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A GENERAL INTEGRAL IDENTITY WITH APPLICATIONS TO A REVERSE SERRIN PROBLEM

ROLANDO MAGNANINI, RICCARDO MOLINAROLO, AND GIORGIO POGGESI

ABSTRACT. We prove a new general differential identity and an associated integral identity, which entails a pair of solutions of the Poisson equation with constant source term. This generalizes a formula that the first and third authors previously proved and used to obtain quantitative estimates of spherical symmetry for the Serrin overdetermined boundary value problem. As a first application, we prove a quantitative symmetry result for the *reverse Serrin problem*, which we introduce for the first time in this paper. In passing, we obtain a rigidity result for solutions of the aforementioned Poisson equation subject to a constant Neumann condition.

1. INTRODUCTION

Let Ω be a bounded domain in the Euclidean space \mathbb{R}^N , $N \geq 2$, with sufficiently regular boundary Γ . We consider solutions of the Poisson equation:

$$(1.1) \quad \Delta u = N \quad \text{in } \Omega.$$

In [19, 20], the first and third author of this paper stated and then proved the following integral identity:

$$(1.2) \quad \int_{\Omega} (-u) \left\{ |\nabla^2 u|^2 - \frac{(\Delta u)^2}{N} \right\} dx = \frac{1}{2} \int_{\Gamma} (u_{\nu}^2 - R^2) (u_{\nu} - q_{\nu}) dS_x.$$

Here, u is a solution of (1.1) such that

$$(1.3) \quad u = 0 \quad \text{on } \Gamma$$

and $q = q^z$ is a quadratic polynomial of the form

$$(1.4) \quad q^z(x) = \frac{1}{2} |x - z|^2 + a \quad \text{for } x \in \mathbb{R}^N,$$

for some $z \in \mathbb{R}^N$ and $a \in \mathbb{R}$. Moreover, ν is the exterior unit normal on Γ and the constant R has the value

$$(1.5) \quad R = \frac{N |\Omega|}{|\Gamma|}.$$

Also, notice that it is easy to see that

$$|\nabla^2 u|^2 - \frac{(\Delta u)^2}{N} = \Delta P,$$

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when we set:

$$P = \frac{1}{2} |\nabla u|^2 - u.$$

This is a standard P -function for (1.1).

The function ΔP is important. It is non-negative, by the Cauchy-Schwarz inequality and vanishes if and only if u is a quadratic polynomial as in (1.4). Thus, it gives a *quadratic-radiality test* for u . By this important feature, (1.2) yields the Serrin Symmetry Theorem (see [30] for the celebrated proof by the method of moving planes and [31] for the first proof based on integral identities). This asserts that, if the solution u of (1.1) and (1.3) has constant normal derivative u_ν on Γ , then Ω must be a ball. This is now easily seen from (1.2), since it turns out that the constant value of u_ν on Γ must equal R , by the divergence theorem. Thus, (1.2) gives that $\Delta P \equiv 0$ (and hence radial symmetry), being as $-u > 0$ on Ω , by the strong maximum principle. The use of the volume integral in (1.2) to test the radiality of u was first noticed in [27].

Besides giving rigidity, (1.2) is even more important, because it allows to construct sharp quantitative estimates on how the relevant domain Ω deviates from being a ball (in the Hausdorff topology of domains) in terms of some norm of the deviation of u_ν from a constant. This theme was inaugurated in [1], by using a quantitative version of the method of moving planes. There, a quantitative symmetry estimate is obtained in terms of a logarithmic profile of a $C^1(\Gamma)$ -norm of the aforementioned deviation. It is worth noticing that this approach also works for positive solutions of quite general semilinear Poisson equations. That strategy was improved in [10] thus obtaining a quantitative symmetry estimate in terms of a polynomial profile of the Lipschitz seminorm of u_ν . (See also [8, 6, 7] for related research and [5, 11, 12] for recent generalizations to the fractional setting.)

An approach based on a quantitative version of the arguments contained in [31] was initiated in [3]. The method only works for the Poisson equation (1.1). However, the measure of the relevant deviation of u_ν from a constant is greatly relaxed by using a Lebesgue norm on Γ . (We refer the interested reader to [18, 23, 29] for a survey on the several stability results available in the literature; see also [9, 13] for related results in different settings.)

Identity (1.2) was used by the first and third author to obtain optimal (for low dimension) and allegedly¹optimal (for large dimension) quantitative bounds. This was the theme of a series of papers ([20, 21, 23]) culminating with the proof of the inequality

$$(1.6) \quad \rho_e - \rho_i \leq c \psi(\|u_\nu - R\|_{2,\Gamma}).$$

(See also [24, 28, 26] for recent extensions to mixed boundary value problems.) In (1.6), we mean that

$$(1.7) \quad \rho_e = \max_{x \in \Gamma} |x - z|, \quad \rho_i = \min_{x \in \Gamma} |x - z|,$$

for some point $z \in \Omega$. Hence, ρ_i and ρ_e are the radii of the largest ball contained in Ω and the smallest ball containing Ω , both centered at z .²

¹Here, we mean that we conjecture that the bounds obtained in [23] are indeed optimal.

²In [23], it is also shown that, besides $\rho_e - \rho_i$, the L^2 -deviation of the Gauss map of Γ from that of a sphere can be estimated by the same profile ψ .

The profile $\psi : (0, \infty) \rightarrow (0, \infty)$ changes with the dimension. In fact, by [21] (and the improvement provided by [23] in the case $N = 3$), we have that

$$(1.8) \quad \psi(t) = \begin{cases} t & \text{if } N = 2, \\ t \max[\log(1/t), 1] & \text{if } N = 3, \\ t^{2/(N-1)} & \text{if } N \geq 4, \end{cases}$$

for $t > 0$. The constant c in (1.6) only depends on the dimension N , the diameter d_Ω of Ω , and the radii r_i and r_e of the uniform interior and exterior sphere conditions of Ω , as defined in Section 2. (We recall that those conditions are equivalent to the $C^{1,1}$ regularity of Γ as shown in [2, Corollary 3.14].) In [23] improvements of the profile are also provided for $N \geq 4$. In particular, if Γ is of class $C^{2,\alpha}$, then [23, Theorem 4.4] ensures that (1.6) holds true with

$$(1.9) \quad \psi(t) = t^{4/(N+1)} \quad \text{for } N \geq 4,$$

provided c depends on the $C^{2,\alpha}$ -regularity of Γ , instead of its $C^{1,1}$ -regularity.

In this paper, we derive an integral identity, which generalizes (1.2). It simply involves any two solutions u and v of class $C^2(\overline{\Omega})$ of (1.1), and reads as:

$$(1.10) \quad \int_{\Omega} (\bar{u} - u) \Delta P \, dx + \int_{\Omega} \langle (I - \nabla^2 v) \nabla u, \nabla u \rangle \, dx = \\ \int_{\Gamma} (\bar{u} - u) \langle \nabla^2 u \nabla u, \nu \rangle \, dS_x + \frac{1}{2} \int_{\Gamma} |\nabla u|^2 (u_\nu + v_\nu) \, dS_x + \\ - \int_{\Gamma} \langle \nabla v, \nabla u \rangle u_\nu \, dS_x - \int_{\Gamma} (\bar{u} - u) u_\nu \, dS_x + N \int_{\Gamma} (\bar{u} - u) (u_\nu - v_\nu) \, dS_x.$$

The proof is a simple application of the divergence theorem to an appropriate differential identity (see Theorem 3.1 for details).

In (1.10), we mean that

$$\bar{u} = \max_{\overline{\Omega}} u = \max_{\Gamma} u,$$

so that $\bar{u} - u > 0$ in Ω , by the strong maximum principle. Of course, if we require that u satisfies (1.3) or, more generally,

$$(1.11) \quad u = u_0 \quad \text{on } \Gamma,$$

for some $u_0 \in \mathbb{R}$, (1.10) will simply return (1.2) (in the latter case with $-u$ replaced by $\bar{u} - u = u_0 - u$).

The significant generality of (1.10) opens the path to its application to old and new rigidity results for solutions of the Poisson equation (1.1). In this paper, we shall test the effectiveness of (1.10) by analysing the stability of what we shall call the *reverse Serrin problem*, as opposed to the *classical Serrin problem*. The former consists in considering a solution of (1.1) subject to the Neumann condition

$$(1.12) \quad u_\nu = R \quad \text{on } \Gamma,$$

and then imposing that u also satisfies (1.11).

Of course, the rigidity part of this problem gives the same (spherical) solution of the classical Serrin problem. The stability part is however not explored.

We shall see in Section 6 that one can derive stability estimates for the reverse Serrin problem by exploiting those already obtained for the classical Serrin problem. However, this procedure leads to estimates which require a strong measure of the deviation of u from being constant on Γ . In fact, we need to use the norm $\|\bar{u} - u\|_{C^{1,\alpha}(\Gamma)}$, as shown in Theorem 6.2.

Instead, the full power of (1.10) (in place of (1.2)) allows to weaken such a stringent deviation. In fact, in the two stability results we shall describe next, the deviation of the function u from being a constant on Γ will be measured in terms of its *oscillation*,

$$\operatorname{osc}_{\Gamma} u = \max_{\Gamma} u - \min_{\Gamma} u,$$

and some suitable norm of its *tangential gradient* $\nabla_{\Gamma} u$ (see Section 2 for its definition). Our first stability result reads as follows.

Theorem 1.1 (The reverse Serrin problem with uniform deviation). *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with boundary Γ of class C^2 .*

Suppose $u \in C^2(\bar{\Omega})$ is a solution of (1.1), (1.12) and let z be any minimum point of u on $\bar{\Omega}$. Then it holds that

$$\rho_e - \rho_i \leq c \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma} \right),$$

where ψ is given in (1.8). The constant $c > 0$ depends on N, d_{Ω}, r_i , and r_e .

We singled out this theorem since it is relatively easy to obtain from our new identity. Moreover, the dependence of the constant c on the mentioned parameters can be written explicitly.

In the next result, we show how the deviation of u from being a constant can be further weakened.

Theorem 1.2 (The reverse Serrin problem with weak deviation). *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with boundary Γ of class $C^{2,\alpha}$.*

Suppose $u \in C^2(\bar{\Omega})$ is a solution of (1.1), (1.12) and let z be any minimum point of u on $\bar{\Omega}$. Then it holds that

$$\rho_e - \rho_i \leq c \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{2, \Gamma} \right),$$

where ψ is given in (1.8). The constant $c > 0$ depends on N, d_{Ω}, r_i , and r_e .

Moreover, for $N \geq 4$ the profile ψ can be improved to (1.9). In this case, the dependence of c on r_i and r_e must be replaced with that on the $C^{2,\alpha}$ -regularity of Γ .

We shall now describe the key points of the proofs of Theorems 1.1 and 1.2 and highlight with the corresponding results in classical Serrin problem.

The first step is to rewrite (1.10) conveniently, when u also satisfies (1.12). In fact, in this case we obtain the following identity:

$$(1.13) \quad \int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx = \frac{1}{2} \int_{\Gamma} |\nabla_{\Gamma} u|^2 h_{\nu} dS_x + \int_{\Gamma} (\bar{u} - u) [(N-1)RH - N] h_{\nu} dS_x - \int_{\Gamma} (\bar{u} - u) \langle (\nabla \nu) \nabla_{\Gamma} u, \nabla_{\Gamma} u \rangle dS_x.$$

Here, $h = q - u$, where q is given in (1.4). Also, H is the mean curvature of Γ and $\nabla \nu$ is the Jacobian of a suitable extension to a neighborhood of Γ of the unit normal vector field ν on Γ . Since up to suitable rotations $\nabla \nu$ depends on the principal curvatures of Γ , we realize that each surface integral at the right-hand side of (1.13) contains a quantity which is locally defined on Γ and can be made small in terms of the relevant deviations used in Theorems 1.1 and 1.2.

In order to obtain the new version (1.13) from (1.10), terms like u_{ν} or $u_{\nu\nu}$ should be replaced in (1.10). The latter term pops up when we consider the first surface integral in (1.10). In order to see that, we extend the vector field ν to a tubular neighborhood of Γ and observe that $\nabla(u_{\nu}) = \langle \nabla(u_{\nu}), \nu \rangle \nu$, since Γ is a level surface of u_{ν} . This procedure leads to discover that

$$\langle (\nabla^2 u) \nabla u, \nu \rangle = -\langle (\nabla \nu) \nabla_{\Gamma} u, \nabla_{\Gamma} u \rangle + u_{\nu} u_{\nu\nu} \quad \text{on } \Gamma,$$

since we also know that $(\nabla \nu) \nu = 0$ on Γ (see Section 2 for details).

Furthermore, the term $u_{\nu\nu}$ is treated by using the well-known formula for the Laplace operator of a smooth function v on a closed surface Σ :

$$\Delta v = v_{\nu\nu} + \Delta_{\Sigma} v + (N-1)H v_{\nu}.$$

Here, Δ_{Σ} is the Laplace-Beltrami operator on Σ and H is the mean curvature of Σ . (All these notations and computations are collected in Section 2.) Thus, since u satisfies (1.1) and (1.12), we obtain that

$$u_{\nu} u_{\nu\nu} = NR - (N-1)R^2 H - R \Delta_{\Gamma} u \quad \text{on } \Gamma.$$

Finally, if we want obtain the desired dependence on $\nabla_{\Gamma} u$, we must use integration by parts on Γ , i.e. apply the formula:

$$\int_{\Gamma} (\bar{u} - u) \Delta_{\Gamma} u dS_x = \int_{\Gamma} |\nabla_{\Gamma} u|^2 dS_x.$$

This last step and the pointwise analysis on Γ are peculiar of the reverse Serrin problem and were not needed in the classical counterpart.

Since we assume that $u_{\nu} = R$ on Γ the remaining integrals in (1.10) are then easily treatable.

Now, we focus our attention on the left-hand side of (1.10). Notice that, if we choose $v = q$, with q as in (1.4), the second volume integral in (1.10) disappears (see also Theorem 3.2). Hence, the left-hand side of (1.13) is easily obtained by observing that $|\nabla^2 h|^2 = \Delta P$. The harmonic function h was also used in the treatment of (1.6) and can be viewed as a deviation of u from q , thus measuring how far the solution (and the domain) is from a spherical configuration.

Therefore, in order to obtain the estimate in Theorem 1.2, the plan is to show that the volume integral in (1.13) is small provided the right-hand

side of (1.13) becomes small in terms of some deviation of u on Γ from a constant.

Notice that if that integral is zero, then $|\nabla^2 h| = 0$, being as $\bar{u} - u > 0$ by the strong maximum principle. Thus, h is an affine function. As a consequence, we obtain in passing a fairly general rigidity result, which holds in the case of fairly general domains.

Theorem 1.3. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with boundary Γ of class C^2 . Let $u \in C^2(\bar{\Omega})$ be a solution of (1.1), (1.12).*

If the right-hand side of (1.13) is non-positive, then h is affine, and hence u is a quadratic polynomial. As a result, Ω is a ball.

A version of this theorem for the solution of (1.1), (1.3) was proved in [20]. Of course, the condition on the sign of the right-hand side of (1.13) in Theorem 1.3 is satisfied if u is also constant on Γ .

Finally, in order to treat the stability issue, one observes that the affine function h in Theorem 1.3 can be further normalized to a constant by an appropriate choice of the center z of the paraboloid q . With such a choice, if the volume integral (1.13) is small, then h is close to a constant. Heuristically, this means that the oscillation of h on Γ can be controlled by a weighted norm of $|\nabla^2 h|$. Now, since we have that

$$\frac{1}{2}(\rho_e^2 - \rho_i^2) = \operatorname{osc}_{\Gamma} q \leq \operatorname{osc}_{\Gamma} h + \operatorname{osc}_{\Gamma} u,$$

the desired estimate for $\rho_e - \rho_i$ can then be derived from one of the oscillation of h on Γ in terms of the aforementioned weighted integral, which can be derived from some inequalities proved in [23].

The structure of this paper is as follows. In Section 2, we collect some preliminary formulas and results for functions defined on surfaces. Section 3 contains our general identity and its corollaries, together with rigidity results related to the reverse Serrin problem, including the proof of Theorem 1.3. In Section 4, we gather some estimates for the Neumann problem, which are instrumental to trace the dependence of the constant c of Theorem 1.2 on the relevant parameters. The proofs of Theorems 1.1 and 1.2 are contained in Section 5. Section 6 contains the alternative stability result for the Serrin reverse problem (Theorem 6.2) obtained via existing results for the classical Serrin problem.

2. NOTATIONS AND PRELIMINARY FORMULAS

Let $\Sigma \subset \mathbb{R}^N$ be a surface of class C^2 , which is the boundary of a bounded domain $D \subset \mathbb{R}^N$ and consider a function $v \in C^2(\bar{D})$.

We use the following decomposition for the gradient ∇v of v on Σ :

$$(2.1) \quad \nabla v = v_{\nu} \nu + \nabla_{\Sigma} v.$$

Here, ν denotes the exterior unit normal vector field to Σ . This decomposition defines what we shall call the *tangential gradient* $\nabla_{\Sigma} v$ of v on Σ . It is clear that, if w is another function in $C^2(\bar{D})$, then

$$\langle \nabla v, \nabla w \rangle = v_{\nu} w_{\nu} + \langle \nabla_{\Sigma} v, \nabla_{\Sigma} w \rangle.$$

We recall the well-known formula (see [15]):

$$(2.2) \quad \Delta v = v_{\nu\nu} + \Delta_{\Sigma} v + (N-1)H v_{\nu} \quad \text{on } \Sigma.$$

Here, Δ_{Σ} is the Laplace-Beltrami operator on Σ and H denotes the *mean curvature* of Σ defined by

$$H = \frac{1}{N-1} \sum_{j=1}^{N-1} \kappa_j,$$

where $\kappa_1, \dots, \kappa_{N-1}$ are the principal curvatures of Σ with respect to the interior normal.

We also recall from [15] the following formula of integration by parts on Σ , which holds for any $v, w \in C^2(\overline{D})$:

$$(2.3) \quad \int_{\Sigma} \langle \nabla_{\Sigma} v, \nabla_{\Sigma} w \rangle dS_x = - \int_{\Sigma} v \Delta_{\Sigma} w dS_x.$$

In particular, we have that $\int_{\Sigma} \Delta_{\Sigma} w dS_x = 0$.

We can always extend the vector field ν smoothly to a tubular neighborhood of Σ in \overline{D} . For instance, we can set $\nu = -\eta \nabla \delta_{\Gamma}$, where δ_{Σ} is the *distance function*, defined by

$$\delta_{\Sigma}(x) = \text{dist}(x, \Sigma) \quad \text{for } x \in \overline{D},$$

and η is a cut-off function which equals 1 in a neighborhood of Γ . In fact, we know from [16] that there is neighborhood \mathcal{U} of Σ in \overline{D} such that $\delta_{\Gamma} \in C^{2,\alpha}(\mathcal{U})$ and we have that

$$|\nabla \delta_{\Sigma}| = 1 \quad \text{in } \mathcal{U}.$$

Hence, η is chosen as a smooth function with support contained in the set in \mathcal{U} and such that $\eta \equiv 1$ near Σ .

At any point in Σ , we can choose coordinates (see, e.g., [14, Appendix 14.6]) so that

$$\nabla \nu = -\nabla^2 \delta_{\Sigma} = \begin{bmatrix} \kappa_1 & \cdots & 0 & 0 \\ \vdots & \ddots & \vdots & \vdots \\ 0 & \cdots & \kappa_{N-1} & 0 \\ 0 & \cdots & 0 & 0 \end{bmatrix}.$$

Throughout the rest of the paper, unless explicitly indicated,

$$(2.4) \quad \begin{array}{l} \Omega \text{ is a bounded domain in } \mathbb{R}^N, \ N \geq 2, \text{ with boundary } \Gamma \\ \text{satisfying the uniform interior and exterior sphere conditions.} \end{array}$$

We denote by d_{Ω} the diameter of Ω . Also, we recall the standard definitions of *uniform interior and exterior sphere conditions*, whose respective radii will be denoted by r_i and r_e . Namely, there exists $r_i > 0$ (resp. $r_e > 0$) such that for each $p \in \Gamma$ it holds that $\overline{B} \cap \Gamma = \{p\}$ for some ball $B \subset \Omega$ (resp. $B \subset \mathbb{R}^N \setminus \overline{\Omega}$) of radius $r_i > 0$ (resp. $r_e > 0$). As already mentioned, the two properties are equivalent to the $C^{1,1}$ -regularity of Γ , as shown in [2].

The following lemma will be useful. For simplicity of notation, we do not use an explicit sign convention for the mean curvature H . In other words, we mean that, on each component Σ of Γ , H is defined as just above described.

Lemma 2.1. *Let $u \in C^2(\overline{\Omega})$ be a solution of (1.1), and $c \in \mathbb{R}$. It holds that*

(i) if $u = c$ on Γ , then

$$\langle \nabla^2 u \nabla u, \nu \rangle = u_\nu [N - (N - 1) H u_\nu] \quad \text{on } \Gamma;$$

(ii) if $u_\nu = c$ on Γ , then

$$\langle \nabla^2 u \nabla u, \nu \rangle = -\langle \nabla \nu \nabla_\Gamma u, \nabla_\Gamma u \rangle + u_\nu [N - \Delta_\Gamma u - (N - 1) H u_\nu] \quad \text{on } \Gamma.$$

Proof. (i) Since Γ is a level surface for u , by (2.1) we infer that $\nabla u = u_\nu \nu$, and hence

$$\langle \nabla^2 u \nabla u, \nu \rangle = u_\nu u_{\nu\nu}.$$

Moreover, (2.2) with $v = u$ gives that

$$(2.5) \quad u_{\nu\nu} = N - \Delta_\Gamma u - (N - 1) H u_\nu \quad \text{on } \Gamma.$$

Since $\Delta_\Gamma u = 0$ on Γ , the desired identity ensues at once.

(ii) We proceed as already described by extending ν to a neighborhood \mathcal{U} . The ensuing computations are generally performed in \mathcal{U} , and hence evaluated on Γ .

Since Γ is a level surface of $\langle \nabla u, \nu \rangle$, we have that

$$\nabla \langle \nabla u, \nu \rangle = \langle \nabla \langle \nabla u, \nu \rangle, \nu \rangle \nu$$

on Γ . Next, we compute that

$$\begin{aligned} \nabla \langle \nabla u, \nu \rangle &= (\nabla^2 u) \nu + \nabla \nu \nabla u = \\ &= (\nabla^2 u) \nu + u_\nu (\nabla \nu) \nu + \nabla \nu \nabla_\Gamma u = (\nabla^2 u) \nu + \nabla \nu \nabla_\Gamma u. \end{aligned}$$

Here, we have used that $(\nabla \nu) \nu = 0$ in \mathcal{U} , since ν is unitary.

Thus, we infer that

$$\begin{aligned} (\nabla^2 u) \nu + (\nabla \nu) \nabla_\Gamma u &= \\ [u_{\nu\nu} + \langle (\nabla \nu) \nabla_\Gamma u, \nu \rangle] \nu &= [u_{\nu\nu} + \langle (\nabla \nu) \nu, \nabla_\Gamma u \rangle] \nu = u_{\nu\nu} \nu. \end{aligned}$$

Hence, multiplying by ∇u gives that

$$\begin{aligned} \langle (\nabla^2 u) \nabla u, \nu \rangle &= \\ -\langle (\nabla \nu) \nabla_\Gamma u, \nabla u \rangle + u_\nu u_{\nu\nu} &= -\langle (\nabla \nu) \nabla_\Gamma u, \nabla_\Gamma u \rangle + u_\nu u_{\nu\nu}. \end{aligned}$$

Here, we have again used (2.1) and $(\nabla \nu) \nu = 0$. Therefore, the desired identity follows by (2.5). \square

Remark 2.2. From the aforementioned properties of $\nabla \nu$, we easily infer that

$$\underline{\kappa} |\nabla_\Gamma u|^2 \leq \langle (\nabla \nu) \nabla_\Gamma u, \nabla_\Gamma u \rangle \leq \bar{\kappa} |\nabla_\Gamma u|^2 \quad \text{on } \Gamma,$$

where

$$\underline{\kappa} = \min[\kappa_1, \dots, \kappa_{N-1}] \quad \text{and} \quad \bar{\kappa} = \max[\kappa_1, \dots, \kappa_{N-1}]$$

at each point of Γ . We also recall that

$$-\frac{1}{r_e} \leq \underline{\kappa} \leq \bar{\kappa} \leq \frac{1}{r_i} \quad \text{on } \Gamma,$$

under our assumption (2.4).

3. INTEGRAL IDENTITIES AND RIGIDITY RESULTS

In this section, we shall derive the identities (1.10) and (1.13). We will also prove Theorem 1.3.

Theorem 3.1 (General identity). *Suppose $\Omega \subset \mathbb{R}^N$, $N \geq 2$, is a bounded domain as defined in (2.4). Let $u, v \in C^2(\overline{\Omega})$ be solutions of (1.1).*

Set

$$\bar{u} = \max_{\overline{\Omega}} u = \max_{\Gamma} u,$$

and

$$P = \frac{1}{2} |\nabla u|^2 + (\bar{u} - u) \quad \text{on } \overline{\Omega}.$$

Then the identity (1.10) holds, that is:

$$\begin{aligned} & \int_{\Omega} (\bar{u} - u) \Delta P \, dx + \int_{\Omega} \langle (I - \nabla^2 v) \nabla u, \nabla u \rangle \, dx = \\ & \int_{\Gamma} (\bar{u} - u) \langle \nabla^2 u \nabla u, \nu \rangle \, dS_x + \frac{1}{2} \int_{\Gamma} |\nabla u|^2 (u_{\nu} + v_{\nu}) \, dS_x + \\ & - \int_{\Gamma} \langle \nabla v, \nabla u \rangle u_{\nu} \, dS_x - \int_{\Gamma} (\bar{u} - u) u_{\nu} \, dS_x + N \int_{\Gamma} (\bar{u} - u) (u_{\nu} - v_{\nu}) \, dS_x. \end{aligned}$$

Proof. The proof proceeds by direct computations and an application of the divergence theorem. By simply taking derivatives and by straightforward algebraic manipulations, we first infer that the following key differential identity holds:

$$\begin{aligned} & (\bar{u} - u) \Delta P + \langle (I - \nabla^2 v) \nabla u, \nabla u \rangle = \\ & \operatorname{div} \left\{ P \nabla u + (\bar{u} - u) \nabla P + \frac{1}{2} |\nabla u|^2 \nabla v - \langle \nabla v, \nabla u \rangle \nabla u \right\} \\ & \quad + \operatorname{div} \{ (N - 1) (\bar{u} - u) \nabla u - N (\bar{u} - u) \nabla v \}. \end{aligned}$$

Thus, an application of the divergence theorem yields:

$$\begin{aligned} & \int_{\Omega} (\bar{u} - u) \Delta P \, dx + \int_{\Omega} \langle (I - \nabla^2 v) \nabla u, \nabla u \rangle \, dx = \\ & \int_{\Gamma} \left\{ P u_{\nu} + (\bar{u} - u) P_{\nu} + \frac{1}{2} |\nabla u|^2 v_{\nu} - \langle \nabla v, \nabla u \rangle u_{\nu} \right\} dS_x + \\ & \int_{\Gamma} \{ (N - 1) (\bar{u} - u) u_{\nu} - N (\bar{u} - u) v_{\nu} \} dS_x. \end{aligned}$$

Hence, we infer that

$$\begin{aligned} & \int_{\Omega} (\bar{u} - u) \Delta P \, dx + \int_{\Omega} \langle (I - \nabla^2 v) \nabla u, \nabla u \rangle \, dx = \int_{\Gamma} \left\{ \frac{1}{2} |\nabla u|^2 + (\bar{u} - u) \right\} u_{\nu} \, dS_x + \\ & \int_{\Gamma} \left\{ \langle \nabla^2 u \nabla u, \nu \rangle - u_{\nu} \right\} (\bar{u} - u) \, dS_x + \int_{\Gamma} \left\{ \frac{1}{2} |\nabla u|^2 v_{\nu} - \langle \nabla v, \nabla u \rangle u_{\nu} \right\} dS_x + \\ & \int_{\Gamma} \{ (N - 1) (\bar{u} - u) u_{\nu} - N (\bar{u} - u) v_{\nu} \} dS_x. \end{aligned}$$

Identity (1.10) then ensues by rearranging the terms. \square

We now present a corollary of the previous result, when v is a quadratic solution q of (1.1).

Corollary 3.2 (Mother identity for the quadratic case). *Suppose $\Omega \subset \mathbb{R}^N$, $N \geq 2$, is a bounded domain as defined in (2.4).*

Let u , \bar{u} , and P be as in Theorem 3.1 and let q be a quadratic polynomial of the form (1.4). Then, the following identity holds:

$$(3.1) \quad \int_{\Omega} (\bar{u} - u) \Delta P \, dx = \frac{1}{2} \int_{\Gamma} |\nabla u|^2 (u_{\nu} + q_{\nu}) \, dS_x - \int_{\Gamma} \langle \nabla q, \nabla u \rangle u_{\nu} \, dS_x + \int_{\Gamma} (\bar{u} - u) \langle \nabla^2 u \nabla u, \nu \rangle \, dS_x + \int_{\Gamma} (\bar{u} - u) [(N-1) u_{\nu} - N q_{\nu}] \, dS_x.$$

An alternative formula is:

$$(3.2) \quad \int_{\Omega} (\bar{u} - u) \Delta P \, dx = \frac{1}{2} \int_{\Gamma} u_{\nu}^2 (u_{\nu} - q_{\nu}) \, dS_x + \frac{1}{2} \int_{\Gamma} |\nabla_{\Gamma} u|^2 (u_{\nu} + q_{\nu}) \, dS_x - \int_{\Gamma} \langle \nabla_{\Gamma} q, \nabla_{\Gamma} u \rangle u_{\nu} \, dS_x + \int_{\Gamma} (\bar{u} - u) \langle \nabla^2 u \nabla u, \nu \rangle \, dS_x + \int_{\Gamma} (\bar{u} - u) [(N-1) u_{\nu} - N q_{\nu}] \, dS_x.$$

Proof. We apply (1.10) with $v = q$, since q is clearly a solution of (1.1) on the whole \mathbb{R}^N . We have that $\nabla^2 q = I$. As a result, the second volume integral at the left-hand side of (1.10) vanishes, and hence (3.1) ensues. Formula (3.2) then simply follows by applying (2.1) and rearranging some terms. \square

Next, we consider the case in which u_{ν} is constant on Γ with no constraint on the values of u on Γ .

Corollary 3.3 (Constant Neumann condition). *Suppose $\Omega \subset \mathbb{R}^N$, $N \geq 2$, is a bounded domain as defined in (2.4).*

Let q be as in (1.4) and set $h = q - u$, where $u \in C^2(\bar{\Omega})$ is a solution of (1.1). Further, suppose that u satisfies (1.12). Then the identity (1.13) holds, that is:

$$\int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 \, dx = \frac{1}{2} \int_{\Gamma} |\nabla_{\Gamma} u|^2 h_{\nu} \, dS_x + \int_{\Gamma} (\bar{u} - u) [(N-1) RH - N] h_{\nu} \, dS_x - \int_{\Gamma} (\bar{u} - u) \langle (\nabla \nu) \nabla_{\Gamma} u, \nabla_{\Gamma} u \rangle \, dS_x.$$

Proof. We work on (3.2). As already observed, we compute that $\Delta P = |\nabla^2 h|^2$. Next, we compute the surface integrals at the right-hand side. We begin with

$$\int_{\Gamma} u_{\nu}^2 (u_{\nu} - q_{\nu}) \, dS_x = R^2 \int_{\Gamma} (u_{\nu} - q_{\nu}) \, dS_x = 0,$$

thanks to the divergence theorem. Next, we compute that

$$\begin{aligned} \frac{1}{2} \int_{\Gamma} |\nabla_{\Gamma} u|^2 (u_{\nu} + q_{\nu}) dS_x - \int_{\Gamma} \langle \nabla_{\Gamma} q, \nabla_{\Gamma} u \rangle u_{\nu} dS_x = \\ \frac{1}{2} \int_{\Gamma} |\nabla_{\Gamma} u|^2 (R + q_{\nu}) dS_x - R \int_{\Gamma} (\bar{u} - u) \Delta_{\Gamma} q dS_x. \end{aligned}$$

Here, we used (1.12) and (2.3), in the second integral.

Moreover, we infer that

$$\int_{\Gamma} (\bar{u} - u) \Delta_{\Gamma} q dS_x = -(N-1) \int_{\Gamma} (\bar{u} - u) H q_{\nu} dS_x + (N-1) \int_{\Gamma} (\bar{u} - u) dS_x.$$

This follows from the fact that taking $v = q$ in (2.2) gives:

$$\Delta_{\Gamma} q = (N-1)(1 - H q_{\nu}) \quad \text{on } \Gamma.$$

Now, we apply item (ii) of Lemma 2.1 and get:

$$\begin{aligned} \int_{\Gamma} (\bar{u} - u) \langle \nabla^2 u \nabla u, \nu \rangle dS_x = - \int_{\Gamma} (\bar{u} - u) \langle (\nabla \nu) \nabla_{\Gamma} u, \nabla_{\Gamma} u \rangle dS_x + \\ R \int_{\Gamma} (\bar{u} - u) [N - \Delta_{\Gamma} u - (N-1)RH] dS_x. \end{aligned}$$

Moreover, thanks to (2.3) we compute that

$$\int_{\Gamma} (\bar{u} - u) \Delta_{\Gamma} u dS_x = \int_{\Gamma} |\nabla_{\Gamma} u|^2 dS_x.$$

Thus, we can write that

$$\begin{aligned} \int_{\Gamma} (\bar{u} - u) \langle \nabla^2 u \nabla u, \nu \rangle dS_x = - \int_{\Gamma} (\bar{u} - u) \langle (\nabla \nu) \nabla_{\Gamma} u, \nabla_{\Gamma} u \rangle dS_x + \\ - (N-1)R^2 \int_{\Gamma} (\bar{u} - u) H dS_x - R \int_{\Gamma} |\nabla_{\Gamma} u|^2 dS_x + NR \int_{\Gamma} (\bar{u} - u) dS_x. \end{aligned}$$

Summing up all these formulas then gives (1.13), after straightforward algebraic manipulations. \square

We now present a quadratic-radial symmetry test. Its analogous for the solution of (1.1), (1.3) essentially provides the spherical detector used in [31, 27, 3, 19, 20] (see also [29, Lemma 1.9] for additional details). Here, we rather focus on solutions of (1.1), (1.12). For comparison, we also provide (in item (i)) a version of its analogous for the solution of (1.1), (1.11).

Lemma 3.4 (Radial symmetry test). *Let Ω be a bounded domain in \mathbb{R}^N as defined in (2.4).*

Let $u \in C^2(\bar{\Omega})$ be a solution of (1.1) satisfying either (1.11) or (1.12). If $\Delta P \equiv 0$ in Ω , then u is a quadratic polynomial and Γ is a sphere of radius R given by (1.5).

Proof. We know that

$$\Delta P = |\nabla^2 u|^2 - \frac{(\Delta u)^2}{N} = |\nabla^2 u|^2 - \frac{\langle \nabla^2 u, I \rangle^2}{N} \geq 0.$$

Here, $\langle \cdot, \cdot \rangle$ denotes the inner product in \mathbb{R}^{N^2} and hence the last inequality follows by the Cauchy-Schwarz inequality. Thus, the fact that $\Delta P \equiv 0$

gives that the N^2 -vectors $\nabla^2 u$ and I coincide in Ω , being as (1.1) in force. Therefore, u is a quadratic polynomial of the form (1.4) for some $z \in \mathbb{R}^N$ and $a \in \mathbb{R}$ (see also [19, 20] and [29, Lemma 1.9]).

(i) If (1.11) holds then we have that $|x - z|^2 = 2(u_0 - a)$ for every $x \in \Gamma$. Hence, Γ must be a sphere of radius $\sqrt{2(u_0 - a)}$ and we have that $x - z = \sqrt{2(u_0 - a)}\nu(x)$. Thus, we obtain that

$$\begin{aligned} 2(u_0 - a)|\Gamma| &= \int_{\Gamma} |x - z|^2 dS_x = \\ &= \sqrt{2|u_0 - a|} \int_{\Gamma} \langle x - z, \nu(x) \rangle dS_x = N|\Omega| \sqrt{2|u_0 - a|}. \end{aligned}$$

Consequently, (1.5) gives that $2(u_0 - a) = R^2$,

$$u(x) = \frac{1}{2}(|x - z|^2 - R^2) + u_0,$$

and Γ is a sphere centered at z of radius R .

(ii) If (1.12) holds, since u is a quadratic polynomial as in (1.4), we infer that

$$(3.3) \quad \langle x - z, \nu(x) \rangle = u_{\nu}(x) = R \quad \text{for } x \in \Gamma.$$

Next, let x^m and x^M be points in Γ such that

$$|x^m - z| = \min_{x \in \Gamma} |x - z| \quad \text{and} \quad |x^M - z| = \max_{x \in \Gamma} |x - z|.$$

It is clear that $x^m - z$ and $x^M - z$ are parallel to $\nu(x^m)$ and $\nu(x^M)$. Hence, (3.3) gives that $|x^m - z| = |x^M - z| = R$, i.e. $|x - z| = R$ for every $x \in \Gamma$. Thus, again, Γ must be the sphere centered at z of radius R . \square

A consequence of item (ii) of this lemma and Corollary 3.3 is Theorem 1.3, the general rigidity result stated in the Introduction.

Proof of Theorem 1.3. The assumption on the right-hand side of (1.13) forces the function $|\nabla^2 h|^2 = \Delta P$ to be identically zero, being as $\bar{u} - u > 0$ by the strong maximum principle. Our claim then follows from Lemma 3.4. \square

4. ESTIMATES FOR SOLUTIONS OF THE NEUMANN PROBLEM

In this section, we derive some geometric and spectral estimates for solutions of (1.1), (1.12), which will be useful to trace the dependence of the constant c in Theorems 1.1 and 1.2.

We begin with a geometric inequality that adapts [20, Lemma 3.1], obtained for the solution of (1.1), (1.11).

Lemma 4.1. *Let Ω be a bounded domain in \mathbb{R}^N . Let $u \in C^2(\bar{\Omega})$ be a solution of (1.1). Then, it holds that*

$$\bar{u} - u(x) \geq \frac{1}{2} \delta_{\Gamma}(x)^2 \quad \text{for every } x \in \bar{\Omega}.$$

Moreover, if Γ is of class C^1 and satisfies the uniform interior sphere condition with radius r_i , then

$$\bar{u} - u(x) \geq \frac{1}{2} r_i \delta_{\Gamma}(x) \quad \text{for every } x \in \bar{\Omega}.$$

Proof. Let us define by f the unique solution of

$$\Delta f = N \text{ in } \Omega, \quad f = 0 \text{ on } \Gamma.$$

Then, by comparison $\bar{u} - u \geq -f$ in $\bar{\Omega}$, and the conclusion follows by [20, Lemma 3.1]. \square

We shall now derive a priori estimates on the harmonic function $h = q - u$ and its derivatives, in terms of geometric, spectral, and regularity parameters of the domain Ω .

In what follows, we shall use the fact that a function u satisfying (1.1) and (1.12) minimizes the functional $\mathcal{E} : W^{1,2}(\Omega) \rightarrow \mathbb{R}$ defined by

$$\mathcal{E}(v) = \frac{1}{2} \int_{\Omega} |\nabla v|^2 dx + N \int_{\Omega} v dx - R \int_{\Gamma} v dS_x,$$

for any $v \in W^{1,2}(\Omega)$. In the following result, $\nu_2(\Omega)$, $\sigma_2(\Omega)$, denote the second (non-trivial) Neumann and Steklov eigenvalues. Respectively, they are defined by

$$\nu_2(\Omega) = \min \left\{ \int_{\Omega} |\nabla v|^2 dx : v \in W^{1,2}(\Omega), \int_{\Omega} v^2 dx = 1, \int_{\Omega} v dx = 0 \right\}.$$

and

$$\sigma_2(\Omega) = \min \left\{ \int_{\Omega} |\nabla v|^2 dx : v \in W^{1,2}(\Omega), \int_{\Gamma} v^2 dS_x = 1, \int_{\Gamma} v dS_x = 0 \right\}.$$

Proposition 4.2 (L^2 bound for oscillation). *Let Ω be a bounded domain in \mathbb{R}^N as defined in (2.4). Let $u \in C^2(\bar{\Omega})$ be a solution of (1.1), (1.12) and set $h = q - u$, with q given by (1.4). Then, it holds that*

$$(4.1) \quad \|h - h_{\Omega}\|_{2,\Omega} \leq \frac{2 \|R - q_{\nu}\|_{2,\Gamma}}{\sqrt{\nu_2(\Omega) \sigma_2(\Omega)}}.$$

Here, h_{Ω} denotes the mean value of h on Ω .

Proof. Since h is harmonic in Ω and $h_{\nu} = q_{\nu} - R$ on Γ , it is clear that h minimizes in $W^{1,2}(\Omega)$ the functional defined by

$$W^{1,2}(\Omega) \ni v \mapsto \frac{1}{2} \int_{\Omega} |\nabla v|^2 dx - \int_{\Gamma} v (q_{\nu} - R) dS_x.$$

By taking $v \equiv 1$, the minimality of h then gives that

$$\int_{\Omega} |\nabla h|^2 dx \leq 2 \int_{\Gamma} h (q_{\nu} - R) dS_x = 2 \int_{\Gamma} (h - h_{\Gamma}) (q_{\nu} - R) dS_x,$$

where h_{Γ} is the mean value of h on Γ . Here, we used that $q_{\nu} - R$ has a zero mean value on Γ . The Cauchy-Schwarz inequality and the definition of $\sigma_2(\Omega)$ then give that

$$\int_{\Omega} |\nabla h|^2 dx \leq 2 \|q_{\nu} - R\|_{2,\Gamma} \|h - h_{\Gamma}\|_{2,\Gamma} \leq \frac{2 \|q_{\nu} - R\|_{2,\Gamma}}{\sqrt{\sigma_2(\Omega)}} \|\nabla h\|_{2,\Omega},$$

and hence

$$\|h - h_{\Omega}\|_{2,\Omega}^2 \leq \nu_2(\Omega)^{-1} \int_{\Omega} |\nabla h|^2 dx \leq \frac{4 \|q_{\nu} - R\|_{2,\Gamma}^2}{\nu_2(\Omega) \sigma_2(\Omega)},$$

by the Poincaré inequality. Thus, (4.1) ensues. \square

Remark 4.3. Thanks to [4, Theorems 1 and 2], we have that, within the class of uniformly bounded and uniformly Lipschitz domains, $\nu_2(\Omega)$ and $\sigma_2(\Omega)$ are bounded from below by a positive constant independent of Ω .

Theorem 4.4 (Uniform bound for the derivatives of h). *Set $m = 1$ or $m = 2$. Let Ω be a bounded domain in \mathbb{R}^N of class $C^{m,\alpha}$, $0 \leq \alpha < 1$. Let u be a solution of (1.1), (1.12) and set $h = q - u$, with q given by (1.4). Then, there exists a constant C that depends on N , d_Ω , and the $C^{m,\alpha}$ regularity of Γ , such that*

$$\|h - h_\Omega\|_{m,\alpha;\Omega} \leq C,$$

where $\|\cdot\|_{m,\alpha;\Omega}$ denotes the norm in $C^{m,\alpha}(\Omega)$.

Proof. For simplicity of notation, in this proof by the same letter c we shall denote a generic constant, whose dependence will be specified if needed.

We have that h is harmonic in Ω and $h_\nu = q_\nu - R$ on Γ . We thus can apply a standard a priori estimate for the Neumann problem (see e.g., [17, Chapter 7]; see also [14, Theorem 6.30] for $m = 2$) to obtain that

$$(4.2) \quad \|h\|_{m,\alpha;\Omega} \leq c \left(\max_{\overline{\Omega}} |h - h_\Omega| + \|q_\nu - R\|_{m-1,\alpha;\Gamma} \right).$$

Here, c depends on N, m, α, d_Ω , and the $C^{m,\alpha}$ regularity of Γ . By arguing as in [24, Lemma 4.9] (see also [25]) we can find a constant c such that

$$(4.3) \quad \max_{\overline{\Omega}} |h - h_\Omega| = \max_{\Gamma} |h - h_\Omega| \leq c \left\{ \frac{\|h - h_\Omega\|_{2,\Omega}}{\sigma^{N/2}} + \sigma \|\nabla h\|_{\infty,\Omega} \right\},$$

for any $0 < \sigma < \sigma_0$. Here, c and σ_0 only depend on N, d_Ω , and the $C^{m,\alpha}$ -regularity of Γ .³

Now, if we choose $\sigma = \min\{1/(2c^2), \sigma_0\}$ (here, c is the maximum of the two constants appearing in (4.2) and (4.3)) and we plug (4.3) into (4.2), we easily find that

$$\|h\|_{m,\alpha;\Omega} \leq c (\|h - h_\Omega\|_{2,\Omega} + \|q_\nu - R\|_{m-1,\alpha;\Gamma}),$$

by using the trivial inequality $\|\nabla h\|_{\infty,\Omega} \leq \|h\|_{m,\alpha;\Omega}$. Here, c can be explicitly derived in terms of σ_0 and the constants in (4.2) and (4.3).

The term $\|q_\nu - R\|_{m-1,\alpha;\Gamma}$ can be easily bounded by a constant depending on the same relevant parameters. Finally, Proposition 4.2 and Remark 4.3 ensure that the norm $\|h - h_\Omega\|_{2,\Omega}$ can be bounded by a constant depending on the same relevant parameters. The desired conclusion then ensues. \square

5. QUANTITATIVE SYMMETRY RESULTS

In this section, based on the identity (1.13), we shall provide our stability estimates for the radial symmetry in the reverse Serrin overdetermined problem (Theorems 1.1 and 1.2). To this aim, for a point $z \in \Omega$, we recall the definition (1.7):

$$\rho_i = \min_{x \in \Gamma} |x - z| \quad \text{and} \quad \rho_e = \max_{x \in \Gamma} |x - z|.$$

³This argument gives a constant depending on N and the parameters related to a uniform interior cone condition. This condition is equivalent to a Lipschitz-type regularity of Γ (see [24] for details). Of course, the relevant parameters can be bounded in terms of the $C^{1,\alpha}$ regularity of Γ .

It is clear that ρ_i is the radius of the largest ball contained in Ω and ρ_e is the radius of the smallest ball that contains Ω , both balls centered at z .

Thus, for a solution u of (1.1), (1.12), we want to bound the difference $\rho_e - \rho_i$ in terms of the sum of the oscillation of u on Γ and a suitable Lebesgue norm of $|\nabla_\Gamma u|$ on Γ .

Remark 5.1. Let u be a solution of (1.1), (1.12). A convenient choice for the point z in (1.7) is any minimum point of u in $\overline{\Omega}$. In fact, such a point must fall in Ω , since otherwise $u_\nu \leq 0$ at that point, contrary to (1.12).

We shall first adapt to our case some estimates on the oscillation of a harmonic function, which were derived in [23].

5.1. Interpolating estimates for Sobolev functions. We now recall three key inequalities for the oscillation of a harmonic function. These descend from some interpolation inequalities proved in [23, Theorem 4.1] (see also [24, Appendix]). Here, we present these inequalities for C^2 domains, as it is enough for the purposes of the present paper. Nevertheless, the original theorem was stated and proved for a bounded domain satisfying the (θ, a) -uniform cone condition (see [24, Appendix] for a definition).

Lemma 5.2. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with boundary Γ of class C^2 , and let u be solution of (1.1), (1.12).*

Let $h = q^z - u$, where q^z is that in (1.4) and z is any global minimum point of u in $\overline{\Omega}$. Then, we have that

$$\text{osc}_\Gamma h \leq c \begin{cases} \|\sqrt{\delta_\Gamma} \nabla^2 h\|_{2,\Omega} & \text{if } N = 2, \\ \|\sqrt{\delta_\Gamma} \nabla^2 h\|_{2,\Omega} \max \left[\log \left(\frac{e \|\nabla h\|_{\infty,\Omega}}{\|\sqrt{\delta_\Gamma} \nabla^2 h\|_{2,\Omega}} \right), 1 \right] & \text{if } N = 3, \\ \|\nabla h\|_{\infty,\Omega}^{\frac{N-3}{N-1}} \|\sqrt{\delta_\Gamma} \nabla^2 h\|_{2,\Omega}^{\frac{2}{N-1}} & \text{if } N \geq 4, \end{cases}$$

where c is an explicit constant that only depends on N, d_Ω, r_i , and a lower bound for $\delta_\Gamma(z)$.

Proof. By definition of h and the choice of z , we have that h is harmonic and that $\nabla h(z) = 0$ at the point $z \in \Omega$.

The desired result is essentially contained in [23, Theorem 4.1]. To be precise, that theorem gives an estimate for the difference $\rho_e - \rho_i$, which is there related to the oscillation of the particular harmonic function $v = q - f$, where f is the solution of the Dirichlet problem (1.1), (1.3) and q is given in (1.4). Indeed there holds that

$$\max_\Gamma v - \min_\Gamma v = \frac{1}{2} (\rho_e^2 - \rho_i^2)$$

and

$$(5.1) \quad \rho_e^2 - \rho_i^2 \geq \left(\frac{|\Omega|}{|B|} \right)^{\frac{1}{N}} (\rho_e - \rho_i).$$

Now, if u is a solution of the Neumann problem (1.1), (1.12), instead, u is no longer constant on Γ . Nevertheless, a careful inspection reveals that the inequalities contained in [23, Theorem 4.1] concern the oscillation on Γ of any harmonic function in Ω , whose gradient vanishes at a given point z

in Ω , and that the constant c only depends on N , d_Ω , r_i , and a lower bound of the distance $\delta_\Gamma(z)$ of z to Γ . Thus, the desired result follows. \square

Remark 5.3. By adapting the arguments of [21, Remark 2.9] (see also [22] for generalizations) to the present setting, we can choose $x \in \Omega$ such that $\delta_\Gamma(x) = r_i$, $y \in \Gamma$ such that $|y - z| = \delta_\Gamma(z)$ and, recalling Lemma 4.1, compute that

$$\begin{aligned} \frac{r_i^2}{2} \leq \bar{u} - u(x) &\leq \bar{u} + \max_{\Omega}(-u) = \bar{u} - u(z) = \\ &\bar{u} - u(y) + u(y) - u(z) \leq \operatorname{osc}_{\Gamma} u + \|\nabla u\|_{\infty, \Omega} \delta_\Gamma(z), \end{aligned}$$

from which we get that

$$\delta_\Gamma(z) \geq \frac{r_i^2 - 2 \operatorname{osc}_{\Gamma} u}{2 \|\nabla u\|_{\infty, \Omega}}.$$

In the following lemma, we use the tangential norm defined by

$$\|\bar{u} - u\|_{1,2,\tau,\Gamma}^2 = \|\bar{u} - u\|_{2,\Gamma}^2 + \|\nabla_\Gamma u\|_{2,\Gamma}^2.$$

Lemma 5.4. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with boundary Γ of class C^2 , and let u be a solution of (1.1), (1.12).*

Let $h = q - u$, where q is that in (1.4) and z is any global minimum point of u in $\bar{\Omega}$. Then, we have that

$$\int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx \leq c \left[1 + \operatorname{osc}_{\Gamma} u \right] \|\bar{u} - u\|_{1,2,\tau,\Gamma}^2,$$

where c is an explicit constant that only depends on N , d_Ω , r_i , r_e , and a lower bound for $\delta_\Gamma(z)$.

Proof. For simplicity of notation, in this proof by the same letter c we shall denote a generic constant, whose dependence will be specified if needed.

We start working on the right-hand side (1.13). By Remark 2.2 and the Holder inequality, we see that there is a constant c , only depending on N , d_Ω , r_e and r_i , such that

$$\begin{aligned} \int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx \leq \\ c \left[\int_{\Gamma} |\nabla_\Gamma u|^2 dS_x + \|h_\nu\|_{2,\Gamma} \|\bar{u} - u\|_{2,\Gamma} + \|\bar{u} - u\|_{\infty,\Gamma} \int_{\Gamma} |\nabla_\Gamma u|^2 dS_x \right]. \end{aligned}$$

Here, we have used the fact that $|h_\nu| \leq d_\Omega + R$ on Γ .

Next, let us define by f the unique solution of

$$\Delta f = N \quad \text{in } \Omega, \quad f = 0 \quad \text{on } \Gamma.$$

By [21, Lemma 2.5] applied with $v = h$, we obtain that

$$\int_{\Gamma} h_\nu^2 dS_x \leq \int_{\Gamma} |\nabla h|^2 dS_x \leq c \int_{\Omega} (-f) |\nabla^2 h|^2 dx$$

where c is an explicit constant that only depends on N , d_Ω , r_i , and a lower bound for $\delta_\Gamma(z)$. Since, by comparison, $\bar{u} - u \geq -f$ on $\bar{\Omega}$, we then infer that

$$\int_{\Gamma} h_\nu^2 dS_x \leq c \int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx.$$

Hence, this formula and the trivial inequalities

$$\|\bar{u} - u\|_{\infty, \Gamma} \leq \text{osc}_{\Gamma} u, \quad \|\bar{u} - u\|_{2, \Gamma} \leq \|\bar{u} - u\|_{1, 2, \tau, \Gamma}, \quad \|\nabla_{\Gamma} u\|_{2, \Gamma} \leq \|\bar{u} - u\|_{1, 2, \tau, \Gamma}$$

give that

$$\int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx \leq c \|\bar{u} - u\|_{1, 2, \tau, \Gamma} \left[\left(1 + \text{osc}_{\Gamma} u\right) \|\bar{u} - u\|_{1, 2, \tau, \Gamma} + \sqrt{\int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx} \right].$$

This inequality easily gives the desired bound. \square

We are now in position to prove our quantitative estimates for the radial symmetry in the reverse Serrin problem.

Proof of Theorem 1.1. Set

$$(5.2) \quad \sigma = \min \left\{ 1, \frac{r_i^2}{4} \right\}.$$

We first notice that if

$$\text{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma} \geq \sigma,$$

then the conclusion trivially holds true. In fact, by recalling the definition of ψ in (1.8), we easily get that

$$\rho_e - \rho_i \leq d_{\Omega} \leq \begin{cases} \frac{d_{\Omega}}{\sigma} \psi(\text{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma}) & \text{if } N = 2, 3, \\ \frac{d_{\Omega}}{\sigma^{2/(N-1)}} \psi(\text{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma}) & \text{if } N \geq 4. \end{cases}$$

Thus, it only remains to prove the result when

$$\text{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma} < \sigma.$$

Under this assumption and recalling (1.1) and (1.12), it is clear that

$$(5.3) \quad \|\nabla u\|_{\infty, \Omega} = \|\nabla u\|_{\infty, \Gamma} = \|\nabla_{\Gamma} u + u_{\nu} \nu\|_{\infty, \Gamma} < \sigma + R \leq \sigma + d_{\Omega}.$$

The last inequality follows from (1.5) and by putting together the isoperimetric inequality $|\Gamma| \geq N|B|^{1/N}|\Omega|^{(N-1)/N}$ and the trivial bound $|\Omega| \leq |B|d_{\Omega}^N$.

As usual, we consider the harmonic function $h = q - u$ and choose the minimum point of q to coincide with the point z in our assumptions. Since z is a minimum point for both q and u , we have that $\nabla h(z) = 0$.

Thanks to Lemma 4.1, the left-hand side of identity (1.13) can be estimated from below as

$$(5.4) \quad \frac{1}{2} r_i \int_{\Omega} \delta_{\Gamma} |\nabla^2 h|^2 dx \leq \int_{\Omega} (\bar{u} - u) |\nabla^2 h|^2 dx.$$

Now, from (5.1) we infer that

$$(5.5) \quad \frac{1}{2} \left(\frac{|\Omega|}{|B|} \right)^{\frac{1}{N}} (\rho_e - \rho_i) \leq \text{osc}_{\Gamma} q \leq \text{osc}_{\Gamma} h + \text{osc}_{\Gamma} u.$$

Combining Lemma 5.2, Lemma 5.4, (5.4), and the trivial inequality $\sqrt{a^2 + b^2} \leq |a| + |b|$, we infer that

$$(5.6) \quad \operatorname{osc}_{\Gamma} h \leq c \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma} \right),$$

for some explicit constant c that only depends on N, d_{Ω}, r_e , and r_i . Here, we used two facts. Firstly, (5.3), (5.2) and the trivial bound $\|\nabla q\|_{\infty, \Omega} \leq d_{\Omega}$ give the explicit upper bound for $|\nabla h|$:

$$\|\nabla h\|_{\infty, \Omega} \leq \|\nabla q\|_{\infty, \Omega} + \|\nabla u\|_{\infty, \Omega} \leq \min \left\{ 1, \frac{r_i^2}{4} \right\} + 2d_{\Omega}.$$

Secondly, combining Remark 5.3, (5.3), (5.2), and the current smallness assumption on the deviation of u from being constant on Γ , gives the explicit lower bound for $\delta_{\Gamma}(z)$:

$$\delta_{\Gamma}(z) \geq \frac{r_i^2}{2 \left(\min \left\{ 1, \frac{r_i^2}{4} \right\} + d_{\Omega} \right)}.$$

Finally, by the trivial inequality $\operatorname{osc}_{\Gamma} u \leq \operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma}$ and the definition of ψ , we easily obtain that

$$\psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma} \right) + \operatorname{osc}_{\Gamma} u \leq C \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma} \right),$$

with

$$C = \begin{cases} 2 & \text{if } N = 2, 3, \\ 1 + \sigma^{(N-3)/(N-1)} & \text{if } N \geq 4, \end{cases}$$

where σ is that defined in (5.2).

The conclusion easily follows by putting together the last inequality, (5.6), and (5.5). \square

Proof of Theorem 1.2. We shall adapt the argument used in the proof of Theorem 1.1 to the setting with the current deviation.

Let σ be given by (5.2). As before, it is clear that it is enough to check the case in which

$$\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{2, \Gamma} < \sigma.$$

This time, we observe that

$$(5.7) \quad \|\nabla u\|_{\infty, \Omega} \leq \|\nabla q\|_{\infty, \Omega} + \|\nabla h\|_{\infty, \Omega} \leq d_{\Omega} + \|\nabla h\|_{\infty, \Omega}.$$

An explicit bound for $\|\nabla h\|_{\infty, \Omega}$ will be obtained at the end of the proof.

Also, as before we can use (5.4). Similarly, by proceeding as in the proof of Theorem 1.1, with $\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{\infty, \Gamma}$ replaced by $\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{2, \Gamma}$, we arrive at the inequalities

$$(5.8) \quad \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{2, \Gamma} \right) + \operatorname{osc}_{\Gamma} u \leq C \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{2, \Gamma} \right)$$

and

$$(5.9) \quad \operatorname{osc}_{\Gamma} h \leq c \psi \left(\operatorname{osc}_{\Gamma} u + \|\nabla_{\Gamma} u\|_{2, \Gamma} \right).$$

Here, ψ is that in (1.8), C is the same constant appearing in the proof of Theorem 1.1, and c is an explicit constant that only depends on N, d_Ω, r_i, r_e , a lower bound for $\delta_\Gamma(z)$, and an upper bound for $\|\nabla h\|_{\infty, \Omega}$.

The desired conclusion will easily follow from (5.5), (5.9), and (5.8), after obtaining suitable bounds for $\delta_\Gamma(z)$ and $\|\nabla h\|_{\infty, \Omega}$.

By putting together (5.2), Remark 5.3, (5.7), and the current smallness assumption on the deviation of u from being constant on Γ , we easily get that

$$\delta_\Gamma(z) \geq \frac{r_i^2}{4(d_\Omega + \|\nabla h\|_{\infty, \Omega})}.$$

We are thus left to obtain an upper bound for $\|\nabla h\|_{\infty, \Omega}$.

Thanks to Theorem 4.4 (with $m = 1$) and recalling [2, Corollary 3.14], $\|\nabla h\|_{\infty, \Omega}$ can be clearly bounded by a constant that depends on N, d_Ω, r_i , and r_e .

When Γ is of class $C^{2, \alpha}$, we can obtain an improvement of the profile ψ , by arguing as in [23, Lemma 4.2 and Corollary 4.3] (with $p = 2, q = +\infty$). In fact, we infer that

$$\|\nabla h\|_{\infty, \Omega} \leq c \|\nabla^2 h\|_{\infty, \Omega}^{(N-1)/(N+1)} \|\delta_\Gamma^{1/2} \nabla^2 h\|_{2, \Omega}^{2/(N+1)},$$

for some c depending on N, d_Ω, r_i, r_e . Hence, by recalling Theorem 4.4 (with $m = 2$), we easily get that

$$\|\nabla h\|_{\infty, \Omega} \leq c \|\delta_\Gamma^{1/2} \nabla^2 h\|_{2, \Omega}^{2/(N+1)},$$

where c depends on N, d_Ω , and the $C^{2, \alpha}$ -regularity of Γ .

Plugging the last inequality in Lemma 5.2 and using Lemma 5.4 and (5.4) as before, gives (5.9) with the improved profile shown in (1.9). Clearly, for this profile, (5.8) remains true with C given by

$$C = \begin{cases} 2 & \text{if } N = 2, 3, \\ 1 + \sigma^{(N-3)/(N+1)} & \text{if } N \geq 4. \end{cases}$$

Thus, combining (5.5), (5.9), and (5.8) gives the improved stability for $N \geq 4$. \square

6. STABILITY VIA THE CLASSICAL SERRIN PROBLEM

We now present a quantitative bound for the reverse Serrin problem that can be obtained exploiting the existing stability results for the classical Serrin problem. The proof is based on a simple trick. As discussed in the Introduction, we get a poorer estimate than those obtained in Theorems 1.1 and 1.2. In fact, the main drawback is that the deviations $\text{osc}_\Gamma u + \|\nabla_\Gamma u\|_{\infty, \Gamma}$ and $\text{osc}_\Gamma u + \|\nabla_\Gamma u\|_{2, \Gamma}$ used in Theorems 1.1 and 1.2 must be replaced by the much more stringent deviation $\|\bar{u} - u\|_{C^{1, \alpha}(\Gamma)}$.

We start with an estimate for an auxiliary function.

Proposition 6.1. *Let $\Omega \subset \mathbb{R}^N$, $N \geq 2$, be a bounded domain with boundary Γ of class $C^{1, \alpha}$, $0 < \alpha < 1$. Let u be a solution of (1.1), (1.12).*

Set $f = u - w$, where w is the solution of the Dirichlet problem

$$\Delta w = 0 \text{ in } \Omega, \quad w = u \text{ on } \Gamma.$$

Then, we have that

$$\|R - f_\nu\|_{C^{0,\alpha}(\Gamma)} \leq c \|\bar{u} - u\|_{C^{1,\alpha}(\Gamma)}.$$

Here, c only depends on N and the $C^{1,\alpha}$ -regularity of Γ .

Proof. We notice that

$$\|R - f_\nu\|_{C^{0,\alpha}(\Gamma)} = \|w_\nu\|_{C^{0,\alpha}(\Gamma)} \leq \|\bar{u} - w\|_{C^{1,\alpha}(\bar{\Omega})}.$$

The desired conclusion then follows from [14, Theorem 8.33]. \square

Theorem 6.2 (The reverse Serrin problem with strong deviation). *Let Ω be a bounded domain in \mathbb{R}^N , $N \geq 2$, with boundary Γ of class $C^{1,1}$.*

Let u be solution of (1.1), (1.12), and let z be any global minimum point of u on $\bar{\Omega}$. Then, we have that

$$\rho_e - \rho_i \leq c \psi (\|u - \bar{u}\|_{C^{1,\alpha}(\Gamma)}),$$

where ψ is the profile defined in (1.8). The constant c only depends on N , d_Ω , r_i , and r_e .

For $N \geq 4$ the profile ψ can be improved to obtain (1.9), at the cost of replacing the dependence of c on the r_i and r_e with that on the $C^{2,\alpha}$ -regularity of Γ .

Proof. It is clear that the function f defined in Proposition 6.1 satisfies:

$$\Delta f = N \text{ in } \Omega, \quad f = 0 \text{ on } \Gamma.$$

By [21, Theorem 3.1] (for $N \neq 3$) and [23, Theorem 4.4] (for $N = 3$), we have that

$$\rho_e - \rho_i \leq c \psi (\|f_\nu - R\|_{L^2(\Gamma)}),$$

where c only depends on N , d_Ω , r_i , and r_e . Here, ψ is as in (1.8).

Furthermore, the improvement of the profile ψ to (1.9) for $N \geq 4$ is obtained from [23, Theorem 4.4], at the aforementioned cost.

The conclusion then follows from Proposition 6.1 and by noting that

$$\|f_\nu - R\|_{L^2(\Gamma)} \leq |\Gamma|^{1/2} \|f_\nu - R\|_{L^\infty(\Gamma)} \leq |\Gamma|^{1/2} \|f_\nu - R\|_{C^{0,\alpha}(\Gamma)}.$$

As usual, $|\Gamma|$ can be estimated in terms of the desired parameters by recalling [23, Remark 3.1]. \square

Remark 6.3. The argument may be adjusted to work also in the semilinear case, at the cost of replacing the application of [21, Theorem 3.1] and [23, Theorem 4.4] by the results in [1, 10], and hence obtaining a more general but poorer stability estimate.

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