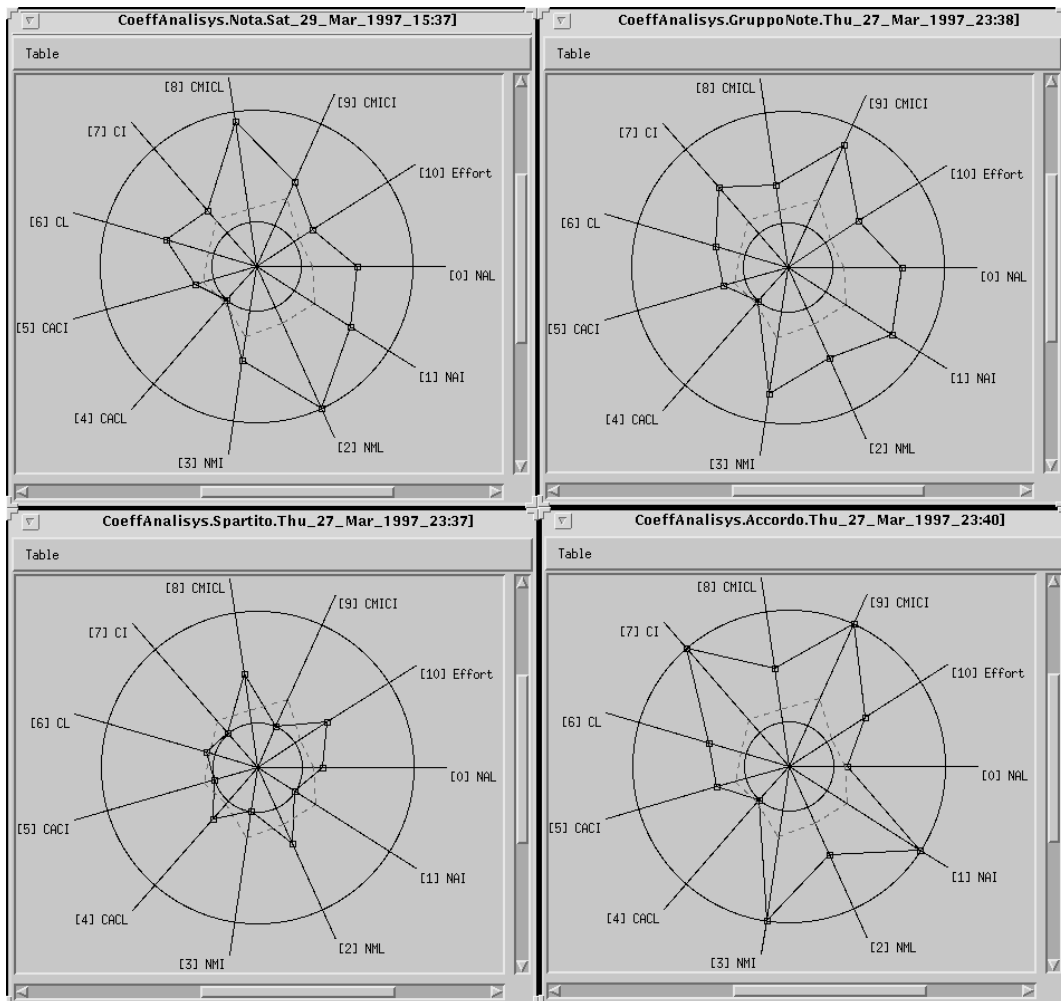


Fig. 6. Views (Kiviat's diagrams) of some of the outliers identified in the previous scatter diagram (project LIOO).

4. a view on conformity to OOP at system level – NRC, NRC/NCL, SC_m /NCL, Max(CC) and Max(NAM);
5. a view on class metrics related to reusability and maintainability – NOC, NSUP, NSUB, DIT, and NAI;
6. a view on class reusability – cognitive complexity, NAM, VI (verifiability index) and CCGI.

Typical actions to be performed when these metrics are out of the predefined bounds are discussed in Fioravanti et al. (1998a,b) and Bucci et al., 1998.

The number of these diagrams for the whole system may become huge and, thus, their analysis fairly complex up to infeasible. For this reason, algorithms for navigating in the results produced by the assessment are needed (see Section 5.3).

A *profile* is a diagram in which the estimations of the several direct and indirect metrics are compared against expected values (reference value). For example, the quality profile defined on the basis of the six features of the ISO 9126. In Fig. 7, the expected profiles are compared with the estimated profiles in a normalized scale. Profiles are typically shown by using bars or Kiviat diagrams. Profiles can be used in any instant in which planned/reference measures can be compared against the actual values (see Fig. 7 on the right, in which the effort planned for each system task is compared with respect to the actual effort). Another very important profile is the product profile. It includes material costs for each piece, general costs, market level, potential reusability, etc. The structure of profiles (the number and selection of aspects to be controlled) is typically fixed for all products of the factory/unit, while the specific reference values may change for each product, e.g., to get a customized profile.

In TAC++, both views and profiles can be defined at method, class and system levels. The structure of views and profiles with their reference values can be organized according to the *measuring context*. Thus, actions and suggestions for solving problems in the case of detection

of critical conditions can be customized for each specific case. Different views can be defined according to the needs of developers, subsystem managers and project manager (Nesi, 1998).

5.2. Histograms

At system/subsystem level, metrics can be used to analyze general system features (e.g., number of classes NCL, number of subsystems, number of root classes NRC, system complexity SC) or as generic system component behavior (e.g., mean CC, mean NA, mean NM and mean NCL for subsystem). In this second case, the views are unsuitable for detecting troubles since the mean values can be within the correct bounds, but the system may present several out-of-bounds at class level.

For this reason, it is important to analyze the distribution of each metric for the system under assessment. For example, by using histograms:

1. the number of classes for the complexity of classes;
2. the number of methods for the complexity of methods;
3. the number of classes for their CCGI;
4. the number of classes for their NSUP;
5. the number of classes for their NSUB, etc.

In Fig. 8, the histogram of CCGI for project LIOO is reported. It is typically recommended, for reuse and understandability, to have classes with a CCGI close to 0.6. This allows the developers to use the class as a “black-box”. For instance, in the example, by observing CCGI histogram, it is evident that the peak is close to the suggested value. Some classes with a too low metric value are present; these classes are not observable enough and, thus, are expensive to be maintained and reused. It is suggested to check these classes in order to verify if the high internal complexity can be justified by their role in the system. In any case, the splitting of these large classes in more classes by using the well-known mechanism of delegation should be a good solution. It is

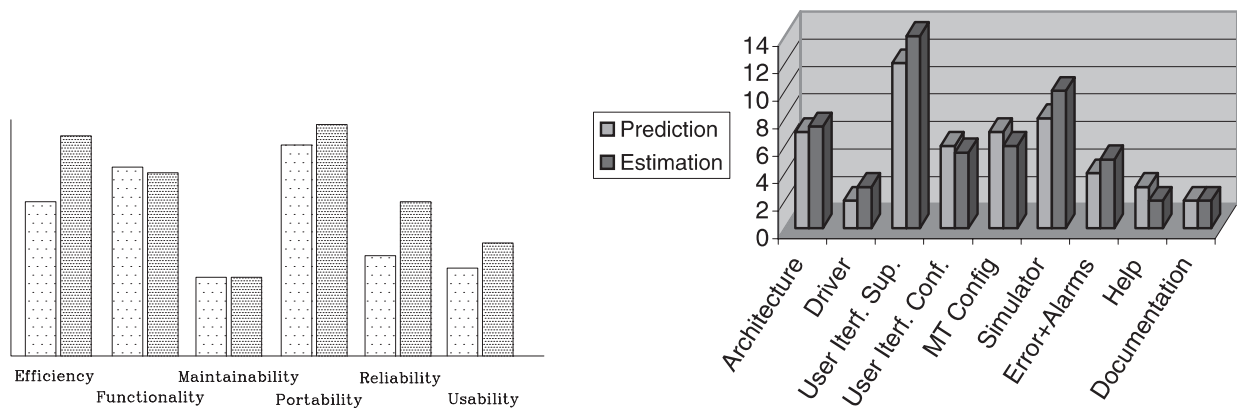


Fig. 7. On the left: project profile according to the ISO 9126 quality standard. On the right: project profile regarding predicted and estimated effort for tasks in men/month; evaluation performed close to the end of the development phase (project ICOOMM).

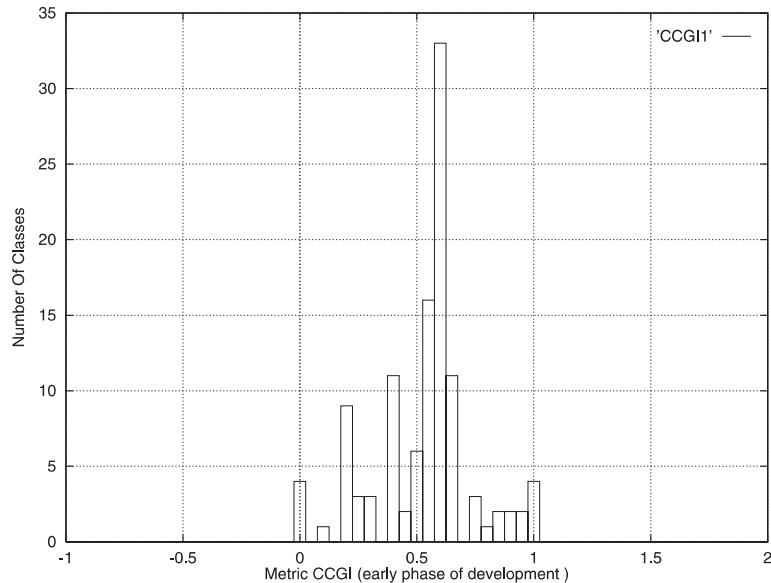


Fig. 8. Histogram for CCGI, obtained at the first checkpoint (project LIOO, version 0).

also possible to identify classes for which the functional complexity is too high with respect to the interface complexity (CCGI close to 0). Owing to the tool used for collecting data, classes having $CC = 0$ have also been collected in this group and, thus, all classes defined, but not yet implemented. Classes with $CCGI = 1$ are structures (according to C++) or have attributes and the external interface defined, but the methods are not yet implemented.

Histograms are strongly useful since the adoption of bounds for detecting problems may lead to make large errors. In fact, according to the life-cycle context some out-of-bounds for some metrics and non-well-behaved histograms (sensibly out of the reference distribution) may be accepted. For example, during the early development phase, the presence of defined but not yet implemented classes has to be accepted without considering them as wrongly implemented classes. In fact, in the early phases the number of special cases can be too high to be manually managed. This problem frequently leads the assessment personnel to wait for a quite complete version before starting with the system assessment. Specific metrics and tools may guide the assessment personnel in these phases.

The result obtained by the scatter diagrams can be better analyzed if compared with the histogram of the corresponding metric. In Fig. 9, the histogram of metric CC (estimated effort), related to the diagram of Fig. 4 is shown. If the reference distribution is a log normal curve (as will be shown in Section 5.3), only some of the classes that are outliers in the scatter diagram are also out of the typical distribution histogram. In particular, classes *H*, *D*, and *E* should be more carefully inspected in order to verify the reasons of the dysfunction and to

define action (if needed) to correct their behavior. Please note that the other classes have not been considered as affected by problems since they are within the reference histogram distribution. This means that in a system there may exist few very complex classes. These are typically called key and/or engine classes (Lorenz and Kidd, 1994; Nesi, 1998).

Histograms are a powerful tool for system assessment. In order to make histograms comparable with other systems and with reference distributions they have to be normalized. The typical distributions of the histograms for each metric have been extracted on the basis of the projects reported in the Introduction. Some typical distributions can be modeled as Gaussian, log normal curves. Normalized histogram distributions are quite independent of the development context, while are depending on the life-cycle context. In most cases, normalized histogram distributions are also independent of the languages (Lorenz and Kidd, 1994; Fioravanti et al., 1998a).

Please note that the above-mentioned views, profiles and histograms are capable of analyzing the system aspects in a given time instant and in a given life-cycle context.

In several cases, the single snapshot of the system status may produce insignificant figures. This is more critical for metrics that are very sensitive to the development life-cycle phase. The trend analysis can be performed on metrics involved in views, profiles and histograms, and is specifically needed to verify if the evolution of metrics is reaching the expected results.

In some cases, the trend analysis can be performed for predicting future values by using some extrapolation algorithm, e.g., for predicting the cost of designing

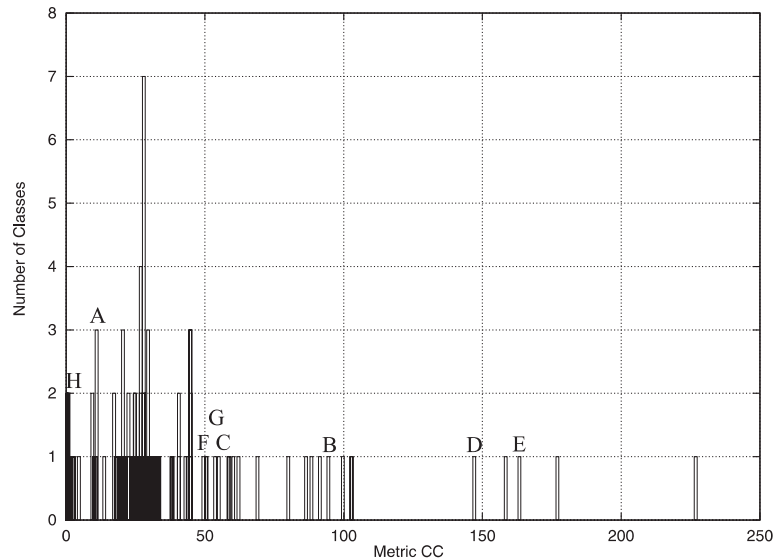


Fig. 9. Histogram of metric CC as the estimated effort, related to the scatter diagram of Fig. 4 (project LIOO).

and coding in the phase of analysis (Fioravanti et al., 1999a).

5.3. Analysis of assessment results

The process of system assessment may produce a huge amount of data, typically analyzed by inspecting profiles, views, and histograms. A manual exhaustive analysis of graphs and diagrams is a very heavy, tedious and time consuming process. Moreover, the number of detected interventions per analyzed graph is really low. This is due to the fact that typically the largest part of the problems is relegated in a small system/subsystem part. For these reasons, and for the repetitive operations that have to be performed, the probability of producing errors in identifying real problems and thus on taking decisions is quite high.

In TAC++, according to the discussions performed in the previous sections, the elements manipulated during the assessment can be defined as:

- $Class \in SubSystem, SubSystem \in System, Class \in System$.

The system can be regarded as a set of subsystems and these in turn are sets of classes. Thus, generally, classes belong to the system, without loss of generality.

- *Metrics*

These are used into views, profiles, and histograms with the associated reference bounds/distributions and weights (if any) on the basis of the measuring context and considering the feature that is intended to be estimated. Metrics formally hold only their definition since the same metric can be used for different purposes with different weights.

- $Profile \equiv \{metric \leftrightarrow (feature, reference_value, weights)\}$.

A profile is a collection of metrics related to features of class, subsystems or systems depending on its goals and on the measuring context (with reference value and weights). A profile reports the specific detailed features that have to be measured and their expected values along the software life-cycle. Profiles are more concise than views (profiles have only a reference value), thus they are more used at system or subsystem level.

- $View \equiv \{metric \leftrightarrow (feature, reference_bounds, weights)\}, \{view\ suggestions\}$.

A view is a collection of metrics related to features of classes, subsystems or systems depending on the view goals and on the measuring context. Reference bounds and weights depend on the measuring context and include minimum, maximum and typical values. A view identifies the specific detailed features that have to be measured and their expected values along the software life-cycle. The views are a more general and powerful working tool than profiles and thus can be used in their place without restriction, but not the vice versa. For each view, a set of suggestions can be associated with the presence of out-of-bounds on a set of its metrics. These suggestions can be modified by the end-users. The suggestions cannot be associated with metrics since their meaning is context-dependent and may depend on more than one metric.

- $Histogram \equiv metric \leftrightarrow (reference_distribution, weights), \{histogram\ suggestions\}$

A histogram reports the distribution of the metric behavior on the whole system/subsystem. For

each histogram, a set of suggestions can be associated with the presence of out-of-distribution. These suggestions can be changed by the end-users. The suggestions cannot be associated with metrics since their meaning is context-dependent.

For system level assessment, specific profiles are typically defined for annualizing effort, quality, etc. The collection of features analyzed via metrics depends on these profile goals. These are typically mean values of class metrics (mean CC, mean NAM, mean NAML, mean CCGI, etc.) or structural consumptive metrics (NRC, NCL, SC, etc.). In the assessment phase, the estimated values are compared with the reference values (the reference profile).

The detection of a problem (a relevant difference between expected and estimated value) by means of a system level metric may be considered as an alarm for the system life-cycle process. Once detected at system level, the same or a corresponding problem may be found into one or more subsystems. On the other hand, the lack of detectable problems in the system (subsystem) profile/view may make the general manager satisfied but does not guarantee the lack of problems in the subsystems (classes). This fact constraints subsystem managers and quality control personnel to analyze all system classes with specific views in systematic manner to look for problems.

At system level, the presence of out-of-bounds can be identified by defining specific *consumptive metrics* for reporting problems at systems (subsystem). These can be based on the results produced at lower level, subsystem (class). This can be obtained by defining metrics such as maximum value of CC among the system (subsystem) classes, maximum value of NAML among the system (subsystem) classes, etc. This kind of consumptive metrics are useful for the fast automatic detection of out-of-bounds; on the other hand, they are too simple since the presence of out-of-bounds does not always imply the needs of intervention; thus a further inspection at class level is consequently needed. On the other hand, metrics based on the mean value of class level metrics are totally unuseful since a correct mean value may hide a lot of undesirable instances of unsatisfactory values.

In the following, an algorithm for partially automating the assessment process is proposed. It has been defined for automatically combining results coming from views and histograms. This reduces the number of views that have to be analyzed during the assessment. The algorithm has been implemented into the so-called assessment assistant inside the TAC++ tool.

5.3.1. Assessment assistant algorithm

Once defined the views with their metrics on the basis of the experience and by using the results of validation phases, the set of views and related histograms can be used for system assessment in a systematic manner.

For example, if the assessment of a (sub)system is based on 4 views with 6 metrics each, and it has 1000 classes, then the tool for system assessment has to estimate 24 000 metric values. Their estimation is not a problem with the support of suitable automatic tools, but a real-time estimation is frequently needed for small projects or subsystems. The main problem is that system classes have to be analyzed by specialized personnel via 4000 views, 4 views per class. The computational complexity of an exhaustive analysis by means of views is an $O(CVM)$ (considering the comparison with the reference value as the dominant operation), where C is the number of classes per (sub)system, V the number of views per class, and M is the mean number of metrics involved in each view. Please note that a metric can be used in different views for different purposes, with different bounds. Thus, in these conditions, the complexity of the assessment process is too heavy to be performed in short time and without errors. A partial screening of the 4000 views can be performed by considering as classes that need of a further analysis only those having more than α metrics out of the suggested bounds (for instance, with the number of out-of-bounds bigger than a value, α). The value of α can be tuned according to the goals used.

In order to make the assessment process easier and faster, an algorithm has been defined and implemented. The main idea behind the algorithm is the adoption of the histogram as the main vehicle for detecting problematic classes. According to the above numerical example, the histograms to be analyzed are only 24. In order to make histograms of a (sub)system comparable with those of other (sub)systems and with the reference distributions they have to be normalized (see Fig. 10). The normalization has to be performed on both axes on the basis of the total number of classes. To this end, in the histogram:

1. X-axis is divided in to a number of *categories* for collecting classes having similar metric values and ranges from 0 to the maximum of the metric in the (sub)system or to the maximum number of categories;
2. Y-axis ranges from 0 to 1, from 0 classes per category to 1 when all classes belong to the same category.

It is possible to pass from the category to the metric value by using the scale factor, F . In Fig. 10, each graph presents the histograms of the same system in two different phases. The project LIOO has been totally reused into project MOODS and thus has changed name. Observing the graphs, the evolution of the histogram distributions is clear.

The typical distributions of the histograms for each metric have to be extracted on the basis of reference projects and can be modeled as Gaussian, log normal curves, etc., depending on the metric. The reference distribution defines the percentage (and thus the number) of classes that may belong to a certain category. This may present the metric value in a certain range.

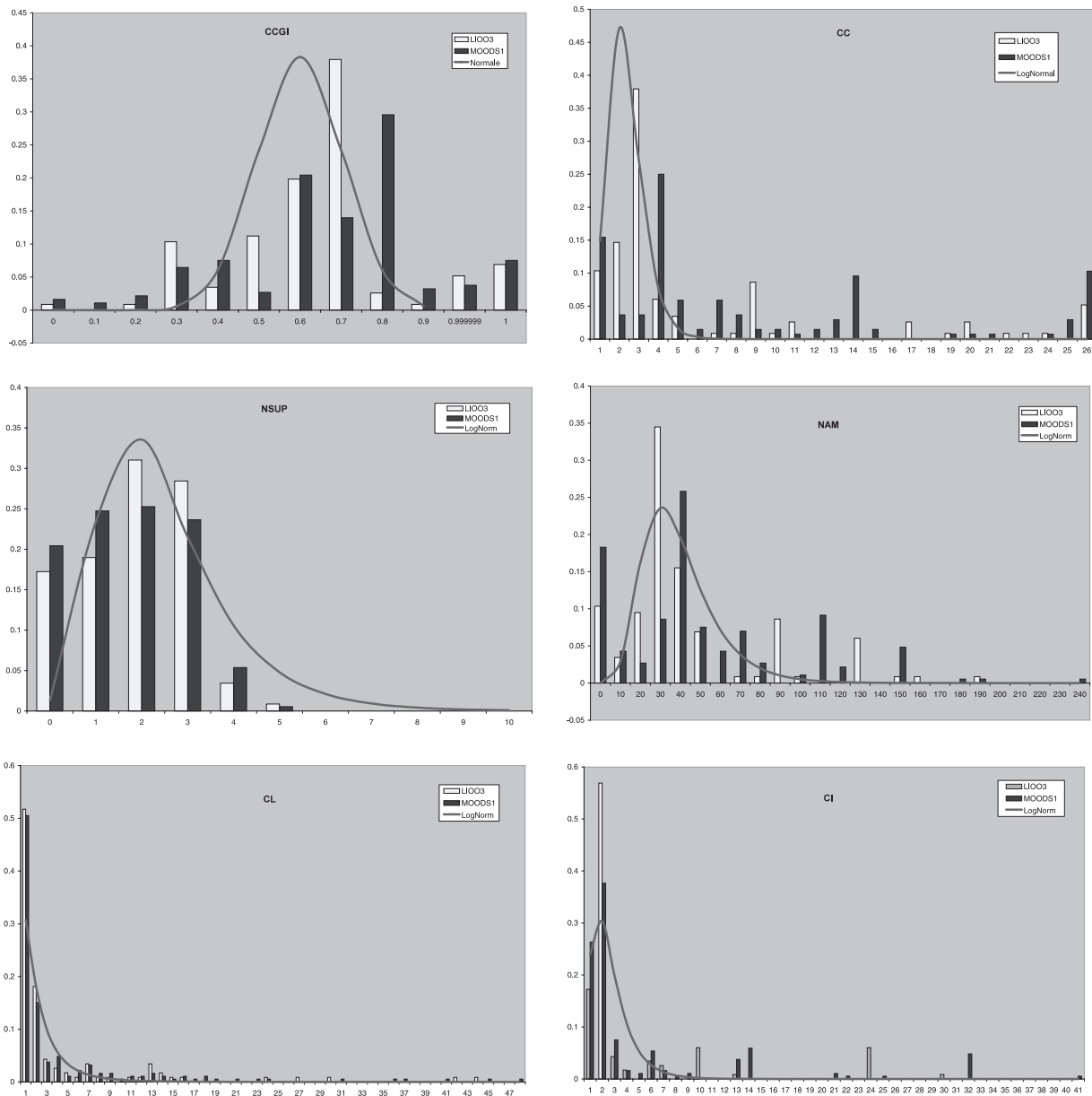


Fig. 10. Each histogram contains the distribution estimated for project MOODS (version 1) and LIOO (version 3) and the reference distribution for the context of LIOO, version 3. Please consider scale factors F reported in Table 6 for estimating the metric values.

Normalized histograms may present several classes out of the histogram distribution in the correspondence of their mean value or close to the zero. These classes may be considered correct depending on the metrics used.

In order to verify if the sample data for each distribution can be generated from a standard distribution like a normal or log normal, the Kolmogorov–Smirnov one sample statistic has been adopted. For this test, the null hypothesis, H_0 , consists in assessing that the samples can be drawn from a predefined distribution, while the alternative hypothesis, H_1 , asserts that it is not possible to draw the samples from the chosen distribu-

tion. In particular, the significance level for rejecting the null hypothesis has been imposed to 0.05. Under this condition for a number of samples equal to 116 (LIOO, version 3) the critical distance for rejecting H_0 is $D = 0.124$, while for a number of samples equal to 186 (MOODS, version 1) is $D = 0.098$. Values lower or equal than those reported confirm that data can be considered as belonging to the supposed distribution. In Table 4, the values related to the validation of the typical histogram distributions are reported. With the same technique, it has been demonstrated that histogram distributions depend on the development and life-cycle

Table 4
Data of metric distributions validated with Kolmogorov–Smirnov statistic test^a

Metric	Distribution type	Project	Version	Mean value	Standard deviation	Distance D	P -value
CCGI	Normal	LIOO	3	0.59	0.15	0.1030	0.161
CCGI	Normal	MOODS	1	0.63	0.21	0.0936	0.072
NAM	Log normal	LIOO	3	1.59	0.45	0.1218	0.059

^aThe values of mean and standard deviation are those that allow obtaining a P -value for the corresponding project for demonstrating that the distribution can model the data.

context as shown in Table 4, where the results of the Kolmogorov–Smirnov test on the distributions of LIOO (version 3) and MOODS (version 1) have been reported. For the test, the H_0 hypothesis states that the two samples are drawn from the same distribution, then H_1 states that the distributions are different. H_0 has been rejected, and then the distributions are different ($D = 0.37$ and P -value = 0.0000). This is mainly due to the different mean values that distributions provide.

According to the histogram distribution, some classes are considered correct even if they present values typically out of the imposed bounds for the metric. This is due to the fact that histograms evaluate the distribution of the metric value in the system and, thus, classes under the first part of distribution tails are considered as belonging to the general system behavior and not affected by problems. On the other hand, the adoption of simple bounds on the metric value marks these classes as affected by problems. According to our experience, both the approaches can be used. The combination of both the techniques is a more robust approach to identify classes that surely need an intervention.

The algorithm reported in Fig. 11 has been defined and implemented in TAC++ for processing the results of the assessment in order to identify in automatic manner the classes that have relevant problems. As already stated, we consider as relevant problems those which lead classes to be out-of-bound in the view and out-of-distribution in the corresponding histogram. This means that the class metric presents unacceptable value and that in the distribution the class belongs to a category out of typical histogram distribution.

The system is analyzed on the basis of the measuring context (*context* plus *phase* plus *level* in the algorithm). On this basis, a set of *views* are identified (as above defined) with their corresponding metrics and reference values. From these *views* all the related *metrics* are extracted.

In a first phase, the histograms of these metrics are automatically inspected in order to exact the classes which are out of the reference distribution, $ClassesOutOfDistrib[m]$, for each metric, m , in at least a histogram. To work only with out-of-distribution classes is a relevant reduction with respect to the analysis of all classes. The extraction of out-of-distribution classes, with $ExtractClasses()$, has to be based on the knowledge of a reference distribution for the histogram, and is

performed by extracting classes that belong to categories in which the number of classes is too high with respect to the planned value of the reference histogram distribution.

In the second phase, each class of the union of all $ClassesOutOfDistrib[i]$ is analyzed to verify if it provides out-of-bounds in the views and if these are also out-of-distribution. To this end, for each view the metrics out-of-bounds, $MetricsOutOfBounds$, are extracted. Then, for each class metric it is verified if the class is also out-of-distribution. With this process, for each class and view the set of $CriticalMetrics$ which are both out-of-bounds and out-of-distribution are extracted. Finally, if the number of critical metrics in the view is bigger than α the algorithm considers the class as affected by a problem and thus suggested actions are searched in both the related view and histogram repositories. The user can customize the corrective actions. Suggested by the assessment assistant and the related rules for their presentation.

The second phase of the algorithm has a computational complexity which is an $O(K_{OD}VM)$, where K_{OD} is the number of classes which have at least an out of histogram distribution. The global complexity of the algorithm is lower than the complexity obtained for the systematic analysis based on classes. It is an $O(CVM)$; since typically, $K_{OD} \ll C$. The algorithm takes advantage from the reduction of the number of classes to be analyzed and avoids the inspection of all views for each class.

The methodology and algorithm have been used in several assessment phases in the projects mentioned in the introduction. After a validation phase, the algorithm has been also implemented in the assistant assessment of TAC++ tool. In Section 5.3.2, an example of the adoption of the assistant assessment for a real project is reported.

5.3.2. Working with the assistant assessment

The following example is mainly referred to project LIOO version 3. In this case, four views have been used. The first view includes metrics related to: development effort (CC, CL, CI, and NAM), hierarchy (NSUP) and comprehensibility (CCGI); effort prediction or estimation at system level – SC, TLOC, NCL, NRC and mean DIT; conformity to OOP at system level – NRC, NRC/NCL, SC_m/NCL , Max(CC) and Max(NAM); reusability

```

∀ SubSystem ∈ System
begin
level = SubSystem.AnalysingLevel(Who);
context = SubSystem.DevelopmentContext(level);
phase = SubSystem.LifeCyclePhase(level, context);
Views = ViewRepositor.Select(level, context, phase);
Metrics = Metrics.Extract(Views);

∀ i ∈ Metrics ClassesOutOfDistrib[i] = ∅;
∀ m ∈ Metrics
begin
histogram = SubSystem.Histogram(m);
ClassesOutOfDistrib[m] = ClassesOutOfDistrib[m] ∪ histogram.ExtractClasses(level, context, phase);
endbegin

∀ class ∈ ∪iMetrics ClassesOutOfDistrib[i]
begin
∀ view ∈ Views
begin
CriticalMetrics = ∅;
MetricsOutOfBound = view.Check(class);
∀ metric ∈ MetricsOutOfBound
begin
if class ∈ ClassesOutOfDistrib[metric] then
CriticalMetrics = CriticalMetrics ∪ metric;
endif
endbegin
if NumberOf(CriticalMetrics) > α then
ActionSuggested = view.CorrectiveAction(CriticalMetrics);
∀ metric ∈ CriticalMetrics
begin
histogram = metric.getHistogram(level, context, phase);
ActionSuggested = ActionSuggested ∪ histogram.CorrectiveAction(metric);
endbegin
InteractiveVisualization(class, ActionSuggested);
endif
endbegin
endbegin
endbegin

```

Fig. 11. Assistant assessment algorithm for automating the result screening and understanding.

and maintainability – NOC, NSUP, NSUB, DIT and NAI for a total of 21 different metrics in the four views.

The following data has been obtained by using the above-presented algorithm for system assessment. The example has a relevance only for showing the evolution of the number of classes identified as needing intervention and not for the specific values used for the metrics. These may have a relevance only for the specific measuring context used.

In Table 5, the number of classes that have been detected out-of-bounds for each metric in project LIOO (version 3), K_{OB} , are reported. The reference bounds used in the above-mentioned first view for identifying classes that may need a further inspection are reported: minimum and maximum values. The bounds depend on the measuring context. In this case, the project was assessed in the first part of its development life-cycle. The bounds are typically very strict (close to the typical mean values) with respect to the bound values which are used for the same metrics in the case of the class selec-

tion only via out-of-bounds (see the second part of the table). Please note that when large bound values (distant from the typical mean value) are used, a lower number of classes are selected. Large bounds are typically used for reducing the number of classes to be inspected. Moreover, the bounds have to be substituted with strict bounds when the algorithm is used to identify classes with problems by using both bounds and distributions.

In Table 6, the data of the reference histogram distributions for the metrics related to a view used in the example are reported. Each reference histogram distribution is defined on the basis of its basic curve (second column, “Histogram distribution”, in the table), mean value, standard deviation, and the scale factor, F . In this context, F can be used for interpreting the graphs reported in Fig. 10. The correlations have been estimated by considering the distribution of metric values in the system and the reference distributions reported in Table 6. The table reports also the number of classes that have been detected to be out of the reference

distribution for each histogram (metric in the view) in project LIOO version 3, K_{OD} .

Typically, classes presenting 1 or more out-of-bounds or out-of-distributions in the selected view metrics are considered as problematic and thus they need a further inspection. This approach, in most cases, produces a too high number of classes that have to be inspected. In order to reduce this high number of classes (thus, the effort for their analysis) the metric bounds are typically enlarged (see Table 5). On the other hand, in this manner, classes with problems (that need to be further inspected) risk to pass the selection without any problem, leaving the system to grow towards degenerative conditions.

By using the above-presented algorithm, this problem is strongly reduced. This has been verified by observing the effects of different criteria for selecting critical classes, as reported in the following against the results produced by an exhaustive analysis. The number of selected classes, NSC, to be inspected and revised can be estimated on the basis of different criteria, that are the detection metrics:

Table 5
Number of identified out-of-bounds classes per metric (first view) for project LIOO (version 3) and related bounds: above the bounds corresponding to correct measuring context; below the large bound values which are typically used in simple approaches based only on out-of-bounds

Project LIOO version 3			
Metric	Minimum	Maximum	K_{OB}
<i>Strict bounds</i>			
CCGI	0.5	0.70	49
CC	0.0	600.0	32
NSUP	0.0	4	1
NAM	0.0	50	31
CL	0.0	400	8
CI	0.0	600	9
<i>Large bounds</i>			
CCGI	0.5	1.0	31
CC	0.0	1500.0	16
NSUP	0.0	5	0
NAM	0.0	90	21
CL	0.0	700	5
CI	0.0	1200	1

Table 6
Number of identified out-of-distribution classes for the metrics related to the first view for project LIOO (version 3); and related mean values and standard deviations

Histogram distributions parameters, project LIOO version 3						
Metric	Histogram distribution	Mean value	Standard deviation	F	K_{OD}	Correlation with distribution
CCGI	Normal	0.6	0.1	1	64	0.86
CC	Log normal	1.0	0.3	100	32	0.84
NSUP	Log normal	1.0	0.45	1	0	0.86
NAM	Log normal	1.4	0.4	10	28	0.79
CL	Log normal	0.6	0.8	20	18	0.81
CI	Log normal	1.0	0.5	50	28	0.85

$$NSC(DM_i) = \sum_c^{NCL} g_c(DM_i, \alpha),$$

where $g_c(DM_i, \alpha)$ is a function of the generic detection metric, DM_i , and threshold α , on a view of class c ,

$$g_c(DM_i, \alpha) = \begin{cases} 1 & \text{if } DM_i > \alpha, \\ 0 & \text{otherwise.} \end{cases}$$

DM_i can be a detection metric considering the out-of-bounds, OB, or the out-of-distributions, OD. Different detection metrics have been defined as reported in Table 7, where OB_m states if metric m is out-of-bound or not, OD_m states if metric m is out-of-distribution or not, and function *istrue()* return a value equal to 1 if its parameter is *out*. In Table 7, the following detection metrics have been defined: DM_{OB} for counting the number of metrics of out-of-bounds in a class view; DM_{OD} for counting the number of metrics of out-of-distribution in a class view; DM_{\wedge} for counting the number of metrics which are out-of-bounds and out-of-distribution for the same class view; DM_{\vee} for counting the number of metrics which are out-of-bounds or out-of-distribution for a class view; DM_{+} for counting the number of metrics which are out-of-bounds plus those which are out-of-distribution for a class view. Therefore, with $NSC()$ is possible to count critical conditions according to different detection criteria.

In Table 8, the data related to the application of detection metrics in the counting of NSC have been combined as a function of α for the first view of LIOO project, version 3, where the percentage of saving for the generic detection metric, DM_i , is estimated by using

$$\text{percentage of saving}(DM_i) = \frac{NSC(DM_{+}) - NSC(DM_i)}{NSC(DM_{+})} \times 100.$$

When $NSC(DM_{+})$ is used as the main criterion for detecting classes that need a further analysis, a larger number of classes are identified. If this approach for identifying classes with problems is performed on all views a very large percentage of classes are selected, in the above case we reached the 93%. This very high number of classes is obviously impossible to be managed

Table 7

Definition of detection metrics and a counting example for a view with 6 metrics, for $m = 1..6$: CC, CL, CI, NAM, NSUP, CCGI

DM metric definition	View with 6 metrics						Value
	CC	CL	CI	NAM	NSUP	CCGI	
$DM_{OB} = \sum_{m \in \text{view}} \text{istrue}(OB_m)$	<i>Out</i>	<i>In</i>	<i>Out</i>	<i>Out</i>	<i>In</i>	<i>Out</i>	4
$DM_{OD} = \sum_{m \in \text{view}} \text{istrue}(OD_m)$	<i>Out</i>	<i>Out</i>	<i>In</i>	<i>Out</i>	<i>In</i>	<i>In</i>	3
$DM_{\wedge} = \sum_{m \in \text{view}} \text{istrue}(OB_m \wedge OD_m)$	<i>Out</i>	<i>In</i>	<i>In</i>	<i>Out</i>	<i>In</i>	<i>In</i>	2
$DM_{\vee} = \sum_{m \in \text{view}} \text{istrue}(OB_m \vee OD_m)$	<i>Out</i>	<i>Out</i>	<i>Out</i>	<i>Out</i>	<i>In</i>	<i>Out</i>	5
$DM_{+} = DM_{OB} + DM_{OD}$	2 <i>Out</i>	<i>Out</i>	<i>Out</i>	2 <i>Out</i>	<i>In</i>	<i>Out</i>	7

Table 8

Number of selected classes, $NSC(DM_i)$, as a function of α for the first view: project LIOO version 3 with 116 classes

α	$NSC(DM_{OB})$	$NSC(DM_{OD})$	$NSC(DM_{\wedge})$	$NSC(DM_{\vee})$	$NSC(DM_{+})$	Percentage of saving (DM_{\wedge})
0	53	79	45	87	87	48
1	34	50	29	54	59	51
2	26	25	15	28	40	62
3	14	11	11	23	31	64
4	2	5	1	6	26	96
5	1	0	0	1	24	100
6	0	0	0	0	14	100
7	0	0	0	0	11	100
8	0	0	0	0	6	100
9	0	0	0	0	1	100
10	0	0	0	0	1	100

and has no sense. This effect is also present (even if in lower manner) when large bound values are used. The percentage of saving for the DM_{\wedge} -based solution has been estimated with respect to DM_{+} -based solution since this is the typically used approach for selecting classes that need a further inspection.

From the table, it is clear that it is possible to obtain a number of selected classes, $NSC(DM_{+})$, comparable with that obtainable by using a different value of α or by using different values for bounds by $NSC(DM_{OB})$ or $NSC(DM_{OD})$. On the other hand, these last detection metrics for identifying the critical classes are not equivalent, they share great part of the same classes but not all as it can be seen comparing $NSC(DM_{OD})$ and $NSC(DM_{OB})$.

A different approach is to consider the operation of conjunction and disjunction for identifying the number of selected classes. For higher values of α , a higher percentage of saving (in terms of classes to be analyzed) is obtained by using DM_{\wedge} instead of DM_{+} . This distribution is also present when the percentage of saving is estimated with respect to either $NSC(DM_{OB})$ or $NSC(DM_{OD})$ or $NSC(DM_{O})$.

Therefore, the more restrictive detection metric is DM_{\wedge} . In this case, an $\alpha = 3$ was considered and thus 11 classes were analyzed. Among these, we discovered that only 3 classes were affected by real design problems. These classes were the same classes identified by quality control personnel by performing a manual exhaustive

analysis of views. Only two of these classes were included in those identified by $NSC(DM_{OB})$ or by $NSC(DM_{OD})$ for $\alpha = 4$. Similar results have been obtained for other projects mentioned in the introduction. For this reason, it is convenient to adopt an α equal 2 or 3, obtaining a time saving of about 40% with respect to working only with bounds or distributions and about a 90% with respect to the exhaustive analysis.

6. Conclusions

The tool described in this paper has been developed during the last years during the assessment and control of several industrial and academic projects. Some of these have been multipartner ESPRIT projects, e.g., ICCOC ESPRIT HPCN, MOODS ESPRIT HPCN, MUPAAC ESPRIT HPCN. During the last few years, a tool has been profitably used for both metrics and system assessment. Together with the tool we identified a collection of guidelines and suggestion that can be considered a sort of modus operandi to work with metrics in order to detect analysis and design problems, and for effort estimation and prediction. Operatively, the methodology provides a set of diagrams: views, profiles and histograms and the strategies for their adoption and the corresponding guidelines for their interpretation. The methodology and related visualization facilities are fully supported by TAC++ tool. In the

paper, some suggestions to avoid confusion and time consuming in processing results and choosing metrics for views and profiles have been also given. The authors' experience in interpreting assessment results and defining a methodology for product assessment along its life-cycle has been reported. By interpreting the suggested

diagrams in the proposed manner a clear picture of the system under assessment can be obtained, and the quick detection of system dysfunction during the development life-cycle is possible. The assistant assessment algorithm has been profitably adopted reducing the detection and intervention time.

Table 9

Glossary of metrics and related acronyms mentioned in this paper^a

Metric	Comment
C	Number of classes per subsystem/system
$CACI_m$	Class attribute complexity/size inherited
$CACL_m$	Class attribute complexity/size local
CBO(Chidamber and Kemerer, 1994)	Class cognitive index local
CC_m (Nesi and Querci, 1998)	Class complexity/size
CC'_m (Nesi and Querci, 1998)	Class complexity/size, predictive form
CCGI (Fioravanti et al., 1998a)	Class cognitive index
CI_m	Class method complexity/size inherited
CL_m	Class mcomplexity/size local, equivalent to CM_m
$CMICI_m$	Class method interface complexity/size inherited
$CMICL_m$	Class method interface complexity/size local
D_i	Generic LLM and/or HML
DIT (Chidamber and Kemerer, 1994)	Deep inheritance tree
DM_v	Number of metrics which are out-of-bounds or out-of-distribution for a class view
DM_Δ	Number of metrics which are out-of-bounds and out-of-distribution for a class view
DM_{OB}	Number of metrics of out-of-bounds
DM_{OD}	Number of metrics of out-of-distribution
DM_+	Number of metrics which are out-of-bounds plus those which are out-of-distribution
M_i	Generic LLM and/or HML
ECD (Fioravanti et al., 1998a)	External class description
F	Scale factor for the histogram distributions
Ha (Halstead, 1977)	Halstead metric
K_{OB}	Number of system classes with at least a metrics out-of-bound
K_{OD}	Number of system classes with at least a metrics out-of-distribution
LOC	Number of LOC
M	Mean number of metrics for each view
$Max(i)$	Maximum value of metric i among those of the system classes
Mc(McCabe, 1976)	McCabe ciclomatic complexity
MCC	Mean value of CC metric estimated on the system
MPAC	Method private attribute cohesion
NA	Number of attributes of a class (local and inherited)
NAI	Number of attributes iInherited of a class
NAL	Number of attributes locally defined of a class
NAM	Number of attributes and methods of a class
NAML	Number of attributes and methods locally defined of a class
NCL	Number of classes
NM	Number of methods of a class (local and inherited)
NMI	Number of methods inherited of a class
NML	Number of methods local of a class
NOC (Chidamber and Kemerer, 1994)	Number of child
NRC	Number of root classes in the system class tree
NSC()	Number of selected classes for a further inspection based on a DM metric
NSUB (Fioravanti et al., 1998a)	Number of subclasses of a class
NSUP (Fioravanti et al., 1998a)	Number of superclasses of a class
R_i	Generic LLM and/or HML
SC_m	System complexity/size
Size2 (Li and Henry, 1993)	Number of class attributes and methods
TLOC	Total number of LOC in the system
TNM	Total number of methods in the system
U_i	Generic LLM and/or HML
V	Number of views per class
VI (Nesi and Campanai, 1996)	Verifiability index
WMC (Chidamber and Kemerer, 1994)	Weighted methods for class, CL_{Mc} in our notation

^a Metrics with m parameter are evaluated on the basis of a functional metric selected from: Mc, Ha or LOC, e.g., CC_{Mc} class complexity/size based on McCabe ciclomatic complexity.

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Appendix A. Metric glossary

See Table 9.

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