

## FLORE

## Repository istituzionale dell'Università degli Studi

 di Firenze
## Geodesics in the space of Kaehler cone metrics, I

Questa è la Versione finale referata (Post print/Accepted manuscript) della seguente pubblicazione:
Original Citation:
Geodesics in the space of Kaehler cone metrics, I / Simone, Calamai; Kai, Zheng. - In: AMERICAN JOURNAL OF MATHEMATICS. - ISSN 0002-9327. - STAMPA. - 137:(2015), pp. 1149-1208. [10.1353/ajm.2015.0036]

Availability:
This version is available at: 2158/863501 since: 2021-03-18T13:56:12Z

Published version:
DOI: 10.1353/ajm.2015.0036

Terms of use:
Open Access
La pubblicazione è resa disponibile sotto le norme e i termini della licenza di deposito, secondo quanto stabilito dalla Policy per l'accesso aperto dell'Università degli Studi di Firenze
(https://www.sba.unifi.it/upload/policy-oa-2016-1.pdf)

Publisher copyright claim:

# GEODESICS IN THE SPACE OF KÄHLER CONE METRICS 

SIMONE CALAMAI AND KAI ZHENG


#### Abstract

In this paper, we study the Dirichlet problem of the geodesic equation in the space of Kähler cone metrics $\mathcal{H}_{\beta}$; that is equivalent to a homogeneous complex Monge-Ampère equation whose boundary values consist of Kähler metrics with cone singularities. Our approach concerns the generalization of the space defined in Donaldson [29] to the case of Kähler manifolds with boundary; moreover we introduce a subspace $\mathcal{H}_{C}$ of $\mathcal{H}_{\beta}$ which we define by prescribing appropriate geometric conditions. Our main result is the existence, uniqueness and regularity of $C_{\beta}^{1,1}$ geodesics whose boundary values lie in $\mathcal{H}_{C}$. Moreover, we prove that such geodesic is the limit of a sequence of $C_{\beta}^{2, \alpha}$ approximate geodesics under the $C_{\beta}^{1,1}$-norm. As a geometric application, we prove the metric space structure of $\mathcal{H}_{C}$.


## Contents

1. Introduction
2. The space of Kähler cone metrics ..... 6
3. A priori estimates ..... 12
3.1. $L^{\infty}$ estimate ..... 13
3.2. Interior Laplacian estimate ..... 14
3.3. Boundary Hessian estimate ..... 18
3.4. Interior gradient estimate ..... 22
4. Solving the geodesic equation ..... 25
4.1. Existence of the $C_{\beta}^{1,1}$ cone geodesic ..... 26
4.2. Interior Schauder estimate: $\tau>0$ ..... 29
4.3. An application to the Kähler-Einstein cone metrics ..... 32
4.4. Boundary Schauder estimate: $\tau>0$ ..... 34
4.5. Uniqueness of the $C_{\beta}^{1,1}$ cone geodesic ..... 36
5. Linearized equation ..... 36
5.1. The maximum principle and the weak solution ..... 37
5.2. Hölder estimates ..... 38
5.3. The Dirichlet problem of the linearized problem ..... 43
6. The metric space structure ..... 44
References ..... 45
[^0]
## 1. Introduction

We shall always denote by $X$ a smooth compact Kähler manifold without boundary of complex dimension $n \geq 1$, by [ $\omega_{0}$ ] a Kähler class of $X$, and by $\mathcal{H}$ the space of Kähler metrics in [ $\omega_{0}$ ]. In their pioneering works, Mabuchi 47], Donaldson [27] and Semmes [56, independently defined the famous Weil-Peterson type metric in $\mathcal{H}$, under which $\mathcal{H}$ becomes a non-positive curved infinite-dimensional symmetric space. Semmes 56] pointed out that the geodesic equation in $\mathcal{H}$ is a homogeneous complex Monge-Ampère (HCMA) equation,

$$
\begin{cases}\left(\Omega_{0}+\frac{\sqrt{-1}}{2} \partial \bar{\partial} \Psi\right)^{n+1}=0 & \text { in } X \times R  \tag{1.1}\\ \sum_{1 \leq i, j \leq n}\left(\Omega_{0}+\frac{\sqrt{-1}}{2} \partial \bar{\partial} \Psi\right)_{i \bar{j}} d z^{i} \wedge d z^{\bar{j}}>0 & \text { in } X \times\left\{z^{n+1}\right\}\end{cases}
$$

here $R$ is a cylinder with boundary, and $\Omega_{0}$ is the pull-back metric of $\omega_{0}$ under the natural projection.

Geodesics are basic geometric objects in the infinity dimensional manifold $\mathcal{H}$. The intensive relation between the geodesics of $\mathcal{H}$ and the existence and the uniqueness of the cscK metrics was pointed out by Donaldson in [27]. He also conjectured that $\mathcal{H}$ endowed with the Weil-Peterson type metric is geodesically convex and is a metric space. Chen [16] established the existence of $C^{1,1}$ geodesic segments (of bounded mixed derivatives) under smooth Dirichlet conditions and thus verified that the space of Kähler metrics is a metric space. Later, Blocki 9] proved the $C^{1,1}$ geodesic segment has bounded Hessian when $\left(X \times R, \Omega_{0}\right)$ has nonnegative bisectional curvature. Phong-Sturm 52, Song-Zeltdich 60 59 61 approximated the $C^{1,1}$ geodesic by the Bergman geodesics in finite-dimensional symmetric spaces. Later Chen and Tian in 13 improved the partial regularity of the $C^{1,1}$ geodesic, then proved the uniqueness of the extremal metrics. Donaldson [28, Darvas-Lempert [25] and Lempert-Vivas [45] showed that a $C^{1,1}$ geodesic does not need to be smooth in general. On the other hand, the geodesic ray induced by the test configuration is constructed in Arezzo-Tian [1], Chen-Tang [21], Phong-Sturm [54] 53 and Phong-Sturm 54]. The $C^{1,1}$ geodesic ray parallel to a given one is constructed in Chen 17] under the geometric condition "tamed by a bounded ambient geometry". We would like to remark that the existence of $C^{1,1}$ geodesic has been proved by Chen-He 20] in the space of volume forms on a Riemannian manifold, by P.-F. Guan-X. Zhang 38 in Sasakian manifolds and by B. Guan-Q. Li 35 in Hermitian manifolds.

In this paper, our aim is to construct the natural geodesic in the moduli space of all Kähler metrics singular along the divisor $D$ for future study. Let us isolate now the concept, central to our aim, of Kähler cone metric.

Definition 1.1. Let $X$ and $\left[\omega_{0}\right]$ as at the beginning of the paper, and let $D=$ $\sum_{i=1}^{m}\left(1-\beta_{i}\right) V_{i}$ be a normal crossing, effective smooth divisor of $X$ with $0<\beta_{i} \leq 1$ for $1 \leq i \leq m$, where $V_{i} \subset X$ are irreducible hypersurfaces. Set $\beta:=\left(\beta_{1}, \ldots, \beta_{m}\right)$ and call the $\beta_{i}$ 's the cone angles. Given a point $p$ in $D$, label a local chart $\left(U_{p}, z^{i}\right)$ centered at $p$ as local cone chart when $z^{1}, \ldots z^{k}$ are the local defining functions of the hypersurfaces where $p$ locates. A Kähler cone metric $\omega$ of cone angle $2 \pi \beta_{i}$ along $V_{i}$, for $1 \leq i \leq m$, is a closed positive $(1,1)$ current and a smooth Kähler metric on the regular part $M:=X \backslash D$. In a local cone chart $U_{p}$ its Kähler form is
quasi-isometric to the cone flat metric, which is

$$
\begin{equation*}
\omega_{\text {cone }}:=\frac{\sqrt{-1}}{2} \sum_{i=1}^{k} \beta_{i}^{2}\left|z^{i}\right|^{2\left(\beta_{i}-1\right)} d z^{i} \wedge d z^{\bar{i}}+\sum_{k+1 \leq j \leq n} d z^{j} \wedge d z^{\bar{j}} \tag{1.2}
\end{equation*}
$$

Let $\mathcal{H}_{\beta}$ be the space of Kähler cone metrics of cone angle $2 \pi \beta_{i}$ along $V_{i}$ in [ $\omega_{0}$ ]. It is clear that when for all $i$ there holds $\beta_{i}=1$, then $\mathcal{H}_{\beta}$ consists of all cohomologous smooth Kähler metrics on a compact Kähler manifold. Let $s$ be a global meromorphic section of $[D]$. Let $h$ be an Hermitian metric on $[D]$. It is shown in Donaldson [29] that, for sufficiently small $\delta>0$,

$$
\begin{equation*}
\omega=\omega_{0}+\delta \sum_{i=1}^{m} \frac{\sqrt{-1}}{2} \partial \bar{\partial}\left|s_{i}\right|_{h_{\Lambda}}^{2 \beta_{i}} \tag{1.3}
\end{equation*}
$$

is a Kähler cone metric. Moreover, $\omega$ is independent of the choices of $\omega_{0}, h_{\Lambda}, \delta$ up to quasi-isometry. We call it model metric in this paper.

A special Kähler cone metric is the Kähler-Einstein cone metric which is studied in many recent papers. They have been studied in McOwen [49, Troyanov 64 65] for Riemannian surfaces. The study of Kähler-Einstein cone metrics was initiated in Tian [62] and Tsuji [66] concerning various inequalities involving the Chern numbers. Recently, Donaldson [29] defined a new function space and developed a program to look for the smooth Kähler-Einstein metric by deforming the cone angle. Existence theorems are proved by Brendle [10] for Ricci flat Kähler cone metrics , by Jeffres, Mazzeo and Rubinstein 42] for the Fano case under the properness of the twisted K-energy , by Campana, Guenancia and Păun [12] for the normal crossing divisors and by Berman, Boucksom, Eyssidieux, Guedj, Zeriahi [5] on log Fano varieties. With the log- $\alpha$ invariants, Berman [4] solved the existence problem for small cone angles. After finishing our paper, more extensive developments of Donaldson's program on the application of the Kähler-Einstein cone metrics to the the Kähler-Einstein problem have appeared; we mention some of the most recent beautiful papers [14 15 , 18 , 19 .

In this paper, we study the geometry of the space of Kähler cone metrics, in particular, the geodesic in $\mathcal{H}_{\beta}$. Now we clarify the concept of geodesic in $\mathcal{H}_{\beta}$. A cone geodesic is a curve segment $\varphi \in \mathcal{H}_{\beta}$ for $0 \leq t \leq 1$ which satisfies the natural generalization of the problem (1.1); i.e. we are requiring that $\omega_{\varphi(t)}$ is a Kähler cone metric for any $0 \leq t \leq 1$. In this article, we find the geometric boundary conditions which assure the existence and the uniqueness of the cone geodesic. Those lead to an appropriate choice of a subspace of $\mathcal{H}_{\beta}$. As we will show in Section 2 the geodesic equation leads to the Dirichlet problem of the HCMA equation with the boundary potentials of cone singularities. The Dirichlet problem of HCMA was studied intensively by many authors under various analytic boundary conditions (see [3] 22] 37] 51] [11]..). In our particular environment, the underlying manifold is a product manifold and the curvature conditions on the background metrics play an important role as in the geometric-analysis problems (see the useful tricks we explain at the beginning of Section 3 and Remark 3.1).

The slight difference between our equation and the standard HCMA is that in our case the boundary values allow cone singularities. So the problem is how to choose the appropriate function spaces where the solutions live in. A possible function space could be the edge space. The corresponding elliptic theory is investigated by many authors (see Mazzeo [48, Melrose [50, Schulze [55] and references therein). In
this edge space, Jeffres, Mazzeo and Rubinstein 42 improved the higher regularity of the Kähler-Einstein cone metrics. In our environment, the problem is that the edge space is defined for manifolds without boundary; which is not our case. So, we do not use edge space in this paper. We overcome this problem by generalizing Donaldson's space to the boundary case (see Definition (2.3)), that is more natural for our geometric problem. However, it would be interesting to understand whether the edge space (or with some modification) could be defined near the boundary and how to improve the regularity in such space. Finally, it is interesting to see that the cone geodesic are translated as solution of the HCMA, then the cone singularities on the boundary travel naturally to the interior of the domain. We hope this phenomenon will be helpful to understand the solution of the complex Monge-Ampère equation.

Now we specify the geometric conditions on the boundary metrics. (The space $C_{\beta}^{3}$ is introduced in Definition 2.2.)

Definition 1.2. Assume $D$ is disjoint smooth hyper surface and the cone angles $\beta$ belong to the interval $\left(0, \frac{1}{2}\right)$. Then, we denote as $\mathcal{H}_{\beta}^{3}$ the space of $C_{\beta}^{3} \omega_{0^{-}}$ plurisubharmonic potentials. Moreover, we label as $\mathcal{H}_{C} \subset \mathcal{H}_{\beta}^{3}$ one of the following spaces;

$$
\begin{aligned}
& \mathfrak{I}_{1}=\left\{\varphi \in \mathcal{H}_{\beta}^{3} \text { such that } \sup \operatorname{Ric}\left(\omega_{\varphi}\right) \text { is bounded }\right\} ; \\
& \mathfrak{I}_{2}=\left\{\varphi \in \mathcal{H}_{\beta}^{3} \text { such that } \inf \operatorname{Ric}\left(\omega_{\varphi}\right) \text { is bounded }\right\}
\end{aligned}
$$

In general the Kähler cone metrics do not have bounded geometry. The Riemannian curvature of $\omega$ is bounded from below when when the cone angle is less than $\frac{1}{2}$. We will compute that the Levi-Civita connection of the model cone metric defined in (1.3) under the cone coordinate (see (2.1)) is bounded when the cone angle is less than $\frac{2}{3}$. So we need the curvature conditions of the boundary metrics to improve the regularities. The space $\mathcal{H}_{C}$ at least contains all Kähler-Einstein cone metrics with the cone angle between 0 and $\frac{1}{2}$ (see Proposition 6.7 in Brendle [10]). The further discussion on the properties of the subspace $\mathcal{H}_{C}$ will be in the forthcoming paper. In the present work, our main aim is to prove the following result (cf. Theorem4.5).

Theorem 1.1. Any two Kähler cone metrics in $\mathcal{H}_{C}$ are connected by a unique $C_{\beta}^{1,1}$ cone geodesic. More precisely, it is the limit under the $C_{\beta}^{1,1}$-norm by a sequence of $C_{\beta}^{2, \alpha}$ approximate geodesics.

The notion of approximate geodesic is given in Lemma 6.2 As an application, we prove the following result.

Theorem 1.2. $\mathcal{H}_{C}$ is a metric space.
Concerning geodesics with weak regularity, we should compare the construction in Berndtsson's remarkable paper [6] with our result. It is easy to compute that the volume of the Kähler cone metric belongs to $L^{p}$ with $p\left(\beta_{i}-1\right)+1>0$ for any $1 \leq i \leq k$. According to Kolodziej's theorem in [43], there exists a unique Hölder continuous $\omega_{0}$-plurisubharmonic potential. Berndtsson [6] proved that given two bounded $\omega_{0}$-plurisubharmonic potentials, there is a bounded geodesic connecting them. Then since the advantage of using the Ding functional (cf. Ding [26]) is that it requires less regularity of the potentials, as observed by Berndtsson, the convexity of
the Ding functional along the bounded geodesic is applied to prove the uniqueness of Kähler-Einstein cone metrics (generalizing the Bando-Mabuchi uniqueness theorem [2]). However the cone geodesic we construct here has more regularity across the divisor in a subspace $\mathcal{H}_{C}$ which still contains the critical metrics. The regularity of the cone geodesic across the divisor are not only important to prove the metric structure as we show in this paper, but also to our further application on existence and uniqueness of cscK cone metrics.

Now we state an application of our main theorem to the smooth Kähler metrics with slightly less geometric conditions than the $C^{1,1}$ geodesic in Chen's theorem 16.

Corollary 1.3. If the $C^{3}$ norm and Ricci curvature upper (or lower) bound of two Kähler potentials are uniformly bounded, then the geodesic connecting them has uniform $C^{1,1}$ bound.

Now we describe the structure of our paper. In Section 2, we recall the notations and the function spaces introduced by Donaldson. In particular, we define the boundary case. Then, we generalize the Riemannian structure to the space of Kähler cone metrics. The delicate part here is the growth rate near the divisor. In the Donaldson space, we derive that the geodesic equation is a HCMA with cone singularities by integration by part and explain the construction of the initial metric for the continuity method.

In Section 3. we obtain the a priori estimates of the approximate Monge-Ampère equation. It is divided into several steps. The $L^{\infty}$ estimate is derived from cone version of the maximum principle and the super-solution of the linear equation obtained in Section 4 In order to find out the proper geometric global conditions, the interior Laplacian estimate is obtained using the techniques of Yau's second order estimate [68] and the Chern-Lu formula (see [23 [46 67]). In order to prove the boundary Hessian estimate estimate near the divisor, we can not use the the distance function as the barrier function which is introduced in Guan-Spruck [36], since we need a uniform estimate independent of the distance to the divisor. So we choose the auxiliary function by solving the linear equation provided by Section 4. We hope this method could have potentially further application to MongeAmpère equation on manifold with boundary arises in other geometric problems. In order to obtain the interior gradient estimate near the divisor, we carefully choose an appropriate test function near the divisor. The appropriate growth rate is important to us.

In Section 4. we solve the linearized equation and prove the $C_{\beta}^{2, \alpha}$ regularity of the approximate geodesic equation. Both the interior and the boundary Schauder estimates are of the general form. Note that the right hand side of the approximation equation (4.1) contains $\log \Omega^{n+1}$. When applying the Evans-Krylov estimate, we need to bound the first derivative of $\log \Omega^{n+1}$. We will show that it is bounded when the cone angle is less than $\frac{2}{3}$. Thus with these estimates, the existence and the uniqueness of the $C_{\beta}^{1,1}$ cone geodesic are proved. Moreover, the approximate geodesic is in $C_{\beta}^{2, \alpha}$.

We also include an application of the interior Schauder estimate to the regularity of the Kähler-Einstein cone metrics (see Proposition 4.8). There is also a term $f$ on the right hand side of the corresponding equation (4.8). When apply the EvansKrylov estimate, it is necessary to bound the first derivative of $f$. We show that
the gradient of this term is bounded when the cone angle is less than $\frac{2}{3}$. When the cone angle is less than $\frac{1}{2}$, Brendle [10] derived Calabi's three order estimate to prove the existence of Ricci flat cone metrics.

Section 5 contains the maximum principle and the Hölder continuity of the linearized equation. In particular, the weak Hanack inequality is used to prove the $C_{\beta}^{2, \alpha}$ regularity of the approximation geodesic equation.

In Section 6, we apply our cone geodesic to prove the metric structure of $\mathcal{H}_{C}$. Once we establish the $C_{\beta}^{1,1}$ regularity of cone geodesic, the proof of the metric structure is immediate.
Acknowledgments: Both authors would like to thank Xiuxiong Chen who brought this problem to their attention. The second author also thanks Claudio Arezzo for helpful discussions and ICTP for their hospitality. He is also grateful to Gérard Besson for his warm encouragement during his visit in Institut Fourier.

## 2. The space of Kähler cone metrics

In this section, we first introduce some notations and knowledge of Donaldson's program [29], which we will stick to in the remainder of the paper. Let $U_{p}$ a local cone chart as in Definition 1.1 Let $W: U_{p} \backslash D \rightarrow U_{p} \backslash D$ be the change of coordinates given by

$$
\begin{equation*}
W\left(z^{1}, \cdots, z^{n}\right):=\left(w^{1}=\left|z^{1}\right|^{\beta_{1}-1} z^{1}, \cdots, w^{k}=\left|z^{k}\right|^{\beta_{k}-1} z^{k}, z^{k+1}, \cdots, z^{n}\right) \tag{2.1}
\end{equation*}
$$

Now, for any $1 \leq i \leq k$ let $0 \leq \theta_{i}<2 \pi, z^{i}:=\rho_{i} e^{\sqrt{-1} \theta_{i}}$ and $r_{i}:=\left|z^{i}\right|^{\beta_{i}}=\left|w^{i}\right|$; meanwhile, for any $k+1 \leq j \leq n$ let $z^{j}:=x^{j}+\sqrt{-1} y^{j}$. Then, let the polar coordinate transformation of $\left(w^{1}, \cdots, w^{k}, z^{k+1}, \cdots, z^{n}\right)$ be

$$
P:\left(w^{1}, \cdots, w^{k}, z^{k+1}, \cdots, z^{n}\right) \rightarrow\left(r_{1}, \theta_{1}, \cdots, r_{k}, \theta_{k}, x^{k+1}, y^{k+1}, \cdots, x^{n}, y^{n}\right)
$$

Thus we obtain that the expression of the push-forward cone flat metric is

$$
\begin{equation*}
\left((P \circ W)^{-1}\right)_{*} g=\sum_{1 \leq i \leq k}\left[d r_{i}^{2}+\beta_{i}^{2} r_{i}^{2} d \theta_{i}^{2}\right]+\sum_{k+1 \leq j \leq n}\left[\left(d x^{j}\right)^{2}+\left(d y^{j}\right)^{2}\right] . \tag{2.2}
\end{equation*}
$$

This flat metric is uniformly equivalent to the standard Euclidean metric. However, letting $\mu_{i}:=\beta_{i}^{-1}-1$, we have $w^{i}=r_{i} e^{\sqrt{-1} \theta_{i}}=\left|w^{i}\right|^{-\mu_{i}} z^{i}$; moreover, we define

$$
\begin{aligned}
\varepsilon_{i} & :=d r_{i}+\sqrt{-1} \beta_{i} r_{i} d \theta_{i}=\beta_{i}\left|w^{i}\right|^{1-\mu_{i}}\left(w^{i}\right)^{-1} d z^{i} \\
& =\beta_{i}\left[\left(1+\frac{\mu_{i}}{2}\right)\left|w^{i}\right|\left(w^{i}\right)^{-1} d w^{i}+\frac{\mu_{i}}{2}\left|w^{i}\right|^{-1} w^{i} d w^{\bar{i}}\right]
\end{aligned}
$$

and we notice that it is not a holomorphic 1 -form, since $\partial_{w^{\bar{i}}} \varepsilon_{i} \neq 0$. Consequently, $\varepsilon_{i}$ and $d z^{j}$ merely form a local orthonormal basis of the ( 1,0 )-forms.

Now we present the function spaces which are introduced by Donaldson in [29]. The Hölder space $C_{\beta}^{\alpha}$ consists in those functions $f$ which are Hölder continuous with respect to a Kähler cone metric. Also, $C_{\beta, 0}^{\alpha}$ denotes the subspace of those functions in $C_{\beta}^{\alpha}$ for which their limit is zero along $V_{i}$ for any $1 \leq i \leq m$. The Hölder continuous ( 1,0 )-forms, in local coordinates $U_{p}$, can be expressed as

$$
\xi=f_{i} \varepsilon_{i}+f_{j} d z^{j}
$$

where the Einstein notation is adopted, $f_{i} \in C_{0}^{\alpha}$ and $f_{j} \in C^{\alpha}$. Meanwhile, a Hölder ( 1,1 )-form $\eta$ in local coordinates $U_{p}$ is of the shape

$$
\eta=f_{i_{1} \bar{i}_{2}} \varepsilon_{i_{1}} \varepsilon_{\overline{i_{2}}}+f_{i \bar{j}} \varepsilon_{i} d z^{\bar{j}}+f_{\bar{i} j} \varepsilon_{\bar{i}} d z^{j}+f_{j_{1} \overline{j_{2}}} d z^{j_{1}} d z^{\overline{y_{2}}}
$$

here the coefficients satisfy $f_{i \bar{j}}, f_{\bar{i} j} \in C_{0}^{\alpha}$ and $f_{i_{1} \overline{i_{2}}}, f_{j_{1} \overline{j_{2}}} \in C^{\alpha}$. Note that according to this Definition, for any Kähler cone metric $\omega \in C_{\beta}^{\alpha}$, around the point $p \in D$, we have a local normal coordinate such that $g_{i j}(p)=\delta_{i j}$.
Definition 2.1. The Hölder space $C_{\beta}^{2, \alpha}$ is defined by

$$
C_{\beta}^{2, \alpha}=\left\{f \mid f, \partial f, \partial \bar{\partial} f \in C_{\beta}^{\alpha}\right\}
$$

Note that the $C_{\beta}^{2, \alpha}$ space, since it concerns only the mixed derivatives, is different from the usual $C^{2, \alpha}$ space. The definition of higher order space $C_{\beta}^{k, \alpha}$ depends on the background metrics. In this paper, we use the flat cone metric $\omega_{\text {cone (1.2) to define }}$ $C_{\beta}^{k, \alpha}$. It is not hard to see that, by the quasi-isometric mapping $W, \partial \bar{\partial} f \in C_{\beta}^{\alpha}$ is equivalent to $\frac{\partial^{2}}{\partial w^{i} \partial w^{j}} \in C^{\alpha}$ for any $1 \leq i, j \leq n$ under the coordinate $\left\{w^{i}\right\}$. So we say the third derivative of a function belongs to $C_{\beta}^{\alpha}$ if

$$
\frac{\partial^{3}}{\partial w^{k} \partial w^{i} \partial w^{\bar{j}}} f \in C^{\alpha}
$$

for any $1 \leq i, j, k \leq n$. In particular,
Definition 2.2. The Hölder space $C^{3}$ is defined by
$C_{\beta}^{3}=\left\{f \mid f \in C_{\beta}^{2, \alpha}\right.$ and the third derivative of $f$ w.r.t $\omega_{\text {cone }}$ is bounded $\}$.
Thus the higher order spaces are defined by induction on the index $k$. Now we postpone the discussion of the function space for a while, we will continue after we introduce the product manifold where the geodesic equation is defined.

We then approach some considerations on the Riemannian geometry of the space of Kähler cone metrics. Recall that $\mathcal{H}_{\beta}^{2, \alpha}$ is the space of $C_{\beta}^{2, \alpha} \omega_{0}$ psh-functions. It is a convex, open set in $C_{\beta}^{2, \alpha}$. The tangent space of $\mathcal{H}_{\beta}^{2, \alpha}$ at a point $\varphi$ is $C_{\beta}^{2, \alpha}$. We generalize the Donaldson [27, Mabuchi [47, Semmes [56] metric to $\mathcal{H}_{\beta}^{2, \alpha}$ by associating to $\varphi \in \mathcal{H}_{\beta}^{2, \alpha}$ and tangent vectors $\psi_{1}, \psi_{2} \in T_{\varphi} \mathcal{H}_{\beta}^{2, \alpha}$, the real number

$$
\begin{equation*}
\int_{M} \psi_{1} \cdot \psi_{2} \omega_{\varphi}^{n} \tag{2.3}
\end{equation*}
$$

The definition makes sense for Kähler cone metrics, since the volume of the Kähler cone metrics is finite. Furthermore, we choose an arbitrary differentiable path $\varphi \in C^{1}\left([0,1], \mathcal{H}_{\beta}^{2, \alpha}\right)$ and along it, differentiable vector field $\psi \in C^{1}\left([0,1], C_{\beta}^{2, \alpha}\right)$. We thus define the following derivation of the vector field on $M=X \backslash D$

$$
\begin{equation*}
D_{t} \psi:=\frac{\partial \psi}{\partial t}-\left(\partial \psi, \partial \frac{\partial \varphi}{\partial t}\right)_{g_{\varphi}} \tag{2.4}
\end{equation*}
$$

We claim that (2.4) is the Levi-Civita connection of (2.3). The fact that (2.4) is torsion free comes from a point-wise computation on $M$. Thus, the claim will be accomplished after verifying the metric compatibility, which is done in Proposition 2.2. We first prove an integration by parts formula.

Lemma 2.1. Assume that $\varphi_{1},\left|\partial \varphi_{1}\right|_{\Omega},\left|\partial \varphi_{2}\right|_{\Omega},\left|\Delta \varphi_{2}\right|_{L^{1}(\Omega)}$ are bounded. Then the following formula holds

$$
\int_{M} \varphi_{1} \Delta \varphi_{2} \omega^{n}=-\int_{M}\left(\partial \varphi_{1}, \partial \varphi_{2}\right)_{\Omega} \omega^{n}
$$

Proof. Choose a cut-off function $\chi_{\epsilon}$ which vanishes in a neighborhood of $D$. Then,

$$
\int_{M} \chi_{\epsilon} \varphi_{1} \Delta \varphi_{2} \omega^{n}=-\int_{M} \chi_{\epsilon}\left(\partial \varphi_{1}, \partial \varphi_{2}\right)_{\Omega} \omega^{n}-\int_{M} \varphi_{1}\left(\partial \chi_{\epsilon}, \partial \varphi_{2}\right)_{\Omega} \omega^{n}
$$

The convergence of the first two terms follows from the Lebesgue dominated convergence theorem. So, it suffices to find a $\chi_{\epsilon}$ such that $\int_{M}\left|\partial \chi_{\epsilon}\right| \Omega \omega^{n} \rightarrow 0$ as $\epsilon \rightarrow 0$. Choose $\chi_{\epsilon}:=\chi\left(\frac{1}{\epsilon^{2}} \prod_{i}\left|s_{i}\right|^{2}\right)$, where $s_{i}$ are the defining functions of $D_{i}$ and $\chi$ is a smooth non-decreasing function such that

$$
\begin{cases}\chi=0 & \text { in }[0,1] \\ 0 \leq \chi \leq 1 & \text { in }[1,2] \\ \chi=1 & \text { in }[2,+\infty)\end{cases}
$$

Now,

$$
\left|\partial \chi_{\epsilon}\right|_{\Omega} \leq \chi^{\prime} \cdot \frac{1}{\epsilon^{2}}\left|s_{i}\right|\left|s_{i}\right|^{1-\beta_{i}}=\frac{C}{\epsilon^{2}}\left|s_{i}\right|^{2-\beta_{i}}
$$

So, as $\epsilon \rightarrow 0$ we get in the cone chart

$$
\begin{aligned}
\int_{M}\left|\partial \chi_{\epsilon}\right| \Omega \omega^{n} & \leq \int_{|s|=r} \int_{0}^{2 \pi} \int_{\epsilon}^{2 \epsilon} \frac{2 \pi}{\epsilon^{2}}|r|^{2-\beta_{i}}|r|^{2\left(\beta_{i}-1\right)} r d r d \theta d z^{2} \wedge \cdots \wedge d z^{n} \\
& \leq \frac{2 \pi}{\epsilon^{2}} \int_{\epsilon}^{2 \epsilon}|r|^{1+\beta_{i}} d r \leq C \epsilon^{\beta_{i}} \rightarrow 0
\end{aligned}
$$

This completes the proof of the lemma.
As an application of the above formula, we have
Proposition 2.2. The connection (2.4) is compatible with the metric (2.3).
Proof. We compute

$$
\frac{1}{2} \frac{d}{d t} \int_{M} \psi^{2} \omega_{\varphi}^{n}=\frac{1}{2} \int_{M}\left(2 \psi \psi^{\prime}+\psi^{2} \Delta_{\varphi} \varphi^{\prime}\right) \omega_{\varphi}^{n}
$$

Since $\psi^{2},\left|\partial\left(\psi^{2}\right)\right|_{g_{\varphi}},\left|\partial \varphi^{\prime}\right|_{g_{\varphi}}, \Delta_{\varphi} \varphi^{\prime}$ are all bounded with respect to $g_{\varphi}$, we are allowed to apply Lemma 2.1 and we get

$$
\frac{1}{2} \frac{d}{d t} \int_{M} \psi^{2} \omega_{\varphi}^{n}=\frac{1}{2} \int_{M}\left[2 \psi \psi^{\prime}-2 \psi\left(\partial \psi, \partial \varphi^{\prime}\right)_{g_{\varphi}}\right] \omega_{\varphi}^{n}
$$

This completes the proof of the proposition.
Next, we derive the geodesic equation.
Proposition 2.3. The geodesic equation satisfies the following equation on $M$ point-wise

$$
\begin{equation*}
\varphi^{\prime \prime}-\left(\partial \varphi^{\prime}, \partial \varphi^{\prime}\right)_{g_{\varphi}}=0 \tag{2.5}
\end{equation*}
$$

Proof. Assume that $\left.\varphi(t)\right|_{0} ^{1}$ is a path from $\varphi_{0}$ to $\varphi_{1}$, and that $\varphi(s, t) \in C^{1}([0,1] \times$ $\left.[0,1], C_{\beta}^{2, \alpha}\right)$ is a 1-parameter variation of $\left.\varphi(t)\right|_{0} ^{1}$ with fixed endpoints. We minimize the length function

$$
L(\varphi(s, t))=\int_{0}^{1} \sqrt{\int_{M}\left(\frac{\partial \varphi(s, t)}{\partial t}\right)^{2} \omega_{\varphi}^{n}} d t
$$

We are going to compute the variation of $\frac{\partial}{\partial s} L(\varphi(s, t))$; denote $\varphi^{\prime}=\frac{\partial \varphi}{\partial t}$ and

$$
E=\int_{M} \varphi^{\prime 2} \omega_{\varphi}^{n}
$$

Then, using (2.4) and the compatibility property we get

$$
\begin{aligned}
\frac{\partial}{\partial s} L(\phi(s, t)) & =\int_{0}^{1} \frac{1}{E} \int_{M} D_{s} \varphi^{\prime} \cdot \varphi^{\prime} \omega_{\varphi}^{n} d t=\int_{0}^{1} \frac{1}{E} \int_{M} D_{t} \frac{\partial}{\partial s} \varphi \cdot \varphi^{\prime} \omega_{\varphi}^{n} d t \\
& =\int_{0}^{1} \frac{1}{E}\left[\frac{\partial}{\partial t} \int_{M} \frac{\partial}{\partial s} \varphi \cdot \varphi^{\prime} \omega_{\varphi}^{n}-\int_{M} D_{t} \frac{\partial}{\partial s} \varphi \cdot \varphi^{\prime} \omega_{\varphi}^{n}\right] d t \\
& =-\int_{0}^{1} \frac{1}{E} \int_{M} \frac{\partial}{\partial s} \varphi \cdot D_{t} \varphi^{\prime} \omega_{\varphi}^{n} d t
\end{aligned}
$$

The first term in the second line vanishes since the endpoints are fixed. So the geodesic condition reads

$$
0=\frac{\partial}{\partial s} L(\phi(s, t))=-\int_{0}^{1} \frac{1}{E} \int_{M} \frac{\partial}{\partial s} \varphi \cdot D_{t} \varphi^{\prime} \omega_{\varphi}^{n} d t
$$

which implies that the geodesic equation is

$$
D_{t} \varphi^{\prime} \equiv 0 \text { on } M
$$

Consider the cylinder $R=[0,1] \times S^{1}$ and introduce the coordinate $z^{n+1}=$ $x^{n+1}+\sqrt{-1} y^{n+1}$ on $R$. Define

$$
\varphi\left(z^{\prime}, z^{n+1}\right)=\varphi\left(z^{1}, \cdots, z^{n}, x^{n+1}\right)=\varphi\left(z^{1}, \cdots, z^{n}, t\right)
$$

on the product manifold $X \times R$ and let $\pi$ be the natural projection form $X \times R$ to $X$. We also denote

$$
\begin{aligned}
z & =\left(z^{\prime}, z^{n+1}\right)=\left(z^{1}, \cdots, z^{n}, z^{n+1}\right) \\
\Omega_{0} & =\left(\pi^{-1}\right)^{*} \omega_{0}+d z^{n+1} \wedge d \bar{z}^{n+1} \\
\Omega & =\left(\pi^{-1}\right)^{*} \omega+d z^{n+1} \wedge d \bar{z}^{n+1} \\
\Psi & =\varphi-\left|z^{n+1}\right|^{2}
\end{aligned}
$$

It is a matter of algebra to show that (2.5) could be reduced to a degenerate MongeAmpère equation. A path $\varphi(t)$ with endpoints $\varphi_{0}, \varphi_{1}$ satisfies the geodesic equation (2.5) on $X$ if and only if $\Psi$ satisfies the following Dirichlet problem involving a degenerate complex Monge-Ampère equation

$$
\begin{cases}\operatorname{det}\left(\Omega_{i \bar{j}}+\Psi_{i \bar{j}}\right)=0 & \text { in } M \times R  \tag{2.6}\\ \Psi(z)=\Psi_{0} & \text { on } X \times \partial R \\ \sum_{1 \leq i, j \leq n}\left(\Omega_{i \bar{j}}+\Psi_{i \bar{j}}\right) d z^{i} d z^{\bar{j}}>0 & \text { in } X \times\left\{z^{n-1}\right\}\end{cases}
$$

Here the following Dirichlet boundary conditions $\Psi_{0}$ are satisfied

$$
\begin{cases}\Psi_{0}\left(z^{\prime}, 0\right) \doteq \Psi\left(z^{\prime}, \sqrt{-1} y^{n+1}\right)=\varphi_{0}\left(z^{\prime}\right)-\left(y^{n+1}\right)^{2} & \text { on } X \times\{0\} \times S^{1}  \tag{2.7}\\ \Psi_{0}\left(z^{\prime}, 1\right) \doteq \Psi\left(z^{\prime}, 1+\sqrt{-1} y^{n+1}\right)=\varphi_{1}\left(z^{\prime}\right)-1-\left(y^{n+1}\right)^{2} & \text { on } X \times\{1\} \times S^{1}\end{cases}
$$

Now we are given a $n+1$-dimensional Kähler manifold $\mathfrak{X}=X \times R$ with boundary; the given data of the Dirichlet problem are put on two disjoint copies of $X$. We also have a divisor $\mathfrak{D}=D \times R$, with $D$ as in Definition (1.1), which intersects transversely the boundary Let $f_{i}$ be the local defining function of each irreducible
analytic component $V_{i}$ of $\mathfrak{D}$. Then the transition functions $\frac{f_{i}}{f_{j}}$ give a line bundle [D] in $\mathfrak{X}$. Let $s$ be a global meromorphic section of [D]. Let $h_{\Lambda}$ be the Hermitian metric on $[\mathfrak{D}]$. There is a small positive $\delta$ such that, on $\mathfrak{X}$,

$$
\begin{equation*}
\Omega=\Omega_{0}+\delta \sum_{i=1}^{m} \frac{\sqrt{-1}}{2} \partial \bar{\partial}\left|s_{i}\right|_{h_{\Lambda}}^{2 \beta_{i}} \tag{2.8}
\end{equation*}
$$

is a Kähler cone metric (cf. (1.3)). Moreover, it is also independent of the choices $\Omega_{0}, h_{\Lambda}, \delta$ up to quasi-isometry.

We could define the Hölder space $C_{\beta}^{3}$ in the interior of $(\mathfrak{X}, \mathfrak{D})$ as that one defined on $(X, D)$. On the boundary, near a point $p$ we choose a local holomorphic coordinate $\left\{U_{p}^{+} ; z^{i}=x^{i}+i y^{i}\right\}, 1 \leq i \leq 2 n+2$ centered at $p$. From the discussion above, we see that the boundary of $\mathfrak{X}$ is $x^{n+1}=0$. When $U_{p}^{+}$does not intersect the divisor $\mathfrak{D}$, the Hölder space is defined in the usual way. So it is sufficient to defined a new Hölder space in the coordinates which contain the points of the divisor. We first note that the solution of geodesic equation is independent of the variable $y^{n+1}$, so the partial derivative on the variable $x^{n+1}$ is the same to the one on the variable $z^{n+1}$. Next, the quasi-isometric mapping $W$ is still well defined in $U_{p}^{+}$as follows,

$$
W\left(z^{1}, \cdots, z^{n+1}\right):=\left(w^{1}=\left|z^{1}\right|^{\beta_{1}-1} z^{1}, \cdots, w^{k}=\left|z^{k}\right|^{\beta_{k}-1} z^{k}, z^{k+1}, \cdots, z^{n+1}\right)
$$

So we could define the Hölder space $C_{\beta}^{\alpha}\left(U_{p}^{+}\right)$to be the set of functions which are Hölder continuous under $\left\{z^{i}\right\}_{i=1}^{n+1}$ with respect to a Kähler cone metric. Also, $C_{\beta, 0}^{\alpha}\left(U_{p}^{+}\right)$denotes the subspace of those functions in $C_{\beta}^{\alpha}\left(U_{p}^{+}\right)$for which their limit is zero along $V_{i}$ for any $1 \leq i \leq m$. The Hölder continuous ( 1,0 )-forms, in local coordinates $U_{p}^{+}$, can be expressed as

$$
\xi=\sum_{i} f_{i} \varepsilon_{i}+\sum_{j} f_{j} d z^{j}
$$

where $f_{i} \in C_{0}^{\alpha}\left(U_{p}^{+}\right)$and $f_{j} \in C^{\alpha}\left(U_{p}^{+}\right)$. Meanwhile, a Hölder $(1,1)$-form $\eta$ in local coordinates $U_{p}^{+}$is of the shape

$$
\eta=f_{i_{1} \overline{i_{2}}} \varepsilon_{i_{1}} \varepsilon_{\overline{i_{2}}}+f_{i \bar{j}} \varepsilon_{i} d z^{\bar{j}}+f_{\bar{i} j} \varepsilon_{\bar{i}} d z^{j}+f_{j_{1} \overline{\bar{j}_{2}}} d z^{j_{1}} d z^{\overline{j_{2}}}
$$

here the coefficients satisfy $f_{i \bar{j}}, f_{\bar{i} j} \in C_{0}^{\alpha}\left(U_{p}^{+}\right)$and $f_{i_{1} \overline{i_{2}}}, f_{j_{1} \overline{j_{2}}} \in C^{\alpha}\left(U_{p}^{+}\right)$. The Hölder space $C_{\beta}^{2, \alpha}\left(U_{p}^{+}\right)$is parallelly defined by

$$
C_{\beta}^{2, \alpha}\left(U_{p}^{+}\right)=\left\{f \mid f, \partial f, \partial \bar{\partial} f \in C_{\beta}^{\alpha}\left(U_{p}^{+}\right)\right\}
$$

Then we use the flat cone metric $\omega_{\text {cone }}$ (1.2) to define the higher order space $C_{\beta}^{k, \alpha}\left(U_{p}^{+}\right)$. The boundary $C^{3}$ space is defined in the same manner.
Definition 2.3. The Hölder space $C^{3}\left(U_{p}^{+}\right)$is defined by
$C_{\beta}^{3}\left(U_{p}^{+}\right)=\left\{f \mid f \in C_{\beta}^{2, \alpha}\left(U_{p}^{+}\right)\right.$and the 3nd derivative of $f$ w.r.t $\omega_{\text {cone }}$ is bounded $\}$.
Thus the higher order spaces are also defined by induction on the index $k$ in the same way.

In order to apply the maximum principle, we require that the maximum point does not live on the divisor. The following lemma by Jeffres 41 is used to overcome this trouble. With the discussion above, we prove this technical auxiliary lemma in our product manifold $\mathfrak{X}$ with boundary.

Lemma 2.4. There is a positive constant $\kappa$ such that $S=\|s\|^{2 \kappa}$ satisfies the following properties
(1) $\frac{\sqrt{-1}}{2} \partial \bar{\partial} S \geq \kappa \frac{\sqrt{-1}}{2} \partial \bar{\partial} \log \|s\|^{2} \geq-C \Omega$,
(2) for any $\alpha>0, S$ grows faster than the collapsing of $\Phi \in C_{\beta}^{\alpha}$ near $\mathfrak{D}$ provided $2 \kappa \leq a \beta$.

Proof. Since

$$
\begin{aligned}
\frac{\sqrt{-1}}{2} \partial \bar{\partial} S & =\frac{\sqrt{-1}}{2} S\left(\kappa \partial \bar{\partial} \log \|s\|^{2}+\partial \log S \wedge \bar{\partial} \log S\right) \\
& \geq \kappa \frac{\sqrt{-1}}{2} S \partial \bar{\partial} \log \|s\|^{2}
\end{aligned}
$$

and since $-\frac{\sqrt{-1}}{2} \partial \bar{\partial} \log \|s\|^{2}$ is the curvature form of the line bundle under the Hermitian metric $h$, there is a constant $C$ such that $\frac{\sqrt{-1}}{2} \partial \bar{\partial} \log S \geq-C \Omega$. So we have

$$
\frac{\sqrt{-1}}{2} S \partial \bar{\partial} \log S \geq-C \kappa S \Omega \geq-C \kappa \Omega
$$

In order to derive the second conclusion, we compute the first derivative of $S$ along the singular direction. Choosing the basis $e$, we have $\|s\|^{2 \kappa}=|z|^{2 \kappa}\|e\|^{2 \kappa}$, then the main term of $\left|\nabla^{a} S\right|_{\Omega}^{2}$ is $\left|z^{1}\right|^{4 \kappa-2 a+2 a(1-\beta)}$. So it is sufficient to choose $\kappa$ such that this main term becomes unbounded as it approaches $\mathfrak{D}$. Meanwhile, $\Psi \in C_{\beta}^{a}$ implies that $\left|\nabla^{a} \Psi\right|_{\Omega}$ is bounded, so the second conclusion follows.

In order to apply the continuity method we first construct the starting metric of the solution path such that it satisfies the boundary conditions. Since $\Psi_{0}$ may not be convex along the direction $\frac{\partial}{\partial z^{n+1}}$, we have to extend $\Psi_{0}$ to whole $\mathfrak{X}$ as follows. Let $\tilde{\Psi}_{0}$ be the line segment between the boundary Kähler cone potentials $\varphi_{0}$ and $\varphi_{1}$; namely, (cf. (2.7))

$$
\tilde{\Psi}_{0}=t \Psi_{0}\left(z^{\prime}, 1\right)+(1-t) \Psi_{0}\left(z^{\prime}, 0\right)+t+\left(y^{n+1}\right)^{2}=t \varphi_{1}+(1-t) \varphi_{0}
$$

Then we choose a function $\Phi$ which depends only on $z^{n+1}$ such that

$$
\begin{cases}\Phi\left(z^{n+1}\right)=0 & \text { on } \partial \mathfrak{X} \\ \Phi_{z^{n+1} \bar{z}^{n+1}}>0 & \text { in } \mathfrak{X}\end{cases}
$$

We denote the new potential by

$$
\Psi_{1}:=\tilde{\Psi}_{0}+m \Phi
$$

Next we verify that $\Psi_{1}$ is a Kähler cone potential on $\mathfrak{X}$.
Proposition 2.5. Suppose that $\varphi_{0}, \varphi_{1} \in \mathcal{H}_{\beta}$. Then there exists a large number $m$ such that

$$
\begin{equation*}
\Omega_{1}:=\Omega+\frac{\sqrt{-1}}{2} \sum_{1 \leq i, j \leq n+1} \partial_{i} \partial_{\bar{j}} \Psi_{1} \tag{2.9}
\end{equation*}
$$

is a Kähler cone metric on $(\mathfrak{X}, \mathfrak{D})$.

Proof. The local expression of $\Omega_{\Psi_{1}}$ is

$$
\begin{aligned}
& \Omega+\frac{\sqrt{-1}}{2} \sum_{1 \leq i, j \leq n+1} \partial_{i} \partial_{\bar{j}}\left(\tilde{\Psi}_{0}+m \Phi\right) \\
& =t \omega_{\varphi_{1}}+(1-t) \omega_{\varphi_{0}}+\frac{\sqrt{-1}}{2}\left(1+m \partial_{n+1} \partial_{\overline{n+1}} \Phi\right) d z^{n+1} \wedge d \bar{z}^{n+1} \\
& +\frac{1}{\sqrt{2}}\left(\partial_{i} \varphi_{1}-\partial_{i} \varphi_{0}\right) d z^{i} d z^{\overline{n+1}}+\frac{1}{\sqrt{2}}\left(\partial_{\bar{i}} \varphi_{1}-\partial_{\bar{i}} \varphi_{0}\right) d z^{\bar{i}} d z^{n+1}
\end{aligned}
$$

We call $\omega_{t}:=t \omega_{\varphi_{1}}+(1-t) \omega_{\varphi_{0}}$ the line segment and $\psi:=\varphi_{1}-\varphi_{0}$ the difference of the boundary Kähler cone potentials.

In order to show that $\Omega_{\Psi_{1}}$ is a Kähler cone metric on $\mathfrak{X}$, it suffices to verify two conditions; that it is positive on the regular part $M$ and that $\Omega_{\Psi_{1}}$ is locally quasi-isometric to

$$
\Omega_{\text {cone }}=\frac{\sqrt{-1}}{2} \sum_{i=1}^{k}\left(\beta_{i}^{2}\left|z^{i}\right|^{2\left(\beta_{i}-1\right)} d z^{i} \wedge d z^{\bar{i}}\right)+\sum_{i=k+1}^{n+1}\left(d z^{i} \wedge d z^{\bar{i}}\right) .
$$

Since the determinant of $\Omega_{\Psi_{1}}$ is $\operatorname{det}\left(g_{t}\right)\left[1+m \Phi_{n+1, \overline{n+1}}-g_{t}^{i \bar{j}} \psi_{i} \psi_{\bar{j}}\right]$, the former condition is true once we choose $m$ large enough. The latter condition is verified as $\varphi_{0}, \varphi_{1} \in \mathcal{H}_{\beta}$.

## 3. A PRIORI ESTIMATES

In this section, we derive uniform a priori estimates for the degenerate equation. With the same background as (2.6), $\mathfrak{M}=M \times R$ and $\Psi_{1}$ a Kähler potential in $\mathfrak{M}$, that is $\Omega_{1}:=\Omega+\frac{\sqrt{-1}}{2} \partial \bar{\partial} \Psi_{1}>0$, we consider the family of Dirichlet problems for $0 \leq \tau \leq 1$,

$$
\begin{cases}\operatorname{det}\left(\Omega_{i \bar{j}}+\Psi_{i \bar{j}}\right)=\tau e^{\Psi-\Psi_{1}} \operatorname{det}\left(\Omega_{i \bar{j}}+\Psi_{1 i \bar{j}}\right) & \text { in } \mathfrak{M},  \tag{3.1}\\ \Psi(z)=\Psi_{0} & \text { on } \partial \mathfrak{X}\end{cases}
$$

in the space $C_{\beta}^{2, \alpha}$. We will specify the conditions on $\Psi_{0}$ in each estimate.
Since the curvature conditions of the background metrics are required when we derive the a priori estimates, we explain an observation on how to choose appropriate background metrics. If we take $\Omega_{1}$ as the background metric, we obtain an equivalent equation

$$
\begin{cases}\operatorname{det}\left(\Omega_{1 i \bar{j}}+\tilde{\Psi}_{i \bar{j}}\right)=\tau f e^{\tilde{\Psi}} \operatorname{det}\left(\Omega_{i \bar{j}}\right)=\tau e^{\tilde{\Psi}} \operatorname{det}\left(\Omega_{1 i \bar{j}}\right) & \text { in } \mathfrak{M}  \tag{3.2}\\ \tilde{\Psi}(z)=0 & \text { on } \partial \mathfrak{X}\end{cases}
$$

where $\tilde{\Psi}:=\Psi-\Psi_{1}$ and $f:=\frac{\operatorname{det}\left(\Omega_{i \bar{j}}+\Psi_{1 i \bar{j}}\right)}{\operatorname{det}\left(\Omega_{i \bar{j}}\right)}$. In general, given a Kähler cone potential $\Phi$ we could take $\Omega^{A}:=\Omega+\frac{\sqrt{-1}}{2} \partial \bar{\partial} \Phi, \Psi^{A}:=\Psi-\Phi, \Psi_{1}^{A}:=\Psi_{1}-\Phi, \Psi_{0}^{A}:=\Psi_{0}-\Phi$. The new family of Dirichlet problems becomes

$$
\begin{cases}\operatorname{det}\left(\Omega_{i \bar{j}}^{A}+\Psi_{i \bar{j}}^{A}\right)=\tau e^{\Psi^{A}-\Psi_{1}^{A}} \operatorname{det}\left(\Omega_{i \bar{j}}^{A}+\Psi_{1 i \bar{j}}^{A}\right) & \text { in } \mathfrak{M}  \tag{3.3}\\ \Psi(z)=\Psi_{0}^{A} & \text { on } \partial \mathfrak{X}\end{cases}
$$

The above observation will be particularly useful when we will derive the a priori estimates later. Note that the right hand side of the equation is positive as long as $\tau$ is positive. When $\tau=1, \Psi_{1}$ solves the equation. When $\tau$ is zero, (3.1) as well as (3.2) provide a solution of the degenerate equation (2.6).
3.1. $L^{\infty}$ estimate. We will see in the following that the $L^{\infty}$ estimate follows from the cone maximum principle (Lemma 5.1) and the global bounded weak solution (Proposition 5.9) provided in Section 5. Applying the logarithm on both sides of (3.2) we have

$$
\begin{equation*}
\log \frac{\operatorname{det}\left(\Omega_{1 i \bar{j}}+\tilde{\Psi}_{i \bar{j}}\right)}{\operatorname{det}\left(\Omega_{1 i \bar{j}}\right)}=\log \tau+\tilde{\Psi} . \tag{3.4}
\end{equation*}
$$

Proposition 3.1. (Lower bound of $\Psi$ ) For any point $x \in \mathfrak{X}$, the following estimate holds

$$
\Psi(x) \geq \Psi_{1}(x)
$$

Proof. According to the second conclusion of Lemma 2.4, $U=\tilde{\Psi}-\epsilon S$ achieves its minimum point $p$ on $\mathfrak{M}$. There are two cases, one when $p$ is on $M \times \partial R$ and the other one when $p$ is in the interior of $\mathfrak{M}$. In the first case, since $p$ is on the regular part of the boundary, then the minimal value is just the boundary value. Thus the inequality holds automatically. Now we explain the second case. The equation (3.4) is rewritten as

$$
\begin{equation*}
\log \frac{\left(\Omega_{1}+\frac{\sqrt{-1}}{2} \partial \bar{\partial}(U+\epsilon S)\right)^{n+1}}{\Omega_{1}^{n+1}}=\log \tau+\tilde{\Psi} \tag{3.5}
\end{equation*}
$$

At the point $p$ the Hessian of $U$ is non-negative $U_{i \bar{i}} \geq 0$; so, after diagonalizing $\Omega_{1}$ and $\Omega_{1}+\frac{\sqrt{-1}}{2} \partial \bar{\partial}(U+\epsilon S)$ simultaneously, (3.5) implies

$$
\tau e^{\tilde{\Psi}(p)} \Pi_{i=1}^{n+1} \Omega_{1 i \bar{i}} \geq \Pi_{i=1}^{n+1}\left(\Omega_{1 i \bar{i}}+\epsilon S_{i \bar{i}}\right) \geq(1-\epsilon C)^{n+1} \Pi_{i=1}^{n+1} \Omega_{1 i \bar{i}}
$$

where, at the second inequality, we use the first conclusion of Lemma 2.4. Then we have

$$
\tilde{\Psi}(p) \geq \log (1-\epsilon C)^{n+1}
$$

Then for any $x \in \mathfrak{X}$, (1) in Lemma 2.4 implies

$$
\begin{aligned}
& \tilde{\Psi}(x)=U(x)+\epsilon S(x) \geq U(p) \\
& =\tilde{\Psi}(p)-\epsilon S(p) \geq \log (1-\epsilon C)^{n+1}-\epsilon
\end{aligned}
$$

which gives the lower bound of $\tilde{\Psi}$ as $\epsilon$ goes to zero.
Proposition 3.2. (Upper bound of $\Psi$ ) For any point $x \in \mathfrak{X}$, the following estimate holds

$$
\Psi(x) \leq h(x)
$$

Proof. From (3.1) the solution is non-negative $\Omega+\frac{\sqrt{-1}}{2} \partial \bar{\partial} \Psi \geq 0$, after taking trace it implies

$$
-\triangle \Psi \leq n+1
$$

In order to obtain the lower bound, we then consider the linear equation

$$
\begin{cases}\triangle h=-n-1 & \text { in } \mathfrak{M}, \\ h=\Psi_{0} & \text { on } \partial \mathfrak{X} .\end{cases}
$$

It is solvable by Proposition 5.6 and 5.9. Then the lemma follows form the weak maximum principle of cone metrics (Lemma 5.5).

Remark 3.1. We could consider the family of equations with parameter $a \in \mathbb{R}$ as

$$
\begin{cases}\operatorname{det}\left(\Omega_{1 i \bar{j}}+\tilde{\Psi}_{i \bar{j}}\right)=\tau e^{a \tilde{\Psi}} \operatorname{det}\left(\Omega_{1 i \bar{j}}\right) & \text { in } \mathfrak{M}  \tag{3.6}\\ \tilde{\Psi}(z)=0 & \text { on } \partial \mathfrak{X}\end{cases}
$$

The approximate equation (3.2) is the former with $a=1$. That is slightly different from the family considered by Chen [16] with $a=0$. We would like to indicate that using the estimate in Section 5 the lower bound of the solution of Chen's approximate equation can be proved by applying the maximum principle with respect to the Kähler cone metric Lemma 5.5 to

$$
\begin{cases}\operatorname{det}\left(\Omega_{1 i \bar{j}}+\tilde{\Psi}_{i \bar{j}}\right) \leq \operatorname{det}\left(\Omega_{1}\right) & \text { in } \mathfrak{M} \\ \tilde{\Psi}=0 & \text { on } \partial \mathfrak{X}\end{cases}
$$

The upper and the lower bound of $\Psi$ imply the boundary gradient estimate

$$
\begin{equation*}
\sup _{M \times \partial R}|\nabla \Psi|_{\Omega} \leq \sup _{\mathfrak{X}}\left|\nabla \Psi_{1}\right|_{\Omega}+\sup _{\mathfrak{X}}|\nabla h|_{\Omega} . \tag{3.7}
\end{equation*}
$$

3.2. Interior Laplacian estimate. The content of the present subsection is the statement and proof of three different interior Laplacian estimates (Proposition 3.3).

We remark that in Lemma 3.4 below, we could choose different background metrics. As a result, constants would have different dependence on geometric quantities.
Proposition 3.3. There are three constants $C_{i}$, for $i=1,2,3$ such that

$$
\begin{equation*}
\sup _{\mathfrak{X}}(n+1+\triangle \Psi) \leq C_{i} \sup _{\partial \mathfrak{X}}(n+1+\triangle \Psi) . \tag{3.8}
\end{equation*}
$$

The constants respectively depend on

$$
\begin{aligned}
& C_{1}=C_{1}\left(\inf \operatorname{Riem}(\Omega), \text { sup } \operatorname{Ric}\left(\Omega_{1}\right), \text { sup } \operatorname{tr}_{\Omega} \Omega_{1}, \operatorname{Osc} \Psi, \operatorname{Osc} \Psi_{1}\right) \\
& C_{2}=C_{2}\left(\left|\operatorname{Riem}\left(\Omega_{1}\right)\right|_{L^{\infty}}, \sup \operatorname{tr}_{\Omega} \Omega_{1}, \sup \operatorname{tr}_{\Omega_{1}} \Omega, \operatorname{Osc} \Psi\right) \\
& C_{3}=C_{3}\left(\sup \operatorname{Riem}(\Omega), \inf \operatorname{Ric}\left(\Omega_{1}\right), \text { sup } \operatorname{tr}_{\Omega} \Omega_{1}, \operatorname{Osc} \Psi, \operatorname{Osc} \Psi_{1}\right)
\end{aligned}
$$

Remark 3.2. The estimates work for any given Kähler cone metric $\Omega$.
We first consider the equation (3.1). We denote

$$
\begin{equation*}
F:=\log \tau+\log f+\Psi-\Psi_{1}=\log \frac{\operatorname{det}\left(\Omega_{i \bar{j}}+\Psi_{i \bar{j}}\right)}{\operatorname{det}\left(\Omega_{i \bar{j}}\right)} \tag{3.9}
\end{equation*}
$$

We calculate $\Delta^{\prime}(n+1+\Delta \Psi)$ of our equation and explain later how to change the background metric.

Lemma 3.4. The following formula holds

$$
\begin{aligned}
\Delta^{\prime}(n+1+\Delta \Psi) & =g^{i \bar{j}} g^{\prime k \bar{l}} g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}}-\operatorname{tr}_{\Omega} \operatorname{Ric}\left(\Omega_{1}\right) \\
& +\Delta \Psi-\Delta \Psi_{1}+g^{\prime k \bar{l}} R^{i \bar{j}}{ }_{k \bar{l}} g^{\prime}{ }_{i \bar{j}} .
\end{aligned}
$$

Proof. Since $g^{\prime}{ }_{i \bar{j}}=g_{i \bar{j}}+\Psi_{i \bar{j}}$, when we take $-\partial_{k} \partial_{\bar{l}}$ on both sides we get

$$
\begin{equation*}
-\partial_{k} \partial_{\bar{l}} g_{i \bar{j}}^{\prime}=R_{i \bar{j} k \bar{l}}-\Psi_{i \bar{j} k \bar{l}} \tag{3.10}
\end{equation*}
$$

Since the Riemannian curvature is defined by

$$
R_{i \bar{j} k \bar{l}}^{\prime}=-\partial_{k} \partial_{\bar{l}} g^{\prime}{ }_{i \bar{j}}+g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}},
$$

inserting the latter in (3.10) and taking the trace with respect to $g^{\prime k \bar{l}}$ and $g^{i \bar{j}}$ we have

$$
\begin{equation*}
g^{i \bar{j}} R_{i \bar{j}}^{\prime}=g^{i \bar{j}} g^{\prime k \bar{l}} g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}}+g^{\prime k \bar{l}} R_{k \bar{l}}-g^{i \bar{j}} g^{\prime k} \bar{l}_{i \bar{j} k \bar{l}} . \tag{3.11}
\end{equation*}
$$

Since

$$
\Delta^{\prime}(n+1+\Delta \Psi)=g^{\prime k \bar{l}} g^{i \bar{l}} \Psi_{i \bar{j} k \bar{l}}+g^{\prime k \bar{l}} R_{k \bar{l}}^{i \bar{j}} \Psi_{i \bar{j}},
$$

inserting the latter in (3.11) we get

$$
\Delta^{\prime}(n+1+\Delta \Psi)=g^{i \bar{j}} g^{\prime k \bar{l}} g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}}-g^{i \bar{j}} R_{i \bar{j}}^{\prime}+g^{\prime k \bar{l}} R_{k \bar{l}}+g^{\prime k \bar{l}} R_{k \bar{l}}^{i \bar{j}} \Psi_{i \bar{j}} .
$$

Since (3.9) implies $R_{i \bar{j}}^{\prime}=R_{i \bar{j}}-F_{i \bar{j}}$ we therefore have

$$
\Delta^{\prime}(n+1+\Delta \Psi)=g^{i \bar{j}} g^{\prime k \bar{l}} g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}}-S(\Omega)+\Delta F+g^{\prime k \bar{l}} R_{k \bar{l}}^{i \bar{j}} g^{\prime}{ }_{i \bar{j}} .
$$

Then the lemma follows from the formula

$$
\Delta F=\Delta\left(\log f+\Psi-\Psi_{1}\right)=-\operatorname{tr}_{\Omega} \operatorname{Ric}\left(\Omega_{1}\right)+\mathrm{S}(\Omega)+\Delta \Psi-\Delta \Psi_{1}
$$

This completes the proof of the lemma.
The following formula follows from the Schwarz inequality. See Yau 68, and Siu [58] page 73 .

$$
\begin{equation*}
g^{i \bar{j}} g^{\prime k \bar{l}} g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}} \geq \frac{|\partial(n+1+\Delta \Psi)|^{2}}{n+1+\Delta \Psi} . \tag{3.12}
\end{equation*}
$$

Lemma 3.5. There is a constant $C$ depending on $\sup \operatorname{Ric}\left(\Omega_{1}\right)$, $\sup \operatorname{tr}_{\Omega} \Omega_{1}, \inf _{\mathrm{i} \neq \mathrm{k}} \mathrm{R}_{\mathrm{iik} \overline{\mathrm{k}}}$ such that

$$
\Delta^{\prime}(\log (n+1+\Delta \Psi)) \geq-C\left(1+\operatorname{tr}_{\Omega^{\prime}} \Omega\right)
$$

Proof. We compute

$$
\Delta^{\prime}(\log (n+1+\Delta \Psi))=\frac{\Delta^{\prime}(n+1+\Delta \Psi)}{n+1+\Delta \Psi}-\frac{|\partial(n+1+\Delta \Psi)|^{2}}{n+1+\Delta \Psi}
$$

Thus, by combining Lemma 3.4 with (3.12), we have

$$
\begin{aligned}
\Delta^{\prime}(\log (n+1+\Delta \Psi)) & \geq \frac{-\operatorname{tr}_{\Omega} \operatorname{Ric}\left(\Omega_{1}\right)+\Delta \Psi-\Delta \Psi_{1}+\mathrm{g}^{\prime k \overline{\mathrm{k}}} \mathrm{R}^{\mathrm{i} \overline{\mathrm{j}}}{ }_{\mathrm{k} \mathrm{l}} \mathrm{~g}^{\prime}{ }_{\mathrm{ij}}}{n+1+\Delta \Psi} \\
& \geq-C\left(1+\frac{1}{n+1+\Delta \Psi}+\operatorname{tr}_{\Omega^{\prime}} \Omega\right)
\end{aligned}
$$

Thus the lemma follows from $\frac{1}{n+1+\Delta \Psi} \leq \frac{1}{1+\Psi_{i \bar{u}}} \leq \operatorname{tr}_{\Omega^{\prime}} \Omega$.
Proof. (proof of constant $C_{1}$ ) Denote

$$
Z:=\log (n+1+\Delta \Psi)-K \Psi+\epsilon S
$$

with $K$ to be chosen. According to Lemma 2.4 with appropriate $\kappa$, the maximum point $p$ of $Z$ stays in the interior of $\mathfrak{M}$. Since $\Delta^{\prime} \Psi=n+1-\operatorname{tr}_{\Omega^{\prime}} \Omega$, and $\Delta^{\prime} S \geq$ $-C \operatorname{tr}_{\Omega^{\prime}} \Omega$ (Lemma 2.4), then at $p$ there holds

$$
0 \geq \Delta^{\prime} Z \geq-C\left(1+\operatorname{tr}_{\Omega^{\prime}} \Omega\right)-\mathrm{K}\left(\mathrm{n}+1-\operatorname{tr}_{\Omega^{\prime}} \Omega\right)-\epsilon \operatorname{Ctr}_{\Omega^{\prime}} \Omega
$$

Now we choose $K$ such that $-C+K-\epsilon C>0$ to obtain the upper bound of $\operatorname{tr}_{\Omega^{\prime}} \Omega(\mathrm{p})$. From the arithmetic-geometric-mean inequality we have

$$
\begin{aligned}
(n+1+\Delta \Psi)^{\frac{1}{n}} \cdot e^{-\frac{F}{n}} & =\left(\sum_{i=1}^{n+1} \frac{1}{\prod_{k=1, k \neq i}^{n+1}\left(1+\Psi_{k \bar{k}}\right)}\right)^{\frac{1}{n}} \\
& \leq \sum_{k=1}^{n+1} \frac{1}{1+\Psi_{k \bar{k}}}=\operatorname{tr}_{\Omega^{\prime}} \Omega
\end{aligned}
$$

Since $F=\log \tau+\log f+\Psi-\Psi_{1}$, so, $n+1+\Delta \Psi$ is bounded from above at $p$ depending on $\sup \operatorname{Ric}\left(\Omega_{1}\right)$, sup $\operatorname{tr}_{\Omega} \Omega_{1}, \inf _{i \neq k} R_{i \bar{i} k \bar{k}}, \sup \Psi$, and $\inf \Psi_{1}$. For any $x \in \mathfrak{X}$, there holds $Z(x) \leq \sup _{\partial \mathfrak{X}} Z+Z(p)$. Hence,

$$
\begin{align*}
n+1+\Delta \Psi & =e^{Z+K \Psi-\epsilon S} \\
& \leq e^{\sup _{\partial \mathscr{X}} Z+Z(p)+K \sup \Psi} \\
& \leq \sup _{\partial \mathscr{X}}(n+1+\Delta \Psi) e^{-K \inf _{\mathscr{X}} \Psi_{0}+1+Z(p)+K \sup \Psi} \tag{3.13}
\end{align*}
$$

This formula gives precisely the claimed inequality (3.8) for the first constant $C_{1}$.

Proof. (proof of constant $C_{2}$ ) Now the same argument as in Lemma 3.4, applied to equation (3.2), gives the following formula

$$
\Delta^{\prime}\left(n+1+\Delta_{1} \tilde{\Psi}\right)=g_{1}{ }^{i \bar{j}} g^{\prime k \bar{l}} g^{\prime p \bar{q}} \partial_{\bar{l}} g^{\prime}{ }_{p \bar{j}} \partial_{k} g^{\prime}{ }_{i \bar{q}}-S\left(\Omega_{1}\right)+\Delta_{1} \tilde{\Psi}+g^{\prime k \bar{l}} R_{1}{ }^{i \bar{j}}{ }_{k \bar{l}} g^{\prime}{ }_{i \bar{j}}
$$

Then, still following an argument similar to that used in the first part of this subsection, we get a constant $C$ which depends on $\sup S\left(\Omega_{1}\right), \inf _{i \neq k} R_{i \bar{i} k \bar{k}}\left(\Omega_{1}\right)$, Osc $\Psi$, such that

$$
n+1+\Delta_{1} \tilde{\Psi} \leq C \sup _{\partial \mathfrak{X}}\left(n+1+\Delta_{1} \tilde{\Psi}\right)
$$

Since $\Omega$ and $\Omega_{1}$ are $L^{\infty}$ equivalent, we have

$$
\begin{equation*}
n+1+\Delta \Psi \leq C\left(\sup \operatorname{tr}_{\Omega_{1}} \Omega\right)\left(\sup \operatorname{tr}_{\Omega} \Omega_{1}\right) \cdot \sup _{\partial \mathscr{X}}(\mathrm{n}+1+\Delta \Psi) \tag{3.14}
\end{equation*}
$$

This formula gives precisely the second constant $C_{2}$ for claimed inequality (3.8). Here the conditions $\inf \operatorname{Riem}\left(\Omega_{1}\right)$ and $\sup S\left(\Omega_{1}\right)$ are bounded are equivalent to the $L^{\infty}$ bound of the Riemannian curvature of $\Omega_{1}$.

Proof. (proof of constant $C_{3}$ ) Now we use the Chern-Lu formula (see [23, 46] 67]) to derive the second order estimate. We get the formula of

$$
\operatorname{tr}_{\Omega^{\prime}} \Omega=\mathrm{n}+1-\Delta^{\prime} \Psi
$$

This following identity is interpreted as the energy identity of the harmonic map $i d$ between $\left(M, g^{\prime}\right)$ to $(M, g)$.

$$
\begin{equation*}
\Delta^{\prime}\left(\operatorname{tr}_{\Omega^{\prime}} \Omega\right)=\mathrm{R}^{i \mathrm{i} \overline{\mathrm{j}}} \mathrm{~g}_{\mathrm{ij}}-\mathrm{g}^{\prime \mathrm{i} \overline{\mathrm{j}}} \mathrm{~g}^{\prime k \overline{\mathrm{k}}} \mathrm{R}_{\mathrm{ij} \mathrm{j} \overline{\mathrm{l}}}-\mathrm{g}^{\mathrm{i} \overline{\mathrm{j}}} \mathrm{~g}^{\prime k \overline{\mathrm{k}}} \mathrm{~g}^{\prime \mathrm{p} \overline{\mathrm{q}}} \partial_{\mathrm{I}} \mathrm{~g}_{\mathrm{pj}}^{\prime} \partial_{\mathrm{k}} \mathrm{~g}_{\mathrm{i} \overline{\mathrm{q}}}^{\prime} \tag{3.15}
\end{equation*}
$$

The Schwarz inequality implies

$$
\begin{equation*}
g^{\prime k \bar{l}} \partial_{k} g^{\prime i \bar{j}} g_{i \bar{j}} \partial_{\bar{l}} g^{\prime p \bar{q}} g_{p \bar{q}} \leq-\left(g^{\prime k \bar{l}} g^{\prime p \bar{j}} g_{i \bar{j}} \partial_{\bar{l}} g_{p \bar{q}}^{\prime} \partial_{k} g^{\prime i \bar{q}}\right)\left(g^{\prime i \bar{j}} g_{i \bar{j}}\right) \tag{3.16}
\end{equation*}
$$

Now we use the equation (3.4).

Lemma 3.6. The following formula holds

$$
\triangle^{\prime}\left(\log \operatorname{tr}_{\Omega^{\prime}} \Omega\right) \geq-(n+1)-C\left(\operatorname{tr}_{\Omega^{\prime}} \Omega\right)
$$

with $C$ that depends on $\inf \operatorname{Ric}\left(\Omega_{1}\right), \sup _{i \neq k} R_{\bar{i} i k \bar{k}}(\Omega), \sup \operatorname{tr}_{\Omega} \Omega_{1}$.
Proof. We apply (3.15) and (3.16) to obtain

$$
\begin{aligned}
\triangle^{\prime}\left[\log t r_{\Omega^{\prime}} \Omega\right] & =\frac{\triangle^{\prime}\left(\operatorname{tr}_{\Omega^{\prime}} \Omega\right)}{\operatorname{tr}_{\Omega^{\prime}} \Omega}-\frac{g^{\prime k \bar{l}} \partial_{k} g^{\prime i \bar{j}} g_{i \bar{j}} \partial_{\bar{l}} g^{\prime p \bar{q}} g_{p \bar{q}}}{\left(\operatorname{tr}_{\Omega^{\prime}} \Omega\right)^{2}} \\
& \geq \frac{R^{\prime i \bar{j}} g_{i \bar{j}}-g^{\prime i \bar{j}} g^{\prime k k} R_{i \bar{j} k \bar{l}}}{\operatorname{tr}_{\Omega^{\prime}} \Omega}
\end{aligned}
$$

From (3.4) we have

$$
\begin{aligned}
\operatorname{Ric}^{\prime} & =\operatorname{Ric}(\Omega)-\frac{\sqrt{-1}}{2} \partial \bar{\partial} F \\
& =\operatorname{Ric}(\Omega)+\operatorname{Ric}\left(\Omega_{1}\right)-\operatorname{Ric}(\Omega)-\Omega^{\prime}+\Omega_{1}
\end{aligned}
$$

then $\operatorname{Ric}^{\prime} \geq\left(\inf \operatorname{Ric}\left(\Omega_{1}\right)+1\right) \Omega_{1}-\Omega^{\prime}$ and

$$
\begin{aligned}
{R^{\prime i}}^{i \bar{j}} g_{i \bar{j}} & \geq\left(\inf \operatorname{Ric}\left(\Omega_{1}\right)+1\right) g^{i \bar{l}} g^{\prime k \bar{j}} g_{1, k \bar{l}} g_{1, i \bar{j}}-g^{\prime i \bar{l}} g^{\prime k \bar{l}} g^{\prime}{ }_{k l} g_{i \bar{j}} \\
& \geq-C\left(\operatorname{tr}_{\Omega^{\prime}} \Omega\right)^{2} \cdot\left(\operatorname{tr}_{\Omega} \Omega_{1}\right)^{2}-(\mathrm{n}+1) \operatorname{tr}_{\Omega} \Omega_{1}
\end{aligned}
$$

where $C$ is a positive constant depending on $\inf \operatorname{Ric}\left(\Omega_{1}\right)$. Then we have

$$
\Delta^{\prime}\left(\log \operatorname{tr}_{\Omega^{\prime}} \Omega\right) \geq-(\mathrm{n}+1)-\mathrm{C}\left(\operatorname{tr}_{\Omega^{\prime}} \Omega\right)
$$

where $C$ depends on $\inf \operatorname{Ric}\left(\Omega_{1}\right), \sup _{i \neq k} R_{\bar{i} \bar{i} k \bar{k}}$, $\sup \operatorname{tr}_{\Omega} \Omega_{1}$. This completes the proof of the lemma.

Consider $Z_{1}:=\log \operatorname{tr}_{\Omega^{\prime}} \Omega-\mathrm{C}^{\prime} \Psi+\epsilon \mathrm{S}$, such it has a maximum point $p$ which stays away from $\mathfrak{D}$, and with $C^{\prime}$ to be chosen. Then

$$
\Delta^{\prime} Z_{1} \geq-(n+1)-C \operatorname{tr}_{\Omega^{\prime}} \Omega-\mathrm{C}^{\prime}\left((\mathrm{n}+1)-\operatorname{tr}_{\Omega^{\prime}} \Omega\right)-\operatorname{Ctt}_{\Omega^{\prime}} \Omega
$$

Now we choose $C^{\prime}$ such that $C^{\prime}-C-C \epsilon>0$ and we have at $p, \operatorname{tr}_{\Omega^{\prime}} \Omega \leq \mathrm{C}$. In the same vein as the first part of the subsection we compute that for any $x \in \mathfrak{X}$ there holds

$$
\begin{aligned}
\log \operatorname{tr}_{\Omega^{\prime}} \Omega(\mathrm{x}) & =Z_{1}(x)+C^{\prime} \Psi-\epsilon S+\sup _{\partial \mathfrak{X}} \log \operatorname{tr}_{\Omega^{\prime}} \Omega \\
& \leq Z_{1}(p)+C^{\prime} \sup \Psi+\sup _{\partial \mathfrak{X}} \log \operatorname{tr}_{\Omega^{\prime}} \Omega
\end{aligned}
$$

Using the arithmetic-geometric-mean inequality we have

$$
\begin{equation*}
\left(\operatorname{tr}_{\Omega} \Omega^{\prime}\right)^{\frac{1}{n}} \leq \operatorname{tr}_{\Omega^{\prime}} \Omega \mathrm{e}^{\frac{\mathrm{F}}{n}} \leq \mathrm{C} \sup _{\partial \mathfrak{X}} \operatorname{tr}_{\Omega^{\prime}} \Omega \tag{3.17}
\end{equation*}
$$

where $C$ depends on $\inf \operatorname{Ric}\left(\Omega_{1}\right), \sup _{i \neq k} R_{i \bar{k} k \bar{k}}(\Omega), \sup \operatorname{tr}_{\Omega} \Omega_{1}$, $\operatorname{Osc} \Psi, \inf \Psi_{1}$. This formula gives precisely the third constant of formula (3.8).

We could choose $\Omega_{1}$ as the background metric and repeat the estimate, but it will not provide more information. The three constants $C_{i}$ are determined by the formulas (3.13), (3.14) and (3.17), respectively. This concludes the proof of Proposition 3.3
3.3. Boundary Hessian estimate. The boundary hessian estimate for real and complex Monge-Ampère equation is developed in [11, 40, [36, (34 and [16]. The difficulty that arises in our problem is the estimate near the singular varieties $V_{i}$. The distance function can not be used in our problem, since we need the uniform estimate which is independent of the distance to the divisor $\mathfrak{D}$. We overcome this difficulty by multiplying singular terms with proper weight and using the linear theory developed in Section 5 to construct an appropriate barrier function which is independent of the distance function.

Proposition 3.7. The following boundary estimate holds

$$
\sup _{X \times \partial R}|\sqrt{-1} \partial \bar{\partial} \Psi|_{\Omega} \leq C\left(\sup _{X}|\partial \Psi|_{\Omega}+1\right) .
$$

The constant $C$ depends on $\left|\partial \tilde{g}_{1 \alpha \bar{\beta}}\right|,|\Psi|,\left|\partial \Psi_{1}\right|_{\Omega},\left|\partial \Psi_{0}\right|_{\Omega},\left|\partial \bar{\partial} \Psi_{0}\right|$,
Proof. Fix a point $p \in M \times \partial R$, and consider $U_{p} \subset M \times R$ an open neighborhood of $p$. Recall that we denote by $\Psi$ an a priori solution of the equation

$$
\operatorname{det}\left(\Omega_{i \bar{j}}+\Psi_{i \bar{j}}\right)=\tau f e^{\Psi-\Psi_{1}} \operatorname{det}\left(\Omega_{i \bar{j}}\right)
$$

whose boundary values are given by the datum $\Psi_{0}$. The tangent-tangent term of the boundary Hessian estimate follows from the boundary value directly. Since the boundary is flat, the normal-normal term follows from the construction of the approximate geodesic equation

$$
\left[\varphi^{\prime \prime}-\left(\partial \varphi^{\prime}, \partial \varphi^{\prime}\right)_{g_{\varphi}}\right] \operatorname{det} \omega_{\varphi}=\Omega_{\Psi}^{n+1}=\tau e^{\Psi-\Psi_{1}} \operatorname{det}\left(\Omega_{1 i \bar{j}}\right)
$$

i.e.

$$
\begin{equation*}
\left|\frac{\partial}{\partial z^{n+1}} \frac{\partial}{\partial z^{\overline{n+1}}} \Psi\right|_{\Omega ; X \times \partial R} \leq \sum_{i}\left|\frac{\partial}{\partial z^{n+1}} \frac{\partial}{\partial z^{\bar{i}}} \Psi\right|_{\Omega ; X \times \partial R}+C \tag{3.18}
\end{equation*}
$$

The constant $C$ depends on $\left|\Psi_{1}\right|,\left|\Psi_{0}\right|,\left|\partial \bar{\partial} \Psi_{0}\right|_{\Omega}$ and $\operatorname{det}\left(\Omega_{1 i \bar{j}}\right)$. The quantity $\operatorname{det}\left(\Omega_{1 i \bar{j}}\right)$ depends on the boundary value and the chosen function $\Phi$ in Proposition 2.5. Then the aim of the present subsection is to derive the mixed tangent-normal estimate on the boundary.

We put

$$
\triangle^{\prime}:=\sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} \frac{\partial^{2}}{\partial z^{\alpha} \partial z^{\bar{\beta}}} .
$$

The elliptic operator $\triangle^{\prime}$ allows the use of the maximum principle in Section 5.1.
Our idea is to construct a barrier function and apply the maximum principle locally in a small neighborhood of the point $p \in M \times \partial R$. Since the second order derivatives of $\Psi$ blow up near the singular points where $\mathfrak{D}$ intersects $X \times \partial R$, we need to prove that the estimates do not depend on the choice of the diameter of the small neighborhood $U_{p}$.

Let us suppose that the open neighborhood $U_{p} \subset X \times R$ is a coordinate chart near $p$ (cf. Definition 1.1) for the first $n$ variables; moreover, the coordinate $z^{n+1}:=$ $x+\sqrt{-1} y$ in $U_{p}$ locally parametrizes the Riemann surface $R$. Next, let us define the function $v: U_{p} \rightarrow \mathbb{R}$ as

$$
\begin{equation*}
v:=\left(\Psi-\Psi_{1}\right)+s x-N x^{2} \tag{3.19}
\end{equation*}
$$

where $N, s$ are constants which depend only on $M \times R$, the background metric $g$ and the datum $\Psi_{0}$, and they will be determined later in (3.21) and (3.22) respectively.

Also, let us fix the small neighborhood of the origin $\Omega_{\delta}:=(M \times R) \cap B_{\delta}(0) \subset U_{p}$ with small radius $\delta<1$. We require that $\Omega_{\delta}$ does not intersect $\mathfrak{D}$. We will show that the estimate does not depend on the choice of $\delta$.

We first prove the following lemma.
Lemma 3.8. The following inequalities hold

$$
\left\{\begin{array}{l}
\triangle^{\prime} v \leq-\frac{\epsilon}{4}\left(1+\sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}\right) \text { in } \Omega_{\delta}  \tag{3.20}\\
v \geq 0 \quad \text { on } \partial \Omega_{\delta}
\end{array}\right.
$$

where $\epsilon>0$ is a constant depending on the lower bound of $\Omega_{\Psi_{0}}$.
Proof. By means of the equation (3.19) and the linearity of $\triangle^{\prime}$, let us first consider the term $\triangle^{\prime}\left(\Psi-\Psi_{1}\right)$. Here the remark to do is that, as the metric $g_{\alpha \bar{\beta}}+\Psi_{1 \alpha \bar{\beta}}$ is $L^{\infty}$ equivalent to $g_{\alpha \bar{\beta}}$ in $X \times R$, then we can find a uniform constant $\epsilon$ such that $g_{\alpha \bar{\beta}}+\Psi_{1 \alpha \bar{\beta}}>\epsilon g_{\alpha \bar{\beta}}$ holds point-wise in $\Omega_{\delta}$ (could be in the whole $\mathfrak{X}$ ). Notice that the lower bound of $\Omega_{\Psi_{1}}$ depends on the lower bound of $\Omega_{\Psi_{0}}$. We conclude, using the remark, that just by definition there holds

$$
\begin{aligned}
& \triangle^{\prime}\left(\Psi-\Psi_{1}\right)=\sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\alpha \bar{\beta}}\left[\left(g_{\alpha \bar{\beta}}+\Psi_{\alpha \bar{\beta}}\right)-\left(g_{\alpha \bar{\beta}}+\Psi_{1 \alpha \bar{\beta}}\right)\right] \\
& =n+1-\sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\Psi_{1} \alpha \bar{\beta}} \leq n+1-\epsilon \sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}} .
\end{aligned}
$$

It is clear that $\triangle^{\prime} x=0$ and $\triangle^{\prime} x^{2}=2 g^{\prime(n+1) \overline{n+1}}$. Thus, we have

$$
\begin{aligned}
\triangle^{\prime} v & =\triangle^{\prime}\left(\Psi-\Psi_{1}\right)+s \triangle^{\prime} x-2 N g^{\prime(n+1) \overline{n+1}} \\
& \leq n+1-\epsilon \sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}-2 N g^{\prime(n+1) \overline{n+1}} \\
& =n+1+\left(-\frac{\epsilon}{2}\right) \sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}-2 N g^{\prime(n+1) \overline{n+1}}-\frac{\epsilon}{2} \sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}} .
\end{aligned}
$$

Without loss of generality we can prove the inequality in the local normal coordinate such that, at the origin, there holds $g_{\alpha \bar{\beta}}=\delta_{\alpha \bar{\beta}}$. We have, at the origin,

$$
\begin{aligned}
& N g^{\prime(n+1) \overline{n+1}}+\frac{\epsilon}{4} \sum_{\alpha, \bar{\beta}=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}} \\
& =\left(N+\frac{\epsilon}{4}\right) \frac{1}{1+\Psi_{(n+1) \overline{n+1}}}+\frac{\epsilon}{4} \sum_{j=1}^{n} \frac{1}{1+\Psi_{j \bar{j}}} \\
& \geq(n+1)\left[\left(N+\frac{\epsilon}{4}\right) \cdot\left(\frac{\epsilon}{4}\right)^{n} \prod_{\alpha=1}^{n+1} \frac{1}{1+\Psi_{\alpha \bar{\alpha}}}\right]^{\frac{1}{n+1}}
\end{aligned}
$$

Since, still at the origin, there holds

$$
\prod_{\alpha=1}^{n+1} \frac{1}{1+\Psi_{\alpha \bar{\alpha}}}=\frac{\Omega^{n+1}}{\Omega_{\Psi}^{n+1}}=\frac{1}{\tau f} e^{\Psi_{1}-\Psi} \geq e^{\inf \left(\Psi_{1}-\Psi\right)} \frac{1}{\sup f}
$$

then we choose the constant $N$ large enough so that

$$
\begin{equation*}
-2(n+1)\left[\left(N+\frac{\epsilon}{4}\right)\left(\frac{\epsilon}{4}\right)^{n} e^{\inf \left(\Psi_{1}-\Psi\right)} \frac{1}{\sup f}\right]^{\frac{1}{n+1}}+n+1<-\frac{\epsilon}{4} \tag{3.21}
\end{equation*}
$$

Here $N$ depends on $\inf \left(\Psi_{1}-\Psi\right), \sup f=\sup \frac{\Omega_{1}^{n+1}}{\Omega^{n+1}}$ and $\epsilon$.
To fully achieve the claim (3.20), we have to verify the condition on $\partial \Omega_{\delta}$. On $\partial \Omega_{\delta} \cap \partial(M \times R)$, there holds $v=0$. On $\partial \Omega_{\delta} \cap \operatorname{Int}(M \times R)$, there holds, since $\Psi \geq \Psi_{1}, v \geq(s-N x) x \geq(s-N \delta) x$. So we choose $s=2 N$ such that

$$
\begin{equation*}
(s-N \delta) x \geq 0 \tag{3.22}
\end{equation*}
$$

This completes the proof of the lemma.
Now, we come to construct the auxiliary function $u$. We construct a nonnegative boundary value $\phi$ such that $\phi$ only vanishes on the point $p$. For example, $\phi=$ $\Psi_{0}-\Psi_{0}(p)+e^{\left|\Psi_{0}-\Psi_{0}(p)\right|}-1$. Then we solve the equation $\triangle_{g} u_{\|}=-n-1$ with the boundary value $\phi$. According to the maximum principle for the cone metrics (cf. Proposition 5.5, we have $u_{\|} \geq 0$. Meanwhile, we choose a smooth nonnegative function $u_{\perp}$ of $z^{n+1}$ monotonic along $\frac{\partial}{\partial z^{n+1}}$ such that it vanishes on the boundary and strictly larger than $u_{\|}+1$ in the interior of $\mathfrak{X}$, since $u_{\|}$is bounded. Now, we define the function $u$ by adding up $u_{\|}$and $u_{\perp}$.

We need to change the variables via the map $W$ defined at (2.1), extended as the identity on the variable $z^{n+1}$; we mark functions and operators transformed under $W$ with on the top. Finally, under $W$ coordinate functions become, for $1 \leq i \leq n$, $w^{i}=x^{i}+\sqrt{-1} y^{i}$; then, we define $D_{i}:=\frac{\partial}{\partial x^{i}}$, for $1 \leq i \leq 2 n$. With the above notations, we define the function $h: U_{p} \rightarrow \mathbb{R}$ as

$$
h:=\lambda_{1} \tilde{v}+\lambda_{2} \tilde{u}+\lambda_{3} \cdot D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)
$$

for one fixed $1 \leq i \leq n$ and three constants $\lambda_{1}, \lambda_{2}$ and $\lambda_{3}$ determined below.
We emphasize that till the end of the subsection, the index $1 \leq i \leq n$ is fixed; we recall that the cone angle $\beta_{i}$ is equal to one for the directions corresponding to $k+1 \leq i \leq n$.

We notice that at the origin (or point $p$ ), the value of $h$ is zero. We define $\rho_{i}$ as the distance from $p$ to the divisor only along the coordinate $w^{i}$. We shrink $\Omega_{\delta}$ to be the set containing such points whose distance to $p$ less than half the distance from $p$ to $D$. So, on $\partial \Omega_{\delta} \cap \partial(M \times R)$ there holds $\frac{\rho_{i}}{2} \leq\left|w^{i}\right| \leq 2 \rho_{i}$ and $\tilde{u} \geq 1$; then, letting $\lambda_{3}$ be the smallest eigenvalue of the inverse matrix of $W_{*} \Omega$, there holds for $q \in \partial \Omega_{\delta} \cap \operatorname{Int}(M \times R)$

$$
\begin{aligned}
h(q) & \geq \lambda_{2} \tilde{u}(q)-\lambda_{3}\left|D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)(q)\right| \\
& \geq \lambda_{2}-C\left|\partial\left(\Psi-\Psi_{1}\right)(q)\right|_{\Omega} \\
& \geq 0
\end{aligned}
$$

where the last inequality is true provided $\lambda_{2}=1+C\left|\partial\left(\Psi-\Psi_{1}\right)(q)\right|_{\Omega}$ with $C$ that depends on background metric $\Omega$. Let us come to analyze $\tilde{\triangle}^{\prime} h$.
Lemma 3.9. There exist $\lambda_{1}$ depending on $\lambda_{2}, \lambda_{4}=\left|D_{i} \log \tilde{\Omega}_{1}^{n+1}\right|+|\partial \Psi|_{\Omega}+\left|\partial \Psi_{1}\right|_{\Omega}$, $\lambda_{5}=\left|D_{i} \tilde{g}_{1 \alpha \bar{\beta}}\right| \Omega$, such that

$$
\tilde{\triangle}^{\prime} h \leq 0
$$

Proof. By our preliminary work, we read off (3.20) an estimate for $\triangle^{\prime} v=\tilde{\triangle}^{\prime} \tilde{v}$. About $\triangle^{\prime} \tilde{u}$, we compute

$$
\begin{equation*}
\tilde{\triangle}^{\prime} \tilde{u}=\triangle^{\prime} u=\sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} u_{\alpha \bar{\beta}} \leq C \sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}} \tag{3.23}
\end{equation*}
$$

where $C$ is a constant depending on $\Psi_{0}$ and $u_{\perp}$. Finally, as $\Psi$ is a solution to $\Omega_{\Psi}^{n+1}=e^{F} \Omega^{n+1}$ with $F=\log \tau+\log f+\Psi-\Psi_{1}$, we differentiate this equation under coordinate $w^{i}$, and we get

$$
\begin{aligned}
& \tilde{\triangle}^{\prime} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right) \\
& =\sum_{\alpha, \beta=1}^{n+1} D_{i} \log \tilde{\Omega}_{1}^{n+1}+D_{i} \tilde{\Psi}-D_{i} \tilde{\Psi}_{1}-\sum_{\alpha, \beta=1}^{n+1}(\tilde{g})^{\prime \alpha \bar{\beta}} D_{i} \tilde{g}_{1 \alpha \bar{\beta}}
\end{aligned}
$$

We end up with the estimate for $\tilde{\triangle}^{\prime} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{0}\right)$,

$$
\begin{equation*}
\tilde{\triangle}^{\prime} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right) \leq \lambda_{4}+\lambda_{5} \sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}} \tag{3.24}
\end{equation*}
$$

There, $\lambda_{4}:=\left|\partial \log \tilde{\Omega}_{1}^{n+1}\right|+|\partial \Psi|_{\Omega}+\left|\partial \Psi_{1}\right|_{\Omega}, \lambda_{5}:=\left|\partial \tilde{g}_{1 \alpha \bar{\beta}}\right|_{\Omega}$. We conclude the following estimate for $\tilde{\triangle}^{\prime} h$ by means of (3.23) and (3.24);

$$
\begin{aligned}
& \tilde{\triangle}^{\prime} h=\lambda_{1} \tilde{\triangle}^{\prime} \tilde{v}+\lambda_{2} \tilde{\triangle}^{\prime} \tilde{u}+\lambda_{3} \tilde{\triangle}^{\prime} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right) \\
& \leq-\lambda_{1} \frac{\epsilon}{4}\left(1+\sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}\right)+\lambda_{2} \cdot C \sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}+\left[\lambda_{4}+\lambda_{5} \sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}\right] \\
& \leq\left[-\frac{\epsilon}{4} \lambda_{1}+\lambda_{2} \cdot C+\lambda_{4}+\lambda_{5}\right] \cdot\left(1+\sum_{\alpha, \beta=1}^{n+1} g^{\prime \alpha \bar{\beta}} g_{\alpha \bar{\beta}}\right)<0,
\end{aligned}
$$

after choosing $\lambda_{1}$ properly.
(Completion of the proof of Proposition 3.7) To summarize, we get $h \geq 0$ on $\partial \Omega_{\delta}$ and $\tilde{\triangle}^{\prime} h<0$ in $\Omega_{\delta}$ in the weak sense. So, by the weak maximum principle, we get that $h \geq 0$ in $\Omega_{\delta}$. Since $h(0)=0$, then we have (recall $z^{n+1}=x+\sqrt{-1} y$ )

$$
\frac{\partial h}{\partial x}(0) \geq 0, \quad \frac{\partial h}{\partial y}(0) \geq 0
$$

In particular, we compute

$$
\frac{\partial h}{\partial x}=\lambda_{1} \frac{\partial\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)}{\partial x}+s-2 N x+\lambda_{2} \frac{\partial \tilde{u}}{\partial x}+\lambda_{3} \frac{\partial}{\partial x} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)
$$

which leads to

$$
\lambda_{3} \frac{\partial}{\partial x} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)(0) \geq-s-\lambda_{1} \frac{\partial\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)}{\partial x}(0)-\lambda_{2} \frac{\partial \tilde{u}}{\partial x}(0)
$$

Combining the above inequality with $\frac{\partial}{\partial y} D_{i}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)=0$, and adding the inequalities, we get that for any $1 \leq i \leq n$

$$
\frac{\partial}{\partial z^{n+1}} \frac{\partial}{\partial w^{\bar{i}}}\left(\tilde{\Psi}-\tilde{\Psi}_{1}\right)(0) \geq-C
$$

where $C$ depends on $\lambda_{1}, \lambda_{2},|\partial \Psi|_{\Omega},\left|\partial \Psi_{1}\right|_{\Omega}$ and $|\partial u|_{\Omega}$. We repeat the same argument for $D_{i}=-\frac{\partial}{\partial x^{i}}$ and for $D_{i}=-\frac{\partial}{\partial y^{i}}$ and we conclude that the tangent-normal derivative is bounded, for $1 \leq i \leq n$, by

$$
\begin{equation*}
\left|\frac{\partial}{\partial z^{n+1}} \frac{\partial}{\partial z^{\bar{i}}} \Psi\right|_{\Omega}(0)=\left|\frac{\partial}{\partial z^{n+1}} \frac{\partial}{\partial w^{\bar{i}}} \Psi\right|(0) \geq\left|\frac{\partial}{\partial z^{n+1}} \frac{\partial}{\partial w^{i}} \Psi_{0}\right|(0)+C \tag{3.25}
\end{equation*}
$$

where again $C$ depends on $\lambda_{1}, \lambda_{2},|\partial \Psi|_{\Omega},\left|\partial \Psi_{1}\right|_{\Omega}$ and $|\partial u|_{\Omega}$. Note from the construction of $\Psi_{1}$ that the derivatives of $\Psi_{1}$ are controlled by the corresponding derivatives of $\Psi_{0}$. As (3.25) clearly coincides with (3.18), this completes the proof of the proposition.
3.4. Interior gradient estimate. We directly calculate the norm of the gradient to obtain the differential inequality in Proposition 3.14. Gradient estimates were obtained by Cherrier and Hanani 24 39 for Hermitian manifolds and later by Blocki [8] for the Kähler case. Since (3.2) has singularity along the divisor, in order to apply the maximum principle, we need to choose an appropriate test function near the divisor.

We define the following functions, where $\epsilon>0$ and $\gamma: \mathbb{R} \rightarrow \mathbb{R}$ are not yet specified

$$
\begin{aligned}
& B:=|\partial \Psi|^{2}=g^{i \bar{\jmath}} \Psi_{i} \Psi_{\bar{j}}, \quad D:=|\partial \Psi|_{g^{\prime}}^{2}=g^{\prime k \bar{l}} \Psi_{k} \Psi_{\bar{l}} \\
& Z:=\log B-\gamma(\Psi), \quad K:=Z-\sup _{\boldsymbol{D}} Z+\epsilon S
\end{aligned}
$$

Consider $\kappa$ and $S=\|s\|^{2 \kappa}$ as in Lemma 2.4. Recall that $0<\alpha<\mu=\beta^{-1}-1$.
Lemma 3.10. Suppose that $\Psi \in C_{\beta}^{2, \alpha}$ with $\alpha>0$ and $\beta_{i}<\frac{1}{2}, \forall 1 \leq i \leq k$. Then for any $\kappa$ satisfies $\beta_{i} \leq 2 \kappa<(1+\alpha) \beta_{i}, \forall 1 \leq i \leq k$, the function $K=Z-\sup _{\mathfrak{D}} Z+\epsilon S$ achieves its maximum away from $\mathfrak{D}$ and $|\partial S|_{\Omega} \leq C$.

Proof. The second claim follows directly from the formula (cf. Lemma 2.4)

$$
g_{\Omega}^{1 \overline{1}} \frac{\partial}{\partial z^{1}} S \frac{\partial}{\partial z^{\overline{1}}} S=O\left(\left|z^{1}\right|^{2(1-\beta)+4 \kappa-2}\right)
$$

and the fact that the exponent is non-negative.
Now we verify the first statement. We only concern one direction $\frac{\partial}{\partial z^{1}}$ perpendicular to one component of the divisor defined by $z^{1}=0$, other directions are verified similarly. We have

$$
\partial_{1} Z=B^{-1} g^{i \bar{j}}\left(\nabla_{1} \nabla_{i} \Psi \cdot \Psi_{\bar{j}}+\Psi_{i} \cdot \partial_{1} \partial_{\bar{j}} \Psi\right)-\gamma^{\prime} \Psi_{1}
$$

In order to prove $Z \in C_{\beta}^{1, \alpha}$, it suffices to prove that $\nabla_{1} \nabla_{i} \Psi \in C_{\beta}^{\alpha}$ which follows from Remark 5.1. On the other hand, $\left|\partial_{1}^{1+\alpha} S\right|=O\left(\left|z^{1}\right|^{2 \kappa-(1+\alpha) \beta}\right)$ with negative power. Thus we see that $S$ grows extremely faster than $Z-\sup _{\mathfrak{D}} Z$ near the divisor. Since $Z-\sup _{\mathfrak{D}} Z$ is non-positive on $\mathfrak{D}$ while $S$ vanishes along $\mathfrak{D}$, we obtain that the maximum point of $Z-\sup _{\mathfrak{D}} Z+\epsilon S$ must be achieved on $\mathfrak{M}$.

With the lemmas above, we could assume that $p$ in the interior of $\mathfrak{M}$ is the maximum point of $K$ and choose the normal coordinate around $p$. We get at $p$,

$$
g_{i \bar{j}}=\delta_{i j} \text { and } \frac{\partial g_{i \bar{j}}}{\partial z^{k}}=\frac{\partial g_{i \bar{j}}}{\partial z^{\bar{j}}}=0
$$

SO

$$
\Psi_{i \bar{j}}=\Psi_{i \bar{i}} \delta_{i j} \text { and } g^{\prime i \bar{j}}=\frac{\delta_{i j}}{1+\Psi_{i \bar{i}}}
$$

We have

$$
\begin{aligned}
\triangle^{\prime} K & =B^{-1} \sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}}\left[R_{i \bar{j} k \bar{k}} \Psi_{j} \Psi_{\bar{i}}+\Psi_{k \bar{k} i} \Psi_{\bar{i}}+\Psi_{i} \Psi_{k \bar{k} \bar{i}}+\Psi_{i k} \Psi_{\bar{i} \bar{k}}+\Psi_{i \bar{k}} \Psi_{\bar{i} k}\right] \\
& -\gamma^{\prime} \triangle^{\prime} \Psi-\gamma^{\prime \prime} D-B^{-2} g^{\prime k \bar{l}} B_{k} B_{\bar{l}}+\epsilon \triangle^{\prime} S
\end{aligned}
$$

We deal with these terms by means of the next lemmas.
Lemma 3.11. The following inequality holds

$$
B^{-1} \sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}} R_{i \bar{j} k \bar{k}} \Psi_{i} \Psi_{\bar{j}}-\gamma^{\prime} \triangle^{\prime} \Psi \geq \sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}}\left(\inf R_{i \bar{j} k \bar{k}}+\gamma^{\prime}\right)-(n+1) \gamma^{\prime}
$$

Proof. From

$$
\triangle^{\prime} \Psi=\sum_{k} \frac{\Psi_{k \bar{k}}}{1+\Psi_{k \bar{k}}}=n+1-\sum_{k} \frac{1}{1+\Psi_{k \bar{k}}}
$$

we have the lemma.
Lemma 3.12. The following formula holds

$$
B^{-1} \sum_{k, i} \frac{1}{1+\Psi_{k \bar{k}}} \Psi_{i} \Psi_{k \bar{k} \bar{i}}=B^{-1} \sum_{k, i} \frac{1}{1+\Psi_{k \bar{k}}} \Psi_{\bar{i}} \Psi_{k \bar{k} i} \leq 1+|\partial \log f|_{\Omega}+\left|\partial \Psi_{1}\right|_{\Omega}
$$

Proof. Differentiating the equation (3.9), we have

$$
g^{\prime i \bar{j}}\left(\partial_{k} g_{i \bar{j}}+\Psi_{i \bar{j} k}\right)-g^{i \bar{j}} \partial_{k} g_{i \bar{j}}=\partial_{k} F,
$$

or

$$
\begin{equation*}
\sum_{i} \frac{\Psi_{i \bar{i} k}}{1+\Psi_{i \bar{i}}}=F_{k}=\partial_{k} \Psi+\partial_{k}\left(\log f-\Psi_{1}\right) \tag{3.26}
\end{equation*}
$$

Then (3.26) implies

$$
\begin{aligned}
B^{-1} \sum_{k, i} \frac{1}{1+\Psi_{k \bar{k}}} \Psi_{i} \Psi_{k \bar{k} \bar{i}} & =B^{-1} \sum_{k, i} \frac{1}{1+\Psi_{k \bar{k}}} \Psi_{\bar{i}} \Psi_{k \bar{k} i} \\
& =B^{-1} \Psi_{i} F_{\bar{i}} \\
& =1+B^{-1} \Psi_{i} \tilde{F}_{\bar{i}} \\
& \leq 1+|\partial \tilde{F}|_{\Omega} .
\end{aligned}
$$

Here $\tilde{F}=\log f-\Psi_{1}$.
Lemma 3.13. The following formula holds
$-B^{-2} g^{\prime k \bar{l}} B_{k} B_{\bar{l}}+B^{-1} \sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}}\left[\Psi_{i k} \Psi_{\bar{i} \bar{k}}+\Psi_{k \bar{k}} \Psi_{\bar{k} k}\right] \geq-\left(\gamma^{\prime}+\epsilon\right)-\epsilon B^{-1}|\partial S|_{\Omega}$.

Proof. At $p$ we have

$$
0=\left(Z_{k}+\epsilon S_{k}\right)(p)=B^{-1} B_{k}-\gamma^{\prime} \Psi_{k}+\epsilon S_{k}^{\prime}
$$

i.e.

$$
B^{-1} B_{k}=\gamma^{\prime} \Psi_{k}-\epsilon S_{k}
$$

Also,

$$
0=\left(Z_{\bar{l}}+\epsilon S_{\bar{l}}\right)(p)=B^{-1} B_{\bar{l}}-\gamma^{\prime} \Psi_{\bar{l}}+\epsilon S_{\bar{l}}
$$

i.e.

$$
B^{-1} B_{\bar{l}}=\gamma^{\prime} \Psi_{\bar{l}}-\epsilon S_{\bar{l}}
$$

Since at $p$ we have

$$
B_{k}=\Psi_{i k} \Psi_{\bar{i}}+\Psi_{i} \Psi_{\bar{i} k},
$$

and

$$
B_{\bar{l}}=\Psi_{i \bar{l}} \Psi_{\bar{i}}+\Psi_{i} \Psi_{\bar{i} \bar{l}}
$$

we obtain

$$
\Psi_{i k} \Psi_{\bar{i}}=B\left(\gamma^{\prime} \Psi_{k}-\epsilon S_{k}\right)-\Psi_{i} \Psi_{\bar{i} k}
$$

and

$$
\Psi_{i} \Psi_{\bar{i} \bar{l}}=B\left(\gamma^{\prime} \Psi_{\bar{l}}-\epsilon S_{\bar{l}}\right)-\Psi_{i \bar{l}} \Psi_{\bar{i}}
$$

So

$$
\begin{aligned}
g^{\prime k \bar{l}} B_{k} B_{\bar{l}} & =g^{\prime k \bar{l}}\left[\Psi_{i k} \Psi_{\bar{i}} \Psi_{j \bar{l}} \Psi_{\bar{j}}+\Psi_{i} \Psi_{\bar{i} k} \Psi_{j} \Psi_{\bar{j} \bar{l}}+\Psi_{i k} \Psi_{\bar{i}} \Psi_{j} \Psi_{\bar{j} \bar{l}}+\Psi_{i \bar{l}} \Psi_{\bar{i}} \Psi_{j} \Psi_{\bar{j} k}\right] \\
& =g^{\prime k \bar{l}}\left\{B\left(\gamma^{\prime} \Psi_{k}-\epsilon S_{k}\right) \Psi_{j \bar{l}} \Psi_{\bar{j}}-\Psi_{i \bar{l}} \Psi_{\bar{i}} \Psi_{j} \Psi_{\bar{j} k}+\Psi_{i k} \Psi_{\bar{i}} \Psi_{j} \Psi_{\bar{j} \bar{l}}\right\}^{\prime}
\end{aligned}
$$

using the normal coordinate at $p$ and assuming $\gamma^{\prime}>0$ we have

$$
\begin{aligned}
g^{\prime k \bar{l}} B_{k} B_{\bar{l}} & =\sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}}\left\{B\left(\gamma^{\prime} \Psi_{k}-\epsilon S_{k}\right) \Psi_{k \bar{k}} \Psi_{\bar{k}}-\left(\Psi_{k \bar{k}} \Psi_{\bar{k}}\right)^{2}+\Psi_{i k} \Psi_{\bar{i}} \Psi_{j} \Psi_{\bar{j} \bar{k}}\right\} \\
& \leq B \sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}}\left\{\left(\gamma^{\prime} \Psi_{k}-\epsilon S_{k}\right)\left(\Psi_{k \bar{k}}+1\right) \Psi_{\bar{k}}-\left(\Psi_{k \bar{k}}\right)^{2}+\Psi_{i k}^{2}\right\} \\
& \leq\left(\gamma^{\prime}+\epsilon\right) B^{2}+\epsilon B|\partial S|_{\Omega}+B \sum_{k, i} \frac{1}{1+\Psi_{k \bar{k}}}\left\{-\left(\Psi_{k \bar{k}}\right)^{2}+\Psi_{i k}^{2}\right\} .
\end{aligned}
$$

So

$$
\begin{aligned}
& -B^{-2} g^{\prime k \bar{l}} B_{k} B_{\bar{l}}+B^{-1} \sum_{k, i, j} \frac{1}{1+\Psi_{k \bar{k}}}\left[\Psi_{i k} \Psi_{\bar{i} \bar{k}}+\Psi_{k \bar{k}} \Psi_{\bar{k} k}\right] \\
& \geq-\left(\gamma^{\prime}+\epsilon\right)-\epsilon B^{-1}|\partial S|_{\Omega}+2 B^{-1} \sum_{k} \frac{\left(\Psi_{k \bar{k}}\right)^{2}}{1+\Psi_{k \bar{k}}}
\end{aligned}
$$

Proposition 3.14. We have the gradient estimate

$$
\sup _{\mathfrak{X}}|\partial \Psi|_{\Omega}^{2} \leq C_{i} \text { for } i=1,2 .
$$

The constants $C_{i}$ depend on, respectively,

$$
\begin{aligned}
& C_{1}=C_{1}\left(\inf _{i \neq k} R_{i \bar{i} k \bar{k}}(\Omega), \text { sup }|\partial \log f|_{\Omega}, \text { sup }\left|\partial \Psi_{1}\right|_{\Omega}, \operatorname{Osc}_{\mathfrak{X}} \Psi, \operatorname{Osc}_{\partial \mathfrak{X}} \Psi_{1}\right) \\
& C_{2}=C_{2}\left(\inf _{i \neq k} R_{i \bar{i} k \bar{k}}\left(\Omega_{1}\right), \sup \left|\partial \Psi_{1}\right|_{\Omega}, \sup \operatorname{tr}_{\Omega} \Omega_{1}, \sup \operatorname{tr}_{\Omega_{1}} \Omega, \operatorname{Osc}_{\mathfrak{X}} \Psi, \operatorname{Osc}_{\mathfrak{X}} \Psi_{1}\right)
\end{aligned}
$$

Proof. We assume $B(p) \geq 1$, otherwise we are done. We compute

$$
\begin{aligned}
\Delta^{\prime}\left(Z-\sup _{\mathfrak{D}} Z+\epsilon S\right) & \geq \sum_{i, j, k} \frac{1}{1+\Psi_{k \bar{k}}}\left(\inf _{i \neq k} R_{i \bar{i} k \bar{k}}+\gamma^{\prime}\right)-(n+1) \gamma^{\prime}-\gamma^{\prime \prime} D-1 \\
& -|\partial \log f|_{\Omega}-\left|\partial \Psi_{1}\right|_{\Omega}-\left|\gamma^{\prime}+\epsilon\right|-\epsilon B^{-1}|\partial S|_{\Omega}-C \epsilon \operatorname{tr}_{\Omega^{\prime}} \Omega \\
& =\left(\inf _{i \neq k} R_{i \bar{i} k \bar{k}}+\gamma^{\prime}-C \epsilon\right) \operatorname{tr}_{\Omega^{\prime}} \Omega-\gamma^{\prime \prime} \mathrm{D}-1-|\partial \log \mathrm{f}|_{\Omega}-\left|\partial \Psi_{1}\right|_{\Omega} \\
& -(n+1) \gamma^{\prime}-(n+2) \gamma^{\prime}-\epsilon-\epsilon|\partial S|_{\Omega}
\end{aligned}
$$

We choose an appropriate $\gamma$, for example

$$
\gamma(t):=-C^{\prime} e^{\sup \Psi-t}, \quad \text { where } C^{\prime}:=\inf _{i \neq k} R_{i \bar{i} k \bar{k}}-C \epsilon+1
$$

We notice that $|\nabla S|$ is bounded by means of Lemma 3.10. Then,

$$
D+\operatorname{tr}_{\Omega^{\prime}} \Omega(\mathrm{p}) \leq \mathrm{C}=\mathrm{C}\left(\inf _{\mathrm{i} \neq \mathrm{k}} \mathrm{R}_{\mathrm{ii} \overline{\mathrm{ik}},}, \sup |\partial \log \mathrm{f}|_{\Omega}, \sup \left|\partial \Psi_{1}\right|_{\Omega}\right)
$$

Since

$$
\left(\operatorname{tr}_{\Omega} \Omega^{\prime}\right)^{\frac{1}{n}}=(n+1+\Delta \Psi)^{\frac{1}{n}} \leq \operatorname{tr}_{\Omega^{\prime}} \Omega \cdot \mathrm{e}^{\frac{\mathrm{F}}{\mathrm{n}}}
$$

so $B \leq \operatorname{tr}_{\Omega} \Omega^{\prime} \cdot \mathrm{D} \leq \mathrm{C}$. Moreover, for any $x \in \operatorname{Int}(\mathfrak{X})$, there holds

$$
\begin{aligned}
\log B(x) & =K(x)+\gamma(\Psi)(x)-\epsilon S(x)+\sup _{\mathfrak{D}} Z \\
& \leq K(p)+\sup _{\partial \mathscr{X}} K+\gamma(\Psi)(x)-\epsilon S(x)+\sup _{\mathfrak{D}} Z \\
& =\log B(p)-\gamma(\Psi)(p)-\sup _{\mathfrak{D}} Z+\epsilon S(p)+\sup _{\partial \mathfrak{X}} K+\gamma(\Psi)(x)-\epsilon S(x)+\sup _{\mathfrak{D}} Z \\
& \leq \log B(p)-\gamma(\Psi)(p)+\gamma(\Psi)(x)+\sup _{\partial \mathfrak{X}}\left(\log B-\sup _{\mathfrak{D}} \log B-\gamma(\Psi)\right)+C .
\end{aligned}
$$

Here we use the assumption that $B \geq 1$, so $\log B \geq 0$. Similarly to former arguments, we change the background metric and we consider

$$
\log \frac{\operatorname{det}\left(\Omega_{1, i \bar{j}}+\tilde{\Psi}_{i \bar{j}}\right)}{\operatorname{det}\left(\Omega_{1, i \bar{j}}\right)}=F_{1}=\log \tau+\tilde{\Psi}
$$

We arrive at

$$
\sup _{\mathfrak{X}}|\partial \tilde{\Psi}|_{\Omega_{1}}^{2} \leq C .
$$

As a result, the proof of the proposition follows from

$$
\sup _{\mathfrak{X}}|\partial \Psi|_{\Omega} \leq \sup _{\mathfrak{X}} \operatorname{tr}_{\Omega} \Omega_{1} \cdot\left(\sup _{\mathfrak{X}}|\partial \tilde{\Psi}|_{\Omega_{1}}+\sup _{\mathfrak{X}}\left|\partial \Psi_{1}\right|_{\Omega_{1}}\right) .
$$

## 4. Solving the geodesic equation

In this section, we assume that the components of $D$ are smooth and disjoint.
4.1. Existence of the $C_{\beta}^{1,1}$ cone geodesic. In the present subsection we are dealing with the Dirichlet problem for the family of approximate geodesic equation (3.2). In order to apply the a priori estimates in Section 3 we require that the pair $\left(\Omega, \Omega_{1}\right)$ satisfies are $\left|\partial \log \tilde{\Omega}_{1}^{n+1}\right|,\left|\partial \log \frac{\Omega_{1}^{n+1}}{\Omega^{n+1}}\right|$ bounded and one of the following conditions

- $\left|\operatorname{Riem}\left(\Omega_{1}\right)\right|$ is bounded;
- $\inf \operatorname{Riem}\left(\Omega_{1}\right)$ and $\sup \operatorname{Riem}(\Omega)$ are bounded;
- $\sup \operatorname{Ric}\left(\Omega_{1}\right)$ and $\inf \operatorname{Riem}(\Omega)$ are bounded;
- $\inf \operatorname{Ric}\left(\Omega_{1}\right)$ and $|\operatorname{Riem}(\Omega)|$ are bounded.

Then we reduce these conditions to geometric conditions on the boundary potentials $\varphi_{0}$ and $\varphi_{1}$ as follows.

The boundedness of the connection of the background cone metric $\omega$ in (1.3) is computed in the following lemma for $0<\beta_{1}<\frac{2}{3}$. It was also computed for $0<\beta_{1}<\frac{1}{2}$ in Brendle 10 .

Lemma 4.1. The connection of $\omega$ is bounded for $0<\beta_{1}<\frac{2}{3}$ under the coordinate chart $\left\{w^{i}\right\}$.

Proof. Since there exists a smooth function $\rho$ such that $\delta|s|_{h_{\Lambda}}^{2 \beta_{1}}=\rho\left|z^{1}\right|^{2 \beta_{1}}$, we can rewrite (1.3) as

$$
\begin{aligned}
\omega & =\omega_{0}+\frac{\sqrt{-1}}{2}\left|z^{1}\right|^{2 \beta_{1}} \rho_{k \bar{l}} d z^{k} \wedge d z^{\bar{l}} \\
& +\frac{\sqrt{-1}}{2} \beta_{1}\left|z^{1}\right|^{2\left(\beta_{1}-1\right)}\left(z^{1} \rho_{k} d z^{k} \wedge d z^{\overline{1}}+z^{\overline{1}} \rho_{\bar{l}} d z^{1} \wedge d z^{\bar{l}}\right) \\
& +\frac{\sqrt{-1}}{2} \beta_{1}^{2} \rho\left|z^{1}\right|^{2\left(\beta_{1}-1\right)} d z^{1} \wedge d z^{\overline{1}}
\end{aligned}
$$

for $k, l$ from 2 to $n$. By means of the change of coordinates (2.1), as $w^{i}=\left|z^{i}\right|^{\beta_{1}-1} z^{i}$, we have, for $i \in\{1, \cdots, n\}$

$$
\frac{\partial w^{i}}{\partial z^{i}}=\frac{\beta_{i}+1}{2}\left|z^{i}\right|^{\beta_{i}-1} ; \frac{\partial w^{i}}{\partial z^{\bar{i}}}=\frac{\beta_{i}-1}{2}\left|z^{i}\right|^{\beta_{i}-3} z^{i} z^{i}
$$

Meanwhile,

$$
\frac{\partial z^{i}}{\partial w^{i}}=\frac{1+\beta_{i}}{2 \beta_{i}}\left|w^{i}\right|^{\frac{1-\beta_{i}}{\beta_{i}}} ; \frac{\partial z^{i}}{\partial w^{\bar{i}}}=\frac{1-\beta_{i}}{2 \beta_{i}}\left|w^{i}\right|^{\frac{1-3 \beta_{i}}{\beta_{i}}} w^{i} w^{i}
$$

The components of the model cone metrics under the variables $w^{i}$ rbecome

$$
\begin{aligned}
& \tilde{g}_{1 \overline{1}}=\left[\left(\frac{1+\beta_{1}}{2 \beta_{1}}\right)^{2}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}+\left(\frac{1-\beta_{1}}{2 \beta_{1}}\right)^{2}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}\right] g_{1 \overline{1}} \circ W^{-1} \\
&=\frac{1+\beta_{1}^{2}}{2 \beta_{1}^{2}}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}\left[g_{01 \overline{1}} \circ W^{-1}+\left|w^{1}\right|^{2} \rho_{1 \overline{1}}\right. \\
&\left.+\beta_{1}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}\left(\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1} w^{1} \rho_{1}+\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1} w^{\overline{1}} \rho_{\overline{1}}\right)+\beta_{1}^{2} \rho\left|w^{1}\right|^{2-\frac{2}{\beta_{1}}}\right] \\
&=\frac{1+\beta_{1}^{2}}{2 \beta_{1}^{2}}\left[g_{01 \overline{1}} \circ W^{-1}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}+\left|w^{1}\right|^{\frac{2}{\beta_{1}}} \rho_{1 \overline{1}}+\beta_{1}\left(w^{1} \rho_{1}+w^{\overline{1}} \rho_{\overline{1}}+\beta_{1}^{2} \rho\right)\right] \\
& \tilde{g}_{1 \bar{l}}=\frac{1+\beta_{1}}{2 \beta_{1}}\left[\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1} g_{01 \bar{l}} \circ W^{-1}+\left|w^{1}\right|^{\frac{1}{\beta_{1}}}+1\right. \\
&\left.\rho_{1 \bar{l}} \circ W^{-1}+\beta_{1} w^{1} \rho_{\bar{l}} \circ W^{-1}\right] \\
& \tilde{g}_{k \bar{l}}=g_{0 k \bar{l}} \circ W^{-1}+\left|w^{1}\right|^{2} \rho_{k \bar{l}} \circ W^{-1}
\end{aligned}
$$

Now, the connection of $\omega$ is the first derivative with respect to $w^{i}$. We check one by one. Note that $\rho$ is smooth on $w^{k}$ for $1 \leq k \leq n$.

$$
\begin{aligned}
& \frac{\partial}{\partial w^{1}} \tilde{g}_{1 \overline{1}}=O\left(\left|w^{1}\right|^{\frac{2}{\beta_{1}}-3}+\left|w^{1}\right|^{\frac{2}{\beta_{1}}-1}\right) ; \\
& \frac{\partial}{\partial w^{i}} \tilde{g}_{1 \overline{1}}=O(1) \\
& \frac{\partial}{\partial w^{i}} \tilde{g}_{1 \bar{l}}=O(1) \\
& \frac{\partial}{\partial w^{1}} \tilde{g}_{k \bar{l}}=\frac{\partial}{\partial w^{i}} \tilde{g}_{k \bar{l}}=O(1)
\end{aligned}
$$

Now let us check $\frac{\partial}{\partial w^{1}} \tilde{g}_{1 \bar{l}}$. It contains three terms. The first term is

$$
\begin{aligned}
& \frac{\partial}{\partial w^{1}}\left(\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1} g_{01 \bar{l}} \circ W^{-1}\right) \\
& =\frac{\partial}{\partial w^{1}}\left[\left(\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1}\left|w^{1}\right|\right)\left(\left|w^{1}\right|^{-1} g_{01 \bar{l}} \circ W^{-1}\right)\right]
\end{aligned}
$$

Since $g_{01 \bar{l}} \circ W^{-1}$ is also smooth and converges to zero as $w^{1}$ goes to zero, so this first term is $O\left(\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1}\right)$. The second and third term are both $O(1)$. Thus we conclude that when $0<\beta_{1}<\frac{2}{3}$, the connection is bounded.

As a corollary, we arrive at the boundedness of the connection of $\Omega_{1}$.
Corollary 4.2. When $0<\beta_{1}<\frac{2}{3}$ and $\varphi_{0}, \varphi_{1} \in C_{\beta}^{3}$, the connection of $\Omega_{1}$ is bounded.

Proof. From Lemma 4.1 and the expression of $\Omega$ in (2.8), we know the connection of $\Omega$ is bounded for $0<\beta_{1}<\frac{2}{3}$. Recall the formula (2.9) of $\Omega_{1}$; we have

$$
\begin{aligned}
\Omega_{1} & =t \omega_{\phi}+(1-t) \omega_{\varphi}+\frac{\sqrt{-1}}{2}\left(1+m \partial_{n+1} \partial_{\overline{n+1}} \Phi\right) d z^{n+1} \wedge d \bar{z}^{n+1} \\
& +\frac{1}{\sqrt{2}} \partial_{i}(\phi-\varphi) d z^{i} d z^{\frac{n+1}{n+1}}+\frac{1}{\sqrt{2}} \partial_{\bar{i}}(\phi-\varphi) d z^{\bar{i}} d z^{n+1}
\end{aligned}
$$

We have the the component of $\Omega_{1}$ to be for $2 \leq i, j \leq n$,

$$
\begin{aligned}
& \left(g_{1}\right)_{1 \overline{1}}=t\left(g_{\varphi_{0}}\right)_{1 \overline{1}}+(1-t)\left(g_{\varphi_{1}}\right)_{1 \overline{1}} ; \\
& \left(g_{1}\right)_{1 \bar{i}}=t\left(g_{\varphi_{0}}\right)_{1 \bar{i}}+(1-t)\left(g_{\varphi_{1}}\right)_{1 \bar{i}} ; \\
& \left(g_{1}\right)_{1 \overline{n+1}}=\partial_{1}\left(\varphi_{0}-\varphi_{1}\right) ; \\
& \left(g_{1}\right)_{i \bar{j}}=t\left(g_{\varphi_{0}}\right)_{i \bar{j}}+(1-t)\left(g_{\varphi_{1}}\right)_{i \bar{j}} ; \\
& \left(g_{1}\right)_{i \overline{n+1}}=\partial_{i}\left(\varphi_{0}-\varphi_{1}\right) ; \\
& \left(g_{1}\right)_{n+1 \overline{n+1}}=1+m \partial_{n+1} \partial_{\overline{n+1}} \Phi .
\end{aligned}
$$

Thus the corollary follows from $\varphi_{0}, \varphi_{1} \in C_{\beta}^{3}$.
Lemma 4.3. Suppose that $\varphi_{0}, \varphi_{1} \in C_{\beta}^{3}$ have curvature lower (upper) bound. Then $\Omega_{1}$ has also curvature lower (resp. upper) bound.
Proof. Since the formula of the bisectional curvature is

$$
R_{i \bar{j} k \bar{l}}=-\frac{\partial^{2} g_{i \bar{j}}}{\partial z^{k} \partial z^{\bar{l}}}+g^{p \bar{q}} \frac{\partial g_{p \bar{j}}}{\partial z^{\bar{l}}} \frac{\partial g_{i \bar{q}}}{\partial z^{k}}
$$

we have for $1 \leq i, j, k, l \leq n$ and $\phi=t \varphi_{1}+(1-t) \varphi_{0}$,

$$
\begin{aligned}
R_{i \bar{j} k \bar{l}}\left(g_{1}\right) & =t R_{i \bar{j} k \bar{l}}\left(g\left(\varphi_{1}\right)\right)+(1-t) R_{i \bar{j} k \bar{l}}\left(g\left(\varphi_{0}\right)\right) \\
& -t g\left(\varphi_{1}\right)^{p \bar{q}} \partial_{\bar{l}} g\left(\varphi_{1}\right)_{p \bar{j}} \partial_{k} g\left(\varphi_{1}\right)_{i \bar{q}} \\
& -(1-t) g\left(\varphi_{0}\right)^{p \bar{q}} \partial_{\bar{l}} g\left(\varphi_{0}\right)_{p \bar{j}} \partial_{k} g\left(\varphi_{0}\right)_{i \bar{q}} \\
& +\sum_{1 \leq p, q \leq n} g_{1}^{p \bar{q}} \partial_{\bar{l}} g(\phi)_{p \bar{j}} \partial_{k} g(\phi)_{i \bar{q}} \\
& +\sum_{1 \leq p \leq n} g_{1}^{p \overline{n+1}} \partial_{\bar{l}} g(\phi)_{p \bar{j} \bar{j}} \frac{1}{\sqrt{2}} \partial_{k} \partial_{i}\left[\varphi_{1}-\varphi_{0}\right] \\
& +\sum_{1 \leq q \leq n} g_{1}^{n+1 \bar{q}} \partial_{k} g(\phi)_{i \bar{q}} \frac{1}{\sqrt{2}} \partial_{\bar{l}} \partial_{\bar{j}}\left[\varphi_{1}-\varphi_{0}\right] \\
& +\frac{1}{2} g_{1}^{n+1 \overline{n+1}} \partial_{k} \partial_{i}\left[\varphi_{1}-\varphi_{0}\right] \partial_{\bar{l}} \partial_{\bar{j}}\left[\varphi_{1}-\varphi_{0}\right] .
\end{aligned}
$$

Also,

$$
\begin{aligned}
R_{i \bar{j} k \overline{n+1}}\left(g_{1}\right) & =-\partial_{k}\left(\varphi_{1}-\varphi_{0}\right)_{i \bar{j}} \\
& +\sum_{1 \leq p, q \leq n} g_{1}^{p \bar{q}}\left(\varphi_{1}-\varphi_{0}\right)_{p \bar{j}} \partial_{k} g(\phi)_{i \bar{q}} \\
& +g_{1}^{p \overline{n+1}}\left(\varphi_{1}-\varphi_{0}\right)_{p \bar{j}} \frac{1}{\sqrt{2}} \partial_{k} \partial_{i}\left[\varphi_{1}-\varphi_{0}\right] \\
R_{i \bar{j}(n+1) \overline{n+1}}\left(g_{1}\right) & =\sum_{1 \leq p, q \leq n} m g_{1}^{p \bar{q}}\left(\varphi_{1}-\varphi_{0}\right)_{p \bar{j}}\left(\varphi_{1}-\varphi_{0}\right)_{i \bar{q}} \\
R_{i \overline{n+1}(n+1) \overline{n+1}}\left(g_{1}\right) & =\sum_{q=1}^{n} m g_{1}^{n+1 \bar{q}} \bar{\partial}_{n+1} \partial_{n+1} \bar{\partial}_{n+1} \Psi\left(\varphi_{1}-\varphi_{0}\right)_{i \bar{q}} \\
R_{n+1 \overline{n+1}(n+1) \overline{n+1}}\left(g_{1}\right) & =-m \partial_{n+1} \bar{\partial}_{n+1} \partial_{n+1} \bar{\partial}_{n+1} \Psi \\
& +m^{2} g_{1}^{n+1 \overline{n+1}} \bar{\partial}_{n+1} \bar{\partial}_{n+1} \partial_{n+1} \Psi \partial_{n+1} \bar{\partial}_{n+1} \partial_{n+1} \Psi .
\end{aligned}
$$

The connection and the lower bound of the curvature of $\varphi_{0}$ and $\varphi_{1}$ are bounded. So the curvature of $\Omega_{1}$ is also bounded below. The upper bound follows in the same way.

Corollary 4.4. Suppose that $0<\beta_{1}<\frac{2}{3}, \varphi_{0}, \varphi_{1} \in C_{\beta}^{3}$ and their Ricci curvature have lower (upper) bound. Then the Ricci curvature of $\Omega_{1}$ also has lower (resp. upper) bound.
Proof. We use the formulas of the Riemannian curvature in Lemma 4.3, and we take the trace to obtain the Ricci curvature. Then the lemma follows directly.

Since $\inf \operatorname{Riem}\left(\Omega_{1}\right)$ is bounded for $0<\beta_{1}<\frac{1}{2}$ and $\sup \operatorname{Riem}\left(\Omega_{1}\right)$ is bounded for $0<\beta_{1}<1$ (c.f. [10] 42]), we introduce the following subspaces of Kähler cone metrics. When $0<\beta_{1}<\frac{1}{2}$, we define

$$
\begin{aligned}
\mathfrak{I}_{1} & :=\left\{\varphi \in \mathcal{H}_{\beta}^{3} \mid \sup \operatorname{Ric}\left(\omega_{\varphi}\right) \text { is bounded }\right\} \\
\mathfrak{I}_{2} & :=\left\{\varphi \in \mathcal{H}_{\beta}^{3} \mid \inf \operatorname{Ric}\left(\omega_{\varphi}\right) \text { is bounded }\right\}
\end{aligned}
$$

Theorem 4.5. Assume that two Kähler cone potentials $\varphi_{0}, \varphi_{1}$ are both in $\mathfrak{I}_{\mathfrak{i}} i=$ 1,2. Then they are connected by a $C_{\beta}^{1,1}$ cone geodesic.

Proof. Note that the right hand side of the equation is positive as long as $\tau$ is positive. When $\tau$ is zero, (3.1) provides a solution of the geodesic equation (2.6).

We denote the set of solvable times of (3.1) by

$$
I=\left\{\tau \in(0,1] \mid(3.1)_{\tau} \text { is solvable in } C_{\beta}^{2, \alpha}\right\}
$$

Automatically, $\Psi=\Psi_{1}$ satisfies the equation at $\tau=1$, so the set $I$ is not empty.
For any $0<\tau \leq 1$, assuming that $\omega\left(\tau_{0}\right)$ solves the equation (3.1), Proposition 5.19 provides a unique solution in $C_{\beta}^{2, \alpha}$ to the following linearized equation

$$
\begin{cases}\triangle_{\tau_{0}} v-v=f & \text { in } \mathfrak{M} \\ v=u & \text { on } \partial \mathfrak{X}\end{cases}
$$

for any $f \in C_{\beta}^{\alpha}$ and $u \in C_{\beta}^{2, \alpha}$. So the linearized operator at $\tau_{0}$ is invertible, and thus $I$ is open. So the solvable time can be extended beyond $\tau_{0}$.

The a priori estimates in Section 3, with one of the geometry conditions in $\mathfrak{I}_{1}$ or $\Im_{2}$ assures the uniform $C_{\beta}^{1,1}$ bound of $\varphi(t)$ which is independent of $\tau$. Two estimates in the next subsections improve $C_{\beta}^{2, \alpha}$ regularity of the solution of (3.1) before $\tau=0$. Thus, we could solve th approximation equation till $\tau=0$. With the uniform $C_{\beta}^{1,1}$ bound, after taking a subsequence $t_{i}$ we have a weak limit $\varphi=\lim _{t_{i} \rightarrow 0} \varphi\left(t_{i}\right)$ under a $C_{\beta}^{1, \alpha}$ norm. In Section 4.5, we prove the uniqueness of a weak solution. Hence the theorem is proved completely.
4.2. Interior Schauder estimate: $\tau>0$. We first prove the $C_{\beta}^{2, \alpha}$ estimate for a general equation.

$$
\begin{equation*}
\log \Omega_{\Psi}^{n+1}=\log \Omega^{n+1}+F \tag{4.1}
\end{equation*}
$$

Proposition 4.6. Assume that we have the second order estimate of $\Psi$. Then the following estimate holds for the solution of (4.1) on any small ball $B \subset \mathfrak{X}$

$$
\begin{equation*}
|\sqrt{-1} \partial \bar{\partial} \Psi|_{C_{\beta}^{\alpha}(B)} \leq C \tag{4.2}
\end{equation*}
$$

where $C$ depends on $\left|\partial \log \tilde{\Omega}^{n+1}\right|_{L^{q}},\left|\log \Omega^{n+1}\right|_{C_{\beta}^{\alpha}},|\partial \Psi|_{\infty},|\triangle \Psi|_{\infty},|\partial \tilde{F}|_{L^{q}},|F|_{C_{\beta}^{\alpha}}$, where $q>2 n+2$.

Proof. Choose a small ball $B_{d}(p)$ around $p$ in the interior of $\mathfrak{X}$. When $B_{d}(p)$ does not intersect $\mathfrak{D}$, this proposition follows directly from the standard Evans-Krylov estimate. So it's sufficient to fix a point $p \in \mathfrak{D}$. We consider (4.1) in $B_{d}(p)$. We consider it in a local holomorphic coordinate chart and we differentiate it in $B_{d}(p) \backslash \mathfrak{D}$. We fix the following piece of notation

$$
h:=\log \Omega^{n+1}+F
$$

So, we fix a $1 \leq k \leq n+1$ and, by taking $\frac{\partial}{\partial z^{k}}$ on both sides of (4.1) we get

$$
g^{\prime i \bar{j}}\left(g_{i \bar{j} k}+\Psi_{i \bar{j} k}\right)=h_{k} .
$$

Taking $\frac{\partial}{\partial z^{l}}$ on both sides of the above equation, we have

$$
-g^{\prime p \bar{j}} g^{\prime i \bar{q}}\left(g_{p \bar{q} \bar{l}}+\Psi_{p \bar{q} \bar{l}}\right)\left(g_{i \bar{j} k}+\Psi_{i \bar{j} k}\right)+g^{\prime i \bar{j}}\left(g_{i \bar{j} k \bar{l}}+\Psi_{i \bar{j} k \bar{l}}\right)=h_{k \bar{l}} .
$$

We introduce the notation $V:=g+\Psi$. Here $g$ is the local potential of $g_{i \bar{j}}$ in $B_{d}(p)$, then

$$
g^{\prime i \bar{j}} V_{k \bar{l} \bar{i} \bar{j}}=g^{\prime p \bar{j}} g^{\prime i \bar{q}} V_{p \bar{q} k} V_{i \bar{j} \bar{l}}+h_{k \bar{l}}
$$

Since this equation is not well-defined along $\mathfrak{D}$, we choose inverse of the flat metric $g^{k \bar{l}}(1.2)$ as the weighted function $\sigma^{k \bar{l}}$, and we consider $g^{\prime i \bar{j}}\left(\sigma^{k \bar{l}} V_{k \bar{l}}\right)_{i \bar{j}}$. We have

$$
\triangle^{\prime}\left(g^{k \bar{l}} V_{k \bar{l}}\right)=g^{\prime i \bar{j}}\left(R_{i \bar{j}}^{k \bar{l}} V_{k \bar{l}}+g^{k \bar{l}} V_{k \bar{l} \bar{j}}\right)
$$

Now given any direction $\eta \in \mathbb{C}^{n+1}$, with $|\eta|=1$, we denote $\partial_{\eta}:=\sum_{k} \eta^{k} \frac{\partial}{\partial z^{k}}$. Also, we set $V_{\eta \bar{\eta}}:=\partial_{\eta \bar{\eta}}^{2} V=\sum_{k, l} \eta^{k} \eta^{\bar{l}} \frac{\partial}{\partial z^{k}} \frac{\partial}{\partial z^{l}} V$. We then define $u_{\eta}:=\sum_{k, l} \eta^{k} \eta^{\bar{l}} \sigma^{k \bar{l}} V_{k \bar{l}}$. We have

$$
\triangle^{\prime}\left(u_{\eta}\right) \geq \sum_{k, l} \eta^{k} \eta^{\bar{l}} \sigma^{k \bar{l}} h_{k \bar{l}}
$$

where we use that the flat cone metric has flat curvature under the coordinate $w^{i}$.
We denote $\tilde{h}_{\bar{l}}:=g^{k \bar{l}} \tilde{h}_{k}$ on the coordinate chat $\left\{w^{i}\right\}$. Let us now introduce the following symbols. We denote

$$
M_{s \eta}:=\sup _{B_{s d}(p)} u_{\eta}, \quad m_{s \eta}:=\inf _{B_{s d}(p)} u_{\eta} .
$$

Applying Proposition 5.11 (weak Hanack inequality) to $M_{2 \eta}-u_{\eta}$, we have that there exists a $q>2 n+2$ such that

$$
\begin{equation*}
\left\{d^{-2 n-2} \int_{B_{d}(p)}\left(M_{2 \eta}-u_{\eta}\right)^{p} \Omega^{n+1}\right\}^{\frac{1}{p}} \leq C\left\{M_{2 \eta}-M_{\eta}+K\right\} \tag{4.3}
\end{equation*}
$$

Here

$$
K:=d^{1-\frac{2 n+2}{q}}\|\partial \tilde{h}\|_{q}
$$

and

$$
\|\partial \tilde{h}\|_{q}=\left\|\partial \log \tilde{\Omega}^{n+1}+\partial \tilde{F}\right\|_{q}
$$

In order to obtain the inverse inequality for $u_{\eta}-m_{2 \eta}$ we use the concavity of the Monge-Ampère operator. Fix any two points $Q_{2} \in B_{2 d}(p)$ and $Q_{1} \in B_{d}(p)$, without loss of generality, we assume the distance from $Q_{2}$ to $\mathfrak{D}$ is longer than $Q_{1}$ to $\mathfrak{D}$. From the formula of the flat metric (1.2), we see that $g^{i \bar{j}}\left(Q_{2}\right)>g^{i \bar{j}}\left(Q_{1}\right)$. From the equation (4.1) we have, writing $g^{\prime}(t):=(1-t) g^{\prime}\left(Q_{2}\right)+t g^{\prime}\left(Q_{1}\right)$, and $a^{i \bar{j}}=\int_{0}^{1} g^{\prime i \bar{j}}(t) d t$, the expression

$$
\begin{align*}
& h\left(Q_{1}\right)-h\left(Q_{2}\right)=\log \operatorname{det}\left(g_{i \bar{j}}^{\prime}\left(Q_{1}\right)\right)-\log \operatorname{det}\left(g_{i \bar{j}}^{\prime}\left(Q_{2}\right)\right) \\
& =\int_{0}^{1} g^{\prime}(t)^{i \bar{j}} d t\left(V\left(Q_{1}\right)-V\left(Q_{2}\right)\right)_{i \bar{j}}=a^{i \bar{j}}\left(V\left(Q_{1}\right)-V\left(Q_{2}\right)\right)_{i \bar{j}} \tag{4.4}
\end{align*}
$$

Now, for $1 \leq i, j \leq n+1$ we define

$$
\tilde{a}^{i \bar{j}}:=\frac{a^{i \bar{j}}}{g^{i \bar{j}}\left(Q_{2}\right)} .
$$

We have (since $g^{\prime}(t)$ is $L^{\infty}$-equivalent to $g$, for $1 \leq i, j \leq n+1$ ) that the matrix $\tilde{a}^{i \bar{j}}$ is positive definite and its eigenvalues range between the positive constants $\lambda$ and $\Lambda$. Thus, we can apply Lemma 17.13 in (33] (see also Section (4.3) in [57);
we get that there exists a finite set of unit vectors $\gamma_{1}, \cdots, \gamma_{N} \in \mathbb{C}^{n+1}$ and positive numbers $\lambda^{*}, \Lambda^{*}$ depending only on $n, \lambda, \Lambda$ such that the matrix $\tilde{a}^{i \bar{j}}$ can be written as

$$
\tilde{a}^{i \bar{j}}=\sum_{\nu=1}^{N} b_{\nu} \gamma_{\nu i} \gamma_{\nu \bar{j}}
$$

Here $\lambda^{*} \leq b_{\nu} \leq \Lambda^{*}$ for any $1 \leq \nu \leq N$. As a result, we can express the matrix $a^{i \bar{j}}$ in terms of $b_{\nu}$ and the vectors $\gamma_{\nu}$. Thus, we continue from (4.4) and we write

$$
\begin{aligned}
& h\left(Q_{1}\right)-h\left(Q_{2}\right)=g^{i \bar{j}}\left(Q_{2}\right) \tilde{a}^{i \bar{j}}\left(V\left(Q_{1}\right)-V\left(Q_{2}\right)\right)_{i \bar{j}} \\
& =\sum_{\nu=1}^{N} b_{\nu} g^{i \bar{j}}\left(Q_{2}\right) \gamma_{\nu i} \gamma_{\nu \bar{j}}\left(V\left(Q_{1}\right)-V\left(Q_{2}\right)\right)_{i \bar{j}} \geq C \sum_{\nu=1}^{N} b_{\nu}\left(u_{\gamma_{\nu}}\left(Q_{1}\right)-u_{\gamma_{\nu}}\left(Q_{2}\right)\right),
\end{aligned}
$$

where we used that the matrix $V_{i \bar{j}}$ is positive-definite and $g^{i \bar{j}}\left(Q_{2}\right) \geq g^{i \bar{j}}\left(Q_{1}\right)$. We conclude that for a fixed $1 \leq l \leq N$

$$
\begin{equation*}
C b_{l}\left(u_{\gamma_{l}}\left(Q_{1}\right)-u_{\gamma_{l}}\left(Q_{2}\right)\right) \leq h\left(Q_{1}\right)-h\left(Q_{2}\right)+C \sum_{\nu \neq l} b_{\nu}\left(u_{\gamma_{\nu}}\left(Q_{2}\right)-u_{\gamma_{\nu}}\left(Q_{1}\right)\right) \tag{4.5}
\end{equation*}
$$

We now fix $1 \leq \nu \leq N, s=1,2$ and we denote

$$
w(s d):=\sum_{\nu=1}^{N} \operatorname{Osc}_{B_{s d}(p)} u_{\gamma_{\nu}}
$$

From (4.5), since $Q_{1} \in B_{d}(p)$ and $Q_{2} \in B_{2 d}(p)$ we get

$$
u_{\gamma_{l}}\left(Q_{1}\right)-m_{2 l} \leq C\left\{d^{\alpha}|h|_{C_{\beta}^{\alpha}}+\sum_{\nu \neq l}\left(M_{2 \gamma_{\nu}}-u_{\gamma_{\nu}}\left(Q_{1}\right)\right)\right\} .
$$

Applying the inequality (4.3), we have

$$
\begin{align*}
& \left\{d^{-2 n-2} \int_{B_{d}(p)}\left(\sum_{\nu \neq l} M_{2 \gamma_{\nu}}-u_{\gamma_{\nu}}\right)^{p} \Omega^{n+1}\right\}^{\frac{1}{p}} \\
& \leq N^{\frac{1}{p}} \sum_{\nu \neq l}\left\{d^{-2 n-2} \int_{B_{d}(p)}\left(M_{2 \gamma_{\nu}}-u_{\gamma_{\nu}}\right)^{p} \Omega^{n+1}\right\}^{\frac{1}{p}} \\
& \leq C\left\{\sum_{\nu \neq l}\left(M_{2 \gamma_{\nu}}-M_{\gamma_{\nu}}\right)+K\right\} \\
& \leq C\{w(2 d)-w(d)+K\} \tag{4.6}
\end{align*}
$$

which entails, by integrating of $Q_{1}$ on $B_{d}(p)$ with respect to $\Omega$ and using (4.6)

$$
\begin{align*}
& \left\{d^{-2 n-2} \int_{B_{d}(p)}\left(u_{\gamma_{l}}\left(Q_{1}\right)-m_{2 l}\right)^{p} \Omega^{n+1}\right\}^{\frac{1}{p}} \\
& \quad \leq C\left\{d^{\alpha}|h|_{C_{\beta}^{\alpha}}+w(2 d)-w(d)+K\right\} \tag{4.7}
\end{align*}
$$

Now, we combine (4.6) and (4.7) to obtain

$$
w(2 d) \leq C\left\{d^{\alpha}|h|_{C_{\beta}^{\alpha}}+w(2 d)-w(d)+K\right\}
$$

where at the last inequality we used (4.3) and (4.7). Let us compute that $|h|_{C_{\beta}^{\alpha}}=$ $\left|F+\log \Omega^{n+1}\right|_{C_{\beta}^{\alpha}}$.

Then, using the Iteration Lemma 8.23 in [33], we have $u_{\eta} \in C_{\beta}^{\alpha}$, for all $\eta \in \mathbb{C}^{n+1}$. So $\Delta V \in C_{\beta}^{\alpha}$ and $V \in C_{\beta}^{2, \alpha}$ follows from Proposition 5.18. This gives (4.2) and completes the proof of the proposition.

In conclusion, we obtain the conical Evans-Krylov estimate of the geodesic equation (3.1).
Proposition 4.7. Assume $0<\beta_{1}<\frac{2}{3}$ and that $\varphi_{0}, \varphi_{1}$ are in $\mathfrak{I}_{\mathfrak{i}}, i=1,2,3$. Then the $C_{\beta}^{1,1}$ solution $\Psi$ of the approximate geodesic equation (3.1) belongs to $C_{\beta}^{2, \alpha}$ in the interior of $\mathfrak{X}$.
Proof. Considering the geodesic equation (3.1), then $F=\log \tau+\log \frac{\Omega_{1}^{n+1}}{\Omega^{n+1}}+\Psi-\Psi_{1}$. Since $\Omega \in C_{\beta}^{\alpha}$, we have $\log \Omega^{n+1} \in C_{\beta}^{\alpha}$. Moreover, $\varphi_{0}, \varphi_{1} \in C_{\beta}^{2, \alpha}$, so $\log \Omega_{1}^{n+1} \in C_{\beta}^{\alpha}$. Thus we have $F \in C_{\beta}^{\alpha}$. When $0<\beta_{1}<\frac{2}{3}$, Lemma4.1, Lemma4.2 and $\varphi_{0}, \varphi_{1} \in C_{\beta}^{3}$ imply that $\partial \tilde{F}$ is bounded.

Our argument presented above follows Evans-Krylov's estimate 31 32 44. We also used Blocki's observation in [7] that $F$ belongs to $W^{1, q}$ is sufficient to the estimate. In our problem, since $V_{k \bar{l}}$ is singular along the direction which is perpendicular to $\mathfrak{D}$, we multiply with the weight. In the next Section, we will develope the linear theory including the weak Hanack inequality for the linear equation and with cone coefficient which is used in the proof above.
4.3. An application to the Kähler-Einstein cone metrics. Now we state an application of our estimate to the Kähler-Einstein metric on $(X, \omega)$ with cone singularities. We first assume the divisor has only one component. I.e. $D=$ $\left(1-\beta_{1}\right) V$. As usual, we assume that $z^{1}$ is the defining function of the hyper surface $V$. The Kähler-Einstein cone metric satisfies for a real number $\lambda$,

$$
\operatorname{Ric}\left(\omega_{\varphi}\right)=\lambda \omega_{\varphi}+2 \pi[D]
$$

This equation implies the cohomology relation

$$
c_{1}(M)=\lambda \Omega+c_{1}\left(L_{D}\right)
$$

Here $L_{D}$ is the corresponding line bundle of $[D]$. Since $\omega_{0}$ is a smooth Kähler metric in $\Omega$, there exists a smooth function $f_{0}$ such that

$$
\operatorname{Ric}\left(\omega_{0}\right)-\lambda \omega_{0}+i \partial \bar{\partial} \log |s|^{2\left(1-\beta_{1}\right)}=i \partial \bar{\partial} f_{0}
$$

Thus we have

$$
\begin{aligned}
\operatorname{Ric}(\omega)-\lambda \omega & =\operatorname{Ric}(\omega)-\operatorname{Ric}\left(\omega_{0}\right)-\lambda\left(\omega-\omega_{0}\right)+\operatorname{Ric}\left(\omega_{0}\right)-\lambda \omega_{0} \\
& =i \partial \bar{\partial} f
\end{aligned}
$$

In which

$$
f=-\log \left(\frac{\omega^{n}}{\omega_{0}^{n}}|s|^{2\left(1-\beta_{1}\right)}\right)-\lambda \delta|s|^{2 \beta_{1}}+f_{0}
$$

Thus the Kähler-Einstein cone metric satisfies

$$
\begin{equation*}
\log \omega_{\varphi}^{n}=\log \omega^{n}-\lambda \varphi+f=F \tag{4.8}
\end{equation*}
$$

When $\lambda$ is nonpositive, the continuity path is

$$
\begin{equation*}
\log \omega_{\varphi}^{n}=\log \omega^{n}-\lambda \varphi+t f \tag{4.9}
\end{equation*}
$$

While when the $\lambda$ is positive, i.e. the Fano case, the Aubin path is

$$
\begin{equation*}
\log \omega_{\varphi}^{n}=\log \omega^{n}-\lambda t \varphi+f \tag{4.10}
\end{equation*}
$$

When we solve this equation by the continuity method, we need to derive the a priori $C_{\beta}^{2, \alpha}$ estimate as following.

Proposition 4.8. Assume that the solutions of (4.9) and (4.10) have up to the second order estimate and $0<\beta_{1}<\frac{2}{3}$. Then the following estimate holds on any small ball $B \subset \mathfrak{X}$

$$
\begin{equation*}
\varphi \in C_{\beta}^{2, \alpha}(B) \tag{4.11}
\end{equation*}
$$

Proof. Applying the proposition above with dimension $n$, it suffices to check $\left|\partial \log \tilde{\omega}^{n}\right|_{L^{q}}$, $\left|\log \omega^{n}\right|_{C_{\beta}^{\alpha}},|\partial \tilde{F}|_{L^{q}},|F|_{C_{\beta}^{\alpha}}$. Since $\omega \in C_{\beta}^{2, \alpha}$, so we have $\log \omega^{n} \in C_{\beta}^{\alpha}$. The proof of Lemma 4.1 implies that when $\left(\frac{2}{\beta_{1}}-3\right) q+2 \beta_{1}>0,\left|\partial \log \omega^{n}\right|_{L^{q}}$ is bounded. Thus the result follows from the next lemma.

Lemma 4.9. $|\partial f|_{\omega}$ is bounded when $0<\beta_{1}<\frac{2}{3}$.
Proof. In local coordinate, we have $f=-\log \left[\omega^{n}|s|^{2\left(1-\beta_{1}\right)}\right]+\log \omega_{0}^{n}-\lambda \delta|s|^{2 \beta_{1}}+f_{0}$. Note that $\omega_{0}$ and $f_{0}$ are both smooth. Moreover, $|s|^{2 \beta_{1}}=\rho\left|z^{1}\right|^{2 \beta_{1}}=\rho \circ W^{-1} \cdot\left|w^{1}\right|^{2}$, so its first derivative is bounded. It remains to verify that the first derivative of $\log \left(\omega^{n}|s|^{2\left(1-\beta_{1}\right)}\right)$ with respect to $\omega$ is bounded. Since $\omega^{n}|s|^{2\left(1-\beta_{1}\right)}$ is positive and bounded, it suffices to prove that $\left|\partial\left(\omega^{n}|s|^{2\left(1-\beta_{1}\right)}\right)\right|_{\omega}$ is bounded. Put the weight into the matrix $\omega$, we have a new metric $\omega_{1}$,

$$
\begin{aligned}
\frac{2}{i} \omega_{1} & =|s|^{2\left(1-\beta_{1}\right)}\left(g_{0}\right)_{1 \overline{1}} d z^{1} \wedge d z^{\overline{1}}+\left(g_{0}\right)_{k \bar{l}} d z^{k} \wedge d z^{\bar{l}} \\
& +|s|^{\left(1-\beta_{1}\right)}\left(g_{0}\right)_{k \overline{1}} d z^{k} \wedge d z^{\overline{1}}+|s|^{\left(1-\beta_{1}\right)}\left(g_{0}\right)_{1 \bar{l}} d z^{1} \wedge d z^{\bar{l}} \\
& +\left|z^{1}\right|^{2 \beta_{1}} \rho_{k \bar{l}} d z^{k} \wedge d z^{\bar{l}} \\
& +|s|^{\left(1-\beta_{1}\right)} \beta_{1}\left|z^{1}\right|^{2\left(\beta_{1}-1\right)}\left(z^{1} \rho_{k} d z^{k} \wedge d z^{\overline{1}}+z^{\overline{1}} \rho_{\bar{l}} d z^{1} \wedge d z^{\bar{l}}\right) \\
& +|s|^{2\left(1-\beta_{1}\right)} \beta_{1}^{2} \rho\left|z^{1}\right|^{2\left(\beta_{1}-1\right)} d z^{1} \wedge d z^{\overline{1}}
\end{aligned}
$$

for $k, l$ from 2 to $n$. The components of $\omega_{1}$ under the variables $w^{i}$ become

$$
\begin{aligned}
& \tilde{g}_{1 \overline{1}}=\frac{1+\beta_{1}^{2}}{2 \beta_{1}^{2}} \rho^{\frac{1-\beta_{1}}{\beta_{1}}}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}\left[g_{01 \overline{1}} \circ W^{-1}\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2}+\left|w^{1}\right|^{\frac{2}{\beta_{1}}} \rho_{1 \overline{1}}+\beta_{1}\left(w^{1} \rho_{1}+w^{\overline{1}} \rho_{\overline{1}}+\beta_{1}^{2} \rho\right)\right] \\
& \tilde{g}_{1 \bar{l}}=\frac{1+\beta_{1}}{2 \beta_{1}} \rho^{\frac{1-\beta_{1}}{2 \beta_{1}}}\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1}\left[\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1} g_{01 \bar{l}} \circ W^{-1}+\left|w^{1}\right|^{\frac{1}{\beta_{1}}+1} \rho_{1 \bar{l}} \circ W^{-1}+\beta_{1} w^{1} \rho_{\bar{l}} \circ W^{-1}\right] \\
& \tilde{g}_{k \bar{l}}=g_{0 k \bar{l}} \circ W^{-1}+\left|w^{1}\right|^{2} \rho_{k \bar{l}} \circ W^{-1}
\end{aligned}
$$

Now, we check one by one the first derivative with respect to $w^{i}$. The first derivative of $\tilde{g}_{k \bar{l}}$ follows from Lemma 4.1. Note that $\rho$ is smooth on $w^{k}$ for $1 \leq k \leq n$.

$$
\begin{aligned}
& \frac{\partial}{\partial w^{1}} \tilde{g}_{1 \overline{1}}=O\left(\left|w^{1}\right|^{\frac{4}{\beta_{1}}-5}+\left|w^{1}\right|^{\frac{2}{\beta_{1}}-3}\right) \\
& \frac{\partial}{\partial w^{i}} \tilde{g}_{1 \overline{1}}=\frac{\partial}{\partial w^{i}} \tilde{g}_{1 \bar{l}}=O(1)
\end{aligned}
$$

Now let us check $\frac{\partial}{\partial w^{1}} \tilde{g}_{1 \bar{l}}$. It contains three terms. The first term is

$$
\begin{aligned}
& \frac{\partial}{\partial w^{1}}\left(\left|w^{1}\right|^{\frac{2}{\beta_{1}}-2} g_{01 \bar{l}} \circ W^{-1}\right) \\
& =\frac{\partial}{\partial w^{1}}\left[\left(\left|w^{1}\right|^{\frac{2}{\beta_{1}}-1}\left|w^{1}\right|\right)\left(\left|w^{1}\right|^{-1} g_{01 \bar{l}} \circ W^{-1}\right)\right] .
\end{aligned}
$$

Since $g_{01 \bar{l} \circ} \circ W^{-1}$ is also smooth and converges to zero as $w^{1}$ goes to zero, so the growth rate of this term is $O\left(\left|w^{1}\right|^{\frac{1}{\beta_{1}}-1}\right)$. The second and third term are both $O(1)$. Thus this lemmas follows.
4.4. Boundary Schauder estimate: $\tau>0$. We adapt Krylov's method 44] (also c.f. [33]) for the boundary estimate to our cone case. We notice that the linear equation is of divergence form, so the Harnack inequality and maximum principle proved in the next section can be applied here. The boundary of $\mathfrak{X}$ is $X \times \partial R$, which is a manifold with $2 n+1$ real dimension. Under the local coordinate $z^{i}=x^{n+1}+i y^{n+1}$, the boundary is defined by $x^{n+1}=0$. Denote $x^{\prime}=$ $\left\{x^{1}, y^{1}, \cdots, x^{n}, y^{n}, y^{n+1}\right\}$.

Proposition 4.10. Assume $0<\beta_{1}<\frac{2}{3}$ and that $\varphi_{0}, \varphi_{1}$ are in $\mathfrak{I}_{\mathfrak{i}}, i=1,2,3$. Then the $C_{\beta}^{1,1}$ solution $\Psi$ of the approximate geodesic equation (3.1) belongs to $C_{\beta}^{2, \alpha}$ on the boundary of $\mathfrak{X}$.

Proof. Recall the approximate geodesic equation is

$$
\begin{cases}\log \operatorname{det}\left(\Omega_{\Psi_{1} i \bar{j}}+\tilde{\Psi}_{i \bar{j}}\right)=h=\log \tau+\tilde{\Psi}+\log \operatorname{det}\left(\Omega_{\Psi_{1} i \bar{j}}\right) & \text { in } \mathfrak{M}  \tag{4.12}\\ \tilde{\Psi}(z)=0 & \text { on } \partial \mathfrak{X}\end{cases}
$$

We first see that the tangent-tangent direction of the boundary estimate equals to the same estimate of the boundary values. Then the normal-normal estimate follows from the approximate geodesic equation

$$
\left[\varphi^{\prime \prime}-\left(\partial \varphi^{\prime}, \partial \varphi^{\prime}\right)_{g_{\varphi}}\right] \operatorname{det} \omega_{\varphi}=\Omega_{\Psi}^{n+1}=\tau e^{\Psi-\Psi_{1}} \operatorname{det}\left(\Omega_{1 i \bar{j}}\right)
$$

with the estimates of the tangent-normal direction and the tangent-tangent direction. We differentiate (4.1) with respect to $\partial_{k}$ for a fixed $k \in 1, \cdots, n$, and we get

$$
\triangle^{\prime} \tilde{\Psi}_{k}=h_{k}-g_{\Psi}^{i \bar{j}} g\left(\Psi_{1}\right)_{i \bar{j} k}
$$

We use the flat metric as the weighted metric to derive the differential equation of $u=\sqrt{g^{k k}} \tilde{\Psi}_{k}$. Then we obtain that $u$ satisfies

$$
\triangle^{\prime} u=\sqrt{g^{k \bar{k}}}\left(h_{k}-g_{\Psi}^{i \bar{j}} g\left(\Psi_{1}\right)_{i \bar{j} k}\right)
$$

We denote the right hand side as $f$. According to Lemma 4.2, $f$ is bounded when $0<\beta_{1}<\frac{2}{3}$ and $\varphi_{0}, \varphi_{1} \in C_{\beta}^{3}$. Note that $u$ vanishes on the boundary $\partial \mathfrak{X}$. We fix a point $p$ on the boundary, and we take coordinates $z^{i}$ centered at $p$. We introduce
the following domains for a small radius $d$.

$$
\begin{aligned}
\left|x^{\prime}\right|_{\beta_{1}}^{2} & =\left|z^{1}\right|^{2 \beta_{1}}+\sum_{i=2}^{n}\left|z^{i}\right|^{2}+\left|y^{n+1}\right|^{2}, B_{d}(p)=\left\{z \in M| | z-\left.p\right|_{\beta_{1}} \leq d\right\} \\
B_{1} & =B_{d}(p) \times\left\{x^{n+1}\left|0 \leq\left|x^{n+1}\right| \leq \delta d, x^{n+1} \geq 0\right\}\right. \\
B_{1}^{3} & =B_{d}(p) \times\left\{x^{n+1}\left|\delta d \leq\left|x^{n+1}\right| \leq 3 \delta d, x^{n+1} \geq 0\right\}\right. \\
S_{2} & =B_{d}(p) \times\left\{\left|x^{n+1}\right|=2 \delta d, x^{n+1} \geq 0\right\} \\
B_{2} & =B_{2 d}(p) \times\left\{x^{n+1}\left|0 \leq\left|x^{n+1}\right| \leq 2 \delta d, x^{n+1} \geq 0\right\}\right. \\
B_{4} & =B_{4 d}(p) \times\left\{x^{n+1}\left|0 \leq\left|x^{n+1}\right| \leq 4 \delta d, x^{n+1} \geq 0\right\}\right.
\end{aligned}
$$

Here, $\delta \ll 1$ is a small positive constant such that $v:=\frac{u}{x^{n+1}}$ is strictly positive on $S_{2}$. We assume that $v$ is nonnegative on $B_{4}$; then $u \geq 0$.

We use the barrier function

$$
w=\left[\left(4-\frac{\left|x^{\prime}\right|_{\beta_{1}}^{2}}{d^{2}}\right) \inf _{S_{2}} v+(1+d \sup |f|) \frac{\frac{x^{n+1}}{2 d}-\delta}{\sqrt{\delta}}\right] x^{n+1}
$$

We first prove that on the boundary of $B_{2}, w \leq u$. On $\left|x^{n+1}\right|=2 \delta d$, we have $w \leq 4 x^{n+1} \inf _{S_{2}} v \leq u$; on $\left|x^{n+1}\right|=0$, we have $w=0 \leq u$; on $\left|x^{\prime}\right|_{\beta_{1}}^{2}=2 d$, $w \leq 0 \leq u$. Then, in $B_{2}$ we compute $\triangle^{\prime} w=-\frac{\inf _{S_{2}} v}{d^{2}} x^{n+1}+(1+d \sup |f|) \frac{1}{2 d \sqrt{\delta}} \geq f$. According to the maximum principle Lemma 5.1. we have $w \leq u$ on $B_{2}$. As a result, we obtain in $B_{1}$,

$$
\begin{align*}
v & \geq\left(4-\frac{\left|x^{\prime}\right|_{\beta_{1}}^{2}}{d^{2}}\right) \inf _{S_{2}} v+(1+d \sup |f|) \frac{\frac{x^{n+1}}{2 d}-\delta}{\sqrt{\delta}} \\
& \geq 2 \inf _{S_{2}} v-d \sup |f| \tag{4.13}
\end{align*}
$$

Note that $\delta$ only needs to be an arbitrarily small constant.
Now, notice that $\triangle^{\prime} u$ is of the divergence form, we could apply the interior Harnack inequality (Proposition 5.12) to $\triangle^{\prime} u=f$ on $B_{1}^{3}$; since now $\frac{u}{3 \delta d} \leq v \leq \frac{u}{\delta d}$ we obtain

$$
\sup _{B_{1}^{3}} v \leq C\left(\inf _{B_{1}^{3}} v+\sup |f|\right)
$$

Here $C$ depends on $\omega$. Since $\inf _{B_{1}^{3}} v \leq \inf _{S_{2}} v$, using (4.13), we have

$$
\begin{equation*}
\sup _{B_{1}^{3}} v \leq C\left(\inf _{B_{1}} v+d \sup |f|\right) \tag{4.14}
\end{equation*}
$$

Replacing in the former arguments, $v$ by $v-\inf _{B_{4}} v$ and then by $\sup _{B_{4}} v-v$, noticing that they are both positive, and finally adding the resulting inequalities (4.14), we arrive at the following inequality,

$$
\operatorname{Osc}_{B_{1}} v \leq \frac{C-1}{C} \operatorname{Osc}_{B_{4}} v+2 d \sup |f|
$$

Then by the iteration Lemma 8.23 in [33], we have the Hölder estimate of $v$ for any $d \leq d_{0}$,

$$
\operatorname{Osc}_{B_{d}} v \leq C \frac{d^{\alpha}}{d_{0}^{\alpha}}\left(\operatorname{Osc}_{B_{d_{0}}} v+d_{0} \sup |f|\right)
$$

For any $q$ in $\mathfrak{X}$, choose $d=|p-q|_{\beta_{1}}$ and $d_{0}=\operatorname{diam}(\mathfrak{X})$, we obtain the Hölder continuity of $v$ as

$$
\frac{|v(p)-v(q)|}{|p-q|_{\beta_{1}}^{\alpha}} \leq C\left(d_{0}^{-\alpha} \sup _{B_{d_{0}}}|v|+d_{0} \sup |f|\right)
$$

Since $u$ vanishes on the boundary and depends trivially on the variable $y^{n+1}$, we have $\partial_{z^{n+1}} u$ is $C_{\beta}^{\alpha}$. Thus the proposition is proved.
4.5. Uniqueness of the $C_{\beta}^{1,1}$ cone geodesic. In Theorem4.5, we have obtained the existence of a $C_{\beta}^{1,1}$ cone geodesic. Our present goal is to prove its uniqueness. Suppose that $\Phi_{i}$ for $i=1,2$ are two cone geodesic segments, which correspond to the solutions $\Psi_{\tau_{i}} \in C_{\beta}^{2, \alpha}$ of

$$
\begin{cases}\frac{\operatorname{det}\left(\Omega_{\Psi_{i}}\right)}{\operatorname{det}\left(\Omega_{1}\right)}=\tau_{i} e^{a\left(\Psi_{\tau_{i}}-\Psi_{1}\right)} & \text { in } \mathfrak{M} \\ \Psi_{\tau_{i}}=\Psi_{0 i} & \text { on } \partial \mathfrak{X}\end{cases}
$$

for $i=1,2$ and $\tau_{i} \in[0,1]$. Since $\Psi_{\tau_{i}} \rightarrow \Psi_{i}$ in $C_{\beta}^{1, \alpha}$ as $\tau_{i} \rightarrow 0$, then for any $\epsilon>0$ we can find two values $\tau_{1}, \tau_{2}$ such that

$$
\sup _{\mathfrak{X}}\left|\Psi_{i}-\Psi_{\tau_{i}}\right| \leq \epsilon .
$$

So, we compute

$$
\log \operatorname{det}\left(\Omega_{\Psi_{\tau_{1}}}\right)-\log \operatorname{det}\left(\Omega_{\Psi_{\tau_{2}}}\right)=\int_{0}^{1} g_{t}^{i \bar{j}} d t\left(\Psi_{\tau_{1}}-\Psi_{\tau_{2}}\right)_{i \bar{j}}>a\left(\Psi_{\tau_{1}}-\Psi_{\tau_{2}}\right)
$$

where $g_{t}=t g_{\Psi_{\tau_{1}}}+(1-t) g_{\Psi_{\tau_{2}}}$ and $a \geq 0$. Now, applying Lemma 5.5 we have,

$$
\sup _{\mathfrak{X}}\left(\Psi_{\tau_{1}}-\Psi_{\tau_{2}}\right) \leq \sup _{\partial \mathfrak{X}}\left(\Psi_{01}-\Psi_{02}\right) .
$$

So we have

$$
\begin{aligned}
\sup _{\mathfrak{X}}\left(\Psi_{1}-\Psi_{2}\right) & \leq \sup _{\mathfrak{X}}\left(\Psi_{\tau_{1}}-\Psi_{1}\right)+\sup _{\mathfrak{X}}\left(-\Psi_{\tau_{2}}+\Psi_{\tau_{1}}\right)+\sup _{\mathfrak{X}}\left(\Psi_{\tau_{2}}-\Psi_{2}\right) \\
& \leq 2 \epsilon+\sup _{\partial \mathfrak{X}}\left(\Psi_{01}-\Psi_{02}\right) .
\end{aligned}
$$

Then, switching $\Psi_{1}$ and $\Psi_{2}$ and letting $\epsilon \rightarrow 0$, we end up with

$$
\sup _{\mathfrak{X}}\left|\Psi_{1}-\Psi_{2}\right| \leq \sup _{\partial \tilde{X}}\left|\Psi_{01}-\Psi_{02}\right| .
$$

The above inequality proves the uniqueness of a cone geodesic segment with prescribed boundary values.

## 5. Linearized equation

In this section we consider the general linear elliptic equation

$$
\left\{\begin{align*}
L v & =g^{i \bar{j}} v_{i \bar{j}}+b^{i} v_{i}+c v=f+\partial_{i} h^{i}  \tag{5.1}\\
v & =v_{0}
\end{align*}\right.
$$

in the space $(\mathfrak{X}, \mathfrak{D})$ defined in Section 2 Here $g^{i \bar{j}}$ is the inverse matrix of a Kähler cone metric $\Omega$ in $H_{\beta}^{2, \alpha}$. Moreover, we are given the following datas.

$$
\begin{equation*}
b^{i}, h^{i} \in C_{\beta}^{1, \alpha} ; c, f \in C_{\beta}^{\alpha} \text { and } v_{0} \in C_{\beta}^{2, \alpha} \tag{5.2}
\end{equation*}
$$

This type of equation has been studied via the general edge calculus theory (c.f. Mazzeo [48] and references therein). However, We consider in this paper the Kähler
manifold with boundary. The edge space is not defined near the boundary. Recently, Donaldson introduced a function space on a closed Kähler manifold which fits well with our geometric problem. In Section 2, Definition 2.3, we generalized Donaldsons space to the boundary case and thus introduced a Hölder space. Now we studied (5.1) this Hölder space. We collect here the analytic results on the linear equation (5.1) which are not only used in previous arguments above but also for our further applications.
5.1. The maximum principle and the weak solution. We say $v$ is the solution of (5.1) if it satisfies this equation on $\mathfrak{X} \backslash \mathfrak{D}$ and belongs to $C_{\beta}^{2, \alpha}$. From the theory of the elliptic equation, we know that $V$ is smooth outside $\mathfrak{D}$. The delicate part here is always the estimate near the divisor. We first prove a maximum principle for the Kahler cone metric.

Lemma 5.1. Assume that $v$ satisfies $L v \geq 0$ (resp. Lv $\leq 0$ ) with $c<0$, then the maximum (minimum) is achieved on the boundary i.e.

$$
\sup _{\mathfrak{X}} v=\sup _{\partial \mathfrak{X} \backslash \partial \mathfrak{D}} v \quad\left(\inf _{\mathfrak{X}} v=\inf _{\partial \mathfrak{X} \backslash \partial \mathfrak{D}} v\right) .
$$

Proof. Set $u=v+\epsilon S$ and $S=\|s\|^{2 \kappa}$ with $(1+\alpha) \beta>2 \kappa \geq \beta$. Then $|\partial S|_{g}$ is bounded. Suppose that $p$ is the maximum point of $u$. According to Lemma 2.4, $p$ cannot be on $\mathfrak{D}$. So either $p$ stays on the boundary $\partial \mathfrak{X} \backslash \partial \mathfrak{D}$ or in the interior of $\mathfrak{X} \backslash \mathfrak{D}$. Then in the latter case, at the maximum point $p$ we have

$$
0 \leq L v=L u-\epsilon L S \leq c u-\epsilon\left(\triangle_{g} S+b^{i} S_{i}+c S\right) \leq c u+\epsilon C
$$

Here we use $b^{i} S_{i} \geq-\left|b^{i}\right|_{g}^{2}-|\partial S|_{g}^{2}$ and the first conclusion in Lemma 2.4 $\triangle_{g} S \geq$ $-C$. Combining these inequalities we obtain

$$
u(p) \leq \epsilon C
$$

Then at any point $x \in \mathfrak{X}$, we have the following relation

$$
v(x)=u(x)-\epsilon S \leq u(p) \leq \sup _{\partial \mathfrak{X} \backslash \partial \mathfrak{D}} v+\epsilon C
$$

since $S$ is nonnegative. Similarly, Similarly, we shall be using $u=v-\epsilon F$ instead for $L v \leq 0$. As a result, the proposition follows as $\epsilon \rightarrow 0$.

Now we use the maximum principle to deduce the uniqueness of solutions of the elliptic equation (5.1).
Corollary 5.2. If $v_{1}, v_{2}$ are two solutions of the linearized equation (5.1) with $c<0$, then $v_{1}=v_{2}$.

The singular volume form $\omega^{n}$ with respect to the cone metric gives a measure on the manifold $\mathfrak{X}$. As a consequence, the $L^{p}(\mathfrak{X}, g)$ space is defined in the usual way. The $W^{1, p}(\mathfrak{X}, g)$ space furthermore requires that the derivatives satisfy $\int_{\mathfrak{X}}|\nabla f|_{\Omega}^{p} \omega^{n}<\infty$.
Definition 5.1. The weak solution in $W^{1,2}$ of (5.1) is defined, for any $\eta \in W_{0}^{1,2}$, in the sense of distributions;

$$
\begin{equation*}
\mathcal{L}(v, \eta)=\int_{\mathfrak{X}}\left[g^{i \bar{j}} v_{i} \eta_{\bar{j}}-b^{i} v_{i} \eta-c v \eta\right] \omega^{n}=\int_{\mathfrak{X}}-\eta f-h^{i} \eta_{i} \omega^{n} . \tag{5.3}
\end{equation*}
$$

Note that our weak solution is defined globally.

The following lemmas follow directly from the local lifting $P \circ W$ (cf. (2.2)).
Lemma 5.3. (Sobolev imbedding) Assume that $f \in W_{0}^{1,2}$. Then there is a constant $C$ depending on $n, \beta$ such that

$$
\|f\|_{\frac{2 n}{n-1}} \leq C\|f\|_{W^{1,2}}
$$

Lemma 5.4. (Kondrakov compact imbedding) The imbedding $W_{0}^{1,2} \rightarrow L^{p}$ for $1 \leq$ $p<\frac{2 n}{n-1}$ is compact.

Lemma 5.5. (Weak maximum principle) Let $v \in W^{1,2}$ satisfy $L v \geq 0(\leq 0)$ in $\mathfrak{X}$ with $c \leq 0$. Then

$$
\sup _{\mathfrak{X}} v \leq \sup _{\partial \mathfrak{X}} v^{+} \quad\left(\inf _{\mathfrak{X}} v \geq \sup _{\partial \mathfrak{X}} v^{-}\right) .
$$

Proof. From the definition of weak solution we have that $L v \geq 0$ implies $\mathcal{L}(v, \eta) \leq 0$. Then for $\eta \geq 0$, we have

$$
\int_{\mathfrak{X}+}\left[g^{i \bar{j}} v_{i} \eta_{\bar{j}}-b^{i} v_{i} \eta\right] \omega^{n} \leq 0
$$

where $\mathfrak{X}^{+}=\{x \in \mathfrak{X} \mid v(x) \geq 0\}$. Let $v^{+}=\max \{0, v\}$. If $b^{i}=0$, letting $\eta=$ $\sup \left\{0, v-\sup _{\partial \mathfrak{X}} v^{+}\right\}$, we have

$$
\int_{\mathfrak{X}^{+}}|\nabla \eta|^{2} \omega^{n} \leq 0 .
$$

So $|\nabla \eta|^{2}=0$ on $\mathfrak{X}^{+} \backslash \mathfrak{D}$. Since $\eta=0$ at the maximum point on the boundary of $\mathfrak{X}^{+}$, we obtain $\eta=0$ on $\mathfrak{X}^{+} \backslash \mathfrak{D}$. Since the measure of $\mathfrak{D}$ is zero, we could modify the value of $\eta$ such that $\eta=0$ on the whole $\mathfrak{X}$. Then the lemma follows for $b^{i}=0$. When $b^{i} \neq 0$, using the Sobolev inequality (5.3), the proof is the same as that of Theorem 8.1 in 33.

Then this lemma and a standard argument by means of the Fredholm alternative theorem implies the uniqueness and the existence of the weak solution.

Proposition 5.6. The linear equation (5.1) with $c \leq 0$ has a unique weak solution in $W^{1,2}$.
5.2. Hölder estimates. We remark that in this subsection, all results hold for normal-crossing divisors $D$ with more than one component. However, we just check for one component. The general multiple case follows from the normal crossing condition. The Hölder estimates derived in this subsection are used iin the proof of both the interior and boundary Schauder estimates of the approximate geodesic equation. Before stating the proposition on the global and local boundedness, we require some technical lemmas which will be useful later. Denote $\omega_{0}=d z^{1} \wedge d \bar{z}^{1}+$ $\cdots+d z^{n+1} \wedge d \bar{z}^{n+1}$. Then locally in a neighborhood $U_{p}$ near $p \in \mathfrak{D}, \omega_{0}^{n+1}=$ $n!\cdot d z^{1} \wedge d \bar{z}^{1} \wedge \cdots \wedge d z^{n+1} \wedge d \bar{z}^{n+1}$, and then we have that there is a bounded function $h$ such that

$$
\omega^{n+1}=\beta^{2}\left|z^{1}\right|^{2(\beta-1)} \omega_{0}^{n+1} e^{h}
$$

Finally, let $m=2 n+2$.

Lemma 5.7. There is a constant $C$ depending on $|h|_{\infty}$ such that, for any $s>\frac{1}{\beta}$, the following inequality holds

$$
\left(\int_{U_{p}} f^{p} \omega^{n+1}\right)^{\frac{1}{p}} \leq C\left(\int_{U_{p}} f^{s p} \omega_{0}^{n+1}\right)^{\frac{1}{s p}}
$$

Proof. Let $z^{1}=\rho e^{i \theta}$ and compute

$$
\begin{aligned}
& \left(\int_{U_{p}} f^{p} \omega^{n+1}\right)^{\frac{1}{p}}=\left(\int_{U_{p}\left(z^{\prime}\right)} \int_{0}^{r_{2}} \int_{0}^{2 \pi} f^{p} \beta^{2} \rho^{2(\beta-1)} e^{h} \omega_{0}^{n+1}\right)^{\frac{1}{p}} \\
& \leq\left(\int_{U_{p}\left(z^{\prime}\right)} \int_{0}^{r_{2}} \int_{0}^{2 \pi} f^{s p} e^{h} \omega_{0}^{n+1}\right)^{\frac{1}{s p}} \cdot\left(\int_{U_{p}\left(z^{\prime}\right)} \int_{0}^{r_{2}} \int_{0}^{2 \pi}\left(\rho^{2 \beta-2}\right)^{t} e^{h} \omega_{0}^{n+1}\right)^{\frac{1}{t p}}
\end{aligned}
$$

Here $\frac{1}{s}+\frac{1}{t}=1$. Since $t<\frac{1}{1-\beta}$, the second term is bounded, we have $s>\frac{1}{\beta}$, which concludes the proof.

Lemma 5.8. There is a constant $C$ depending on $\beta$ and $|h|_{\infty}$ such that, for any $s>1$, the following formula holds

$$
\left(\int_{U_{l}} f^{p} \omega_{0}^{n+1}\right)^{\frac{1}{p}} \leq C\left(\int_{U_{l}} f^{s p} \omega^{n+1}\right)^{\frac{1}{s p}}
$$

Proof. Again we compute in polar coordinates

$$
\begin{aligned}
& \left(\int_{U_{p}} f^{p} \omega_{0}^{n+1}\right)^{\frac{1}{p}}=\left(\int_{U_{p}\left(z^{\prime}\right)} \int_{0}^{r_{2}} \int_{0}^{2 \pi} f^{p} \rho^{\frac{2(\beta-1)}{s}} \rho^{-\frac{2(\beta-1)}{s}} \omega_{0}^{n+1}\right)^{\frac{1}{p}} \\
& \leq\left(\int_{U_{p}} f^{s p} \beta^{-2} e^{-h} \omega^{n+1}\right)^{\frac{1}{s p}}\left(\int_{U_{p}\left(z^{\prime}\right)} \int_{0}^{r_{2}} \int_{0}^{2 \pi} \rho^{-\frac{2(\beta-1) t}{s}} \omega_{0}^{n+1}\right)^{\frac{1}{t_{p}}}
\end{aligned}
$$

Here $s, t$ are two positive constants such that $\frac{1}{s}+\frac{1}{t}=1$. The second term is bounded as $\frac{t}{s}>\frac{1}{\beta-1}$ which is trivially satisfied.

The proof of the following propositions are in the same vein as the proofs in Chapter 8 in 33. However, by the lemmas stated above, we need a careful analysis in the charts which intersect the divisor.

Proposition 5.9. (Global boundedness) If $v$ is a $W^{1,2}$ sub-solution (respectively super-solution) of (5.1) in $\mathfrak{X}$ satisfying $v \leq 0$ (resp.v $\geq 0$ ) on $\partial \mathfrak{X}$; moreover, if $f \in L^{\frac{q}{2}}$ and $h^{i} \in L^{q}, i=1, \cdots, n+1$ with $q>m$ then there is a constant $C$ depending on $\left|b^{i}\right|_{g},|c|_{\infty}, q, \beta$ such that

$$
\sup _{\mathfrak{X}} v(-v) \leq C\left(\left\|v^{+}\left(v^{-}\right)\right\|_{2}+\|f\|_{\frac{q}{2}}+\left\|h^{i}\right\|_{q}\right) .
$$

Proof. Assume that $v$ is a $W^{1,2}$ sub-solution of (5.1). We are going to use the De Giorgi-Nash-Moser iteration as in Theorem 8.15 in 33]. Denote $k=\|f\|_{\frac{q}{2}}+\left\|h^{i}\right\|_{q}$. Choose $w=v^{+}+k$ and $\eta=\int_{k}^{w} a^{2} s^{2(a a-1)} d s$ for $a \geq 1$ in $\mathcal{L}(v, \eta)$. With the Sobolev inequality Lemma 5.3, we have

$$
\|w\|_{\frac{2 n a}{n-1} ; \omega} \leq(C(a+1))^{\frac{1}{a}}\|w\|_{2 a ; \omega} .
$$

We use Lemma 5.7 and Lemma 5.8 on the coordinates which intersect the divisor $\mathfrak{D}$ and the Hölder inequality in the remainder coordinates. After patching them together via a partition of the unity we have, for $s>\frac{1}{\beta} \geq 1$,

$$
\|w\|_{\frac{2 n a s}{n-1} ; \omega_{0}} \leq(C(a+1))^{\frac{1}{a}}\|w\|_{2 a s ; \omega_{0}} .
$$

Now we follow a standard iteration argument; using the interpolation inequality we have with $\chi=\frac{n}{n-1}$

$$
\|w\|_{\frac{\chi^{N 2 s}}{n-1} ; \omega_{0}} \leq C\|w\|_{\frac{2}{s} ; \omega_{0}}
$$

Finally, letting $N \rightarrow \infty$ and using Lemma 5.8 again, we get the proposition.
Denote as $d$ the distance measured via the Kähler cone metric $\omega$
Proposition 5.10. (Local boundedness) Suppose that $v$ is a $W^{1,2}$ sub-solution of (5.1) and suppose that $f \in L^{q}$, and $h^{i} \in L^{q}, i=1, \cdots, n+1$ with $q>m$. Then for any ball $B_{2 d}(y) \subset \mathfrak{X}$ and any $p>1$ there is a constant $C$ depending on $\left(\left|b^{i}\right|_{g}+|c|_{\infty}\right) d$, $q, \beta, p$ such that

$$
\sup _{B_{d}(y)} v(-v) \leq C\left(d^{-\frac{m}{p}}\left\|v^{+}\left(v^{-}\right)\right\|_{L^{p}\left(B_{2 d}(y)\right)}+d^{2\left(1-\frac{m}{2 q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}\right) .
$$

Proof. We will prove the local boundedness of the homogeneous equation. The general case follows by means of using $v+d^{2\left(1-\frac{m}{2 q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}$ instead of $v$. Then $v$ would be a weak sub-solution of (5.1) with $f=0$ and $h^{i}=0$; namely $\mathcal{L}(v, \eta) \leq 0$. Assume $d=1$ and take the test function to be $\eta^{2} v^{\alpha}$ for $\eta \in C_{0}^{1}\left(B_{4}\right)$ and $\alpha>0$. Then we have for $w:=v^{\frac{\alpha+1}{2}}$

$$
\|\eta w\|_{\frac{2 n}{n-1} ; \omega} \leq C \cdot\left(\|w \partial \eta\|_{2 ; \omega}+\|w \eta\|_{2 ; \omega}\right)
$$

Using Lemma 5.7 and Lemma 5.8 we obtain, on any open set $U_{p}$ which intersects the divisor $D$ for $s>\frac{1}{\beta}$

$$
\|\eta w\|_{\frac{2 n}{s(n-1)} ; \omega_{0}} \leq C\left[\|w \partial \eta\|_{2 ; \omega}+\|w \eta\|_{2 s ; \omega_{0}}\right]
$$

We claim for the first addendum on the right hand side it holds $\|w \partial \eta\|_{2 ; \omega} \leq$ $C\|w \partial \eta\|_{2 s ; \omega_{0}}$ with $s>\frac{1}{\beta}$. Again, by means of Lemma 5.7 and Lemma 5.8 we compute

$$
\begin{aligned}
& \|w \partial \eta\|_{2 ; \omega}=\left[\int_{U_{p}} w^{2}\left(\partial_{z_{1}} \eta \partial_{z_{\overline{1}}} \eta\left|z^{1}\right|^{2(1-\beta)} \frac{1}{\beta^{2}}+\sum_{i=2}^{n+1} \partial_{z_{i}} \eta \partial_{z_{\bar{\imath}}} \eta\right) \omega^{n+1}\right]^{\frac{1}{2}} \\
& \leq\left[\int_{U_{p}} w^{2}\left(\partial_{z_{1}} \eta \partial_{z_{\overline{1}}} \eta\right) e^{h} \omega_{0}^{n+1}+C\left(\int_{U_{p}} \sum_{i=2}^{n+1} w^{2 s}\left(\partial_{z_{i}} \eta \partial_{z_{\bar{\imath}}} \eta\right)^{s} \omega^{n+1}\right)^{\frac{1}{s}}\right]^{\frac{1}{2}} \\
& \leq C\left(\int_{U_{p}} w^{2 s}|\partial \eta|_{\omega_{0}}^{2 s} \omega_{0}^{n+1}\right)^{\frac{1}{2 s}}
\end{aligned}
$$

where to get the last step we used the Hölder inequality on the first term. So standard argument with Lemma 5.8 implies

$$
\|v\|_{\infty ; B_{1}, \omega_{0}} \leq C\|v\|_{p s ; B_{2}, \omega_{0}} \leq C\|v\|_{p s^{2} ; B_{2}, \omega}
$$

The local boundedness follows from the next observation; $B_{1}(0, \omega) \subset B_{1}\left(0, \omega_{0}\right)$ which follows from the distance inequality,

$$
\sqrt{\left|z^{1}\right|^{2}+\sum_{i=2}^{n}\left|z^{i}\right|^{2}} \leq \sqrt{\left|z^{1}\right|^{2 \beta}+\sum_{i=2}^{n}\left|z^{i}\right|^{2}} \leq 1
$$

Proposition 5.11. (Weak Harnack inequality) Suppose that $v$ is a $W^{1,2}$ supersolution of (5.1), non-negative in a ball $B_{4 d}(y) \subset \mathfrak{X}$ and suppose that $f \in L^{\frac{q}{2}}$ and $h^{i} \in L^{q}, i=1, \cdots, n+1$ with $q>m$. Then, for any $\frac{n+1}{n}>p>1$ there is $a$ constant $C$ depending on $\left(\left|b^{i}\right|_{g}+|c|_{\infty}\right) d, q, \beta$, $p$ such that

$$
\begin{equation*}
d^{-\frac{m}{p}}\|v\|_{L^{p}\left(B_{2 d}(y)\right)} \leq C\left\{\inf _{B_{d(y)}} v+d^{2\left(1-\frac{m}{q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}\right\} \tag{5.4}
\end{equation*}
$$

Proof. We assume $d=a$ and argue as in the proof of the local boundedness with different test function. Thus it suffices to prove, for the weak super-solution of (5.1) with vanishing right hand side, there is a $p>0$ and constant $C$ such that

$$
\begin{equation*}
\int_{B_{2}} v^{-p} \omega^{n+1} \int_{B_{2}} v^{p} \omega^{n+1} \leq C . \tag{5.5}
\end{equation*}
$$

Choose a test function of the form $\eta^{2} v^{\alpha}$ and let $w:=\log v$ and $\alpha=-1$. Here $\eta$ is the cut-off function defined in Lemma 2.1. We have by the CauchySchwarz's inequality for small $\epsilon_{1}$ and $\epsilon_{2}$,

$$
\int_{B_{r}}|\partial w|^{2} \omega^{n+1} \leq \frac{2}{\epsilon_{1}} \int_{\mathfrak{X}}|\partial \eta|^{2} \omega^{n+1}+2\left(\frac{\left|b^{i}\right|_{0}}{4 \epsilon_{2}}+|c|_{0}\right) \int_{\mathfrak{X}} \eta^{2} \omega^{n+1}
$$

Since $(\mathfrak{X}, \omega)$ has finite volume, the second term is bounded. Concerning the first addendum, we compute,

$$
\int_{U_{p}}|\partial \eta|^{2} \omega^{n+1} \leq C \int_{0}^{2 \pi} \int_{0}^{r} t^{4-2 \beta+2(\beta-1)} d t d \theta \leq C r^{3}
$$

We conclude that $\int_{B_{r}}|\partial w| \omega^{n+1}$ is bounded.
Next we claim that $\int_{B_{r}}|\partial w|_{0} \omega_{0}^{n+1}$ is also bounded. To prove the claim, let's compute

$$
\int_{B_{r}}|\partial w|_{0} \omega_{0}^{n+1}=\int_{B_{r}}\left(\left|\partial_{z^{1}} w\right|_{0}^{2}+\sum_{i=2}^{n+1}\left|\partial_{z^{i}} w\right|_{0}^{2}\right)^{\frac{1}{2}} \beta^{-2}\left|z^{1}\right|^{2(1-\beta)} e^{-h} \omega^{n+1}
$$

The second is bounded, since $h$ and $\left|z^{1}\right|$ are bounded. For the first addendum, we first consider the case when $\left|\partial_{z^{1}} w\right|_{0} \leq 1$. The its boundedness follows from the finiteness of the volume. The second case is when $\left|\partial_{z^{1}} w\right|_{0}>1$. In this second case $\left|\partial_{z^{1}} w\right|_{0}<\left|\partial_{z^{1}} w\right|_{0}^{2}$ and so its integral is bounded by $\int_{B_{r}}|\partial w|^{2} \omega^{n}$. The claim thus holds. Now we apply the Moser-Trudinger inequality (see Theorem 7.21 in [33]) with respect to $\omega_{0}$. Thus there exists a constant $p_{0}$ such that

$$
\int_{B_{3}} e^{p_{0}\left|w-w_{0}\right|} \omega_{0}^{n}
$$

is bounded and so is

$$
\int_{B_{3}} v^{p_{0}} \omega_{0}^{n} \int_{B_{3}} v^{-p_{0}} \omega_{0}^{n} .
$$

From Lemma 5.7 we have, for some $s_{0}>\beta^{-1}$,

$$
\int_{B_{3}} v^{\frac{p_{0}}{s_{0}}} \omega^{n} \int_{B_{3}} v^{\frac{-p_{0}}{s_{0}}} \omega^{n} \leq C\left(\int_{B_{3}} v^{p_{0}} \omega_{0}^{n} \int_{B_{3}} v^{-p_{0}} \omega_{0}^{n}\right)^{\frac{1}{s_{0}}} \leq C
$$

The above inequality gives the wanted inequality (5.5) with $p=\frac{p_{0}}{s_{0}}$. The proof of the proposition is therefore achieved.

As a result we have the following estimates.
Proposition 5.12. (The Harnack inequality) For any $B_{4 d}(y) \subset \mathfrak{X}$, suppose that $v$ is a non-negative $W^{1,2}$ solution of (5.1) with homogeneous right hand side in a ball $B_{4 d}(y) \subset \mathfrak{X}$. Then, there is a constant $C$ depending on $\left(\left|b^{i}\right|_{g}+|c|_{\infty}\right) d$, $\beta$ such that

$$
\begin{equation*}
\sup _{B_{d}} v \leq C \inf _{B_{d}} v \tag{5.6}
\end{equation*}
$$

Proposition 5.13. (Interior Hölder estimate) Suppose that $v$ is a $W^{1,2}$ solution of (5.1) in $\mathfrak{X}$ and suppose that $f \in L^{\frac{q}{2}}$ and $h^{i} \in L^{q}$ with $q>m$. Then, for any $B_{d_{0}}(y) \subset \operatorname{Int} \mathfrak{X}$ and $d \leq d_{0}$, there is a constant $C\left(\left|b^{i}\right|_{g},|c|_{\infty}, d_{0}, q\right)$ and $\alpha\left(\left(\left|b^{i}\right|_{g}+\right.\right.$ $\left.\left.|c|_{\infty}\right) d_{0}, q\right)$ such that

$$
o s c_{B_{d}(y)} v \leq C d^{\alpha}\left(d_{0}^{-\alpha} \sup _{B_{d_{0}}(y)}|v|+d^{2\left(1-\frac{m}{q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}\right)
$$

5.2.1. Local estimates at the boundary. Consider a point $y \in \partial \mathfrak{X}$ and using the local holomorphic coordinate in the half space $R_{+}^{2 n+2}=\left\{x \mid x^{n+1} \geq 0\right\}$, here $x^{n+1}$ is the real part of the variable $z^{n+1}$. Then the coordinate chart near $y$ becomes a domain $T$ in $R_{+}^{2 n+2}$. Recall that we assumed $v_{0}$ in $C_{\beta}^{\alpha}(\partial \mathfrak{X})$ in (5.2). We let

$$
M:=\sup _{\partial \mathfrak{X}} \cap B_{2 d} v, \quad m:=\inf _{\partial \mathfrak{X}} \cap B_{2 d} v .
$$

Moreover we extend $v$ from the half space to the whole space $R^{2 n+2}$.

$$
\begin{aligned}
v_{M}^{+} & :=\left\{\begin{array}{cc}
\sup \{v(x), M\}, & x \in T \\
M & x \notin T
\end{array}\right. \\
v_{m}^{-} & :=\left\{\begin{array}{cc}
\inf \{v(x), m\}, & x \in T \\
m & x \notin T
\end{array}\right.
\end{aligned}
$$

Just by following the proof of interior estimates, we obtain
Proposition 5.14. (Local boundedness at the boundary) Suppose that $v$ is a $W^{1,2}$ sub-solution of (5.1) and suppose that $f \in L^{q}$, and $h^{i} \in L^{q}, i=1, \cdots, n+1$ with $q>m$. Then for any ball $B_{2 d}(y)$ and any $p>1$ there is a constant $C$ depending on $\left(\left|b^{i}\right|_{g}+|c|_{\infty}\right) d, q, \beta, p$ such that

$$
\sup _{B_{d}(y)} v_{M}^{+} \leq C\left(d^{-\frac{m}{p}}\left\|v_{M}^{+}\right\|_{L^{p}\left(B_{2 d}(y)\right)}+d^{2\left(1-\frac{m}{q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}\right)
$$

Proposition 5.15. (Weak Harnack inequality at the boundary) Suppose that $v$ is a $W^{1,2}$ super-solution of (5.1), non-negative in a ball $B_{4 d}(y) \cap T$ and suppose that $f \in L^{\frac{q}{2}}$ and $h^{i} \in L^{q}, i=1, \cdots, n+1$ with $q>m$. Then, for any $\frac{n+1}{n}>p>1$ there is a constant $C$ depending on $\left(\left|b^{i}\right|_{g}+|c|_{\infty}\right) d, q, \beta, p$ such that

$$
d^{-\frac{m}{p}}\left\|v_{m}^{-}\right\|_{L^{p}\left(B_{2 d}(y)\right)} \leq C\left(\inf _{B_{d(y)}} v_{m}^{-}+d^{2\left(1-\frac{m}{q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}\right)
$$

Proposition 5.16. (Höder estimate at the boundary) Suppose that $v$ is a $W^{1,2}$ solution of (5.1) in $\mathfrak{X}$ and $f \in L^{\frac{q}{2}}$ and $h^{i} \in L^{q}, i=1, \cdots, n+1$ with $q>m$. Suppose that $y$ is on the boundary of $\mathfrak{X}$. Then, for any $B_{d_{0}}(y)$ and $d \leq d_{0}$, there is a constant $C\left(\left|b^{i}\right|_{g},|c|_{\infty}, d_{0}, q\right)$ and $\alpha\left(\left(\left|b^{i}\right|_{g}+|c|_{\infty}\right) d_{0}, q\right)$ such that
$\operatorname{Osc}_{B_{d}(y) \cap \mathfrak{X}} v \leq C\left\{d^{\alpha}\left(d_{0}^{-\alpha} \sup _{B_{d_{0}}(y) \cap T}|v|+d^{2\left(1-\frac{m}{q}\right)}\|f\|_{\frac{q}{2}}+d^{1-\frac{m}{q}}\left\|h^{i}\right\|_{q}\right)+\operatorname{Osc}_{B}{\sqrt{d_{0} d}}(y) \cap \partial \mathfrak{X} v\right\}$.
5.3. The Dirichlet problem of the linearized problem. Fix $0<\beta<1$, and write $\mu:=\beta^{-1}-1$. Denote by $G$ the Green function of the standard cone metric $d r^{2}+\beta^{2} r^{2} d \theta^{2}$ and by $T$ one of the second order operators

$$
\frac{\partial^{2}}{\partial s^{i} \partial s^{j}}, r^{-1} \frac{\partial^{2}}{\partial \theta \partial s^{i}}, \frac{\partial^{2}}{\partial r \partial s^{i}} .
$$

It is shown in Donaldson [29] Proposition 4 that the polyhomogeneous expansion of the Green function around the singular set $D$

$$
\begin{equation*}
G=\sum_{j, k} a_{j, k}(s) r^{\nu+2 j} \cos k\left(\theta-\theta^{\prime}\right) \tag{5.7}
\end{equation*}
$$

Donaldson proved the following Schauder estimate.
Proposition 5.17. (Donaldson [29]) Suppose that $\alpha \in(0, \mu)$, then there exists $a$ constant $C$ which depends only on $\alpha, m, \beta$ such that for all functions $\rho \in C_{c}^{\infty}\left(\mathbb{R}^{m}\right)$, we have

$$
[i \partial \bar{\partial}(G \rho)]_{\alpha} \leq C[\rho]_{\alpha}
$$

Remark 5.1. The Schauder estimates of the remainder pure second order derivatives (i.e. $\partial \partial$ direction) of $G \rho$ are proved in Brendle [10] (Proposition A.1) and Jeffres, Mazzeo and Rubinstein 42 (Proposition 3.3).

In our problem, the interior Schauder estimate follows from Proposition 5.17 When we consider the Schauder estimate near the boundary, we notice that our manifold is a product manifold, then the new Green function is constructed by replacing $s$ by $\left(s, x^{n+1}, y^{n+1}\right)$ in (5.7). So when $i$ or $j$ is not equal to $n+1$, then the $\partial_{i} \bar{\partial}_{j}$ estimate follows exactly the same line of Donaldson's proof (and further regularity by Jeffres, Mazzeo and Rubinstein [42]). The $\partial_{n+1} \bar{\partial}_{n+1}$ estimate follows from the equation (cf. Section 4.4 in [33). Now we patch the local estimates to the whole manifold by the partition of unity in the standard way.

Proposition 5.18. Fix $\alpha$ with $0<\alpha<\mu=\beta^{-1}-1$. Then there is a constant $C$ depending on $\beta, m, \alpha$ such that for all the functions $f \in C_{\beta}^{\alpha}$ we have the Schauder estimate of the weak solution of the equation (5.1)

$$
|v|_{C_{\beta}^{2, \alpha}} \leq C\left(|v|_{L^{\infty}}+|f|_{C_{\beta}^{\alpha}}+\sum_{i}\left|h^{i}\right|_{C_{\beta}^{1, \alpha}}\right) .
$$

Combining the existence and uniqueness of the weak solution Proposition 5.6. we obtain

Proposition 5.19. There exists a unique solution of (5.1) with data as (5.2) in $C_{\beta}^{2, \alpha}$.

The linear theory in this section immediately implies the $\partial \bar{\partial}$-lemma with cone singularities.

## 6. The metric space structure

In this section we apply our geodesic to study the geometry of the space of Kähler cone metrics. We equip the space of Kähler cone metrics with the following normalization condition; we ask any Kähler cone potential $\varphi$ with respect to the background modes metric $\omega$ to satisfies $I(\varphi)=0$ vanishes, where

$$
I_{\omega}(\varphi)=\frac{1}{V} \int_{M} \varphi \omega^{n}-\frac{1}{V} \sum_{i=0}^{n-1} \frac{i+1}{n+1} \int_{M} \partial \varphi \wedge \bar{\partial} \varphi \wedge \omega^{i} \wedge \omega_{\varphi}^{n-i-1}
$$

In particular, the functional $I(\varphi)$ is well defined along the $C_{\beta}^{1,1}$ geodesic. We show that the space of cone metrics has a structure of metric space following the approach in [16]. We said that $\varphi(t)$ is an $\epsilon$-approximate geodesic if it solves

$$
\begin{equation*}
\left(\varphi^{\prime \prime}-\left|\partial \varphi^{\prime}\right|_{g_{\varphi}}^{2}\right) \operatorname{det} g_{\varphi}=\epsilon f \operatorname{det} g \tag{6.1}
\end{equation*}
$$

where $f=\frac{\operatorname{det} \Omega_{1}}{\operatorname{det} \Omega}=\left|m \Phi_{n+1, \overline{n+1}}-\partial(\varphi(1)-\varphi(0))\right|_{\Omega}$. Recall the energy $E:=$ $\int_{0}^{1} \int_{M} \varphi^{\prime}(t) \omega_{\varphi(t)}^{n} d t$. Along the $C_{\beta}^{1,1}$ geodesic, there holds

$$
\begin{equation*}
\frac{1}{2}\left|\frac{d}{d t} E\right|=\left|\int_{M} \varphi^{\prime}\left(\varphi^{\prime \prime}-|\partial \varphi|_{g_{\varphi}}^{2}\right) \omega_{\varphi}^{n}\right| \leq \epsilon \sup _{\mathfrak{X}}\left|\phi^{\prime}\right| \cdot \sup _{\mathfrak{X}}|f| \cdot \mathrm{Vol} \tag{6.2}
\end{equation*}
$$

We show positivity of the length of any non-trivial geodesic segment and the geodesic approximation lemma. We omit the proof here, since along the $C_{\beta}^{1,1}$ geodesic, all the inequalities are well defined.
Proposition 6.1. Let $\varphi(t)$ be a $C_{\beta}^{1,1}$ geodesic from 0 to $\varphi$, and $I(\varphi)=0$. Then the following inequality holds

$$
\int_{0}^{1} \sqrt{\int_{M}\left(\varphi^{\prime}\right)^{2} \frac{\omega_{\varphi}^{n}}{n!}} d t \geq \operatorname{Vol}^{-\frac{1}{2}}\left(\sup \left(\int_{\varphi>0} \varphi \frac{\omega_{\varphi}^{n}}{n!}, \int_{\varphi<0} \varphi \frac{\omega_{0}^{n}}{n!}\right)\right)
$$

In particular, the length of any non-constant $C_{\beta}^{1,1}$ geodesic is positive.
Lemma 6.2. Let $\mathcal{H}_{C} \subset \mathcal{H}_{\beta}$ be as in Definition 1.2. Also, let $C_{i}:=\varphi_{i}(s):[0,1] \rightarrow$ $\mathcal{H}_{C}$, for $i=1,2$, be two smooth curves. Then, for a small enough $\epsilon_{0}$, there is a two-parameter family of curves

$$
C(s, \epsilon): \varphi(t, s, \epsilon):[0,1] \times[0,1] \times\left(0, \epsilon_{0}\right] \rightarrow \mathcal{H}
$$

such that the following properties hold:
(1) Fixed $s, \epsilon$, then $C(s, \epsilon) \in C_{\beta}^{2, \alpha}$ is an $\epsilon$-approximate geodesic from $\varphi_{1}(s)$ to $\varphi_{2}(s)$.
(2) There exists a uniform constant $C$ such that

$$
|\varphi|+\left|\frac{\partial \varphi}{\partial t}\right|+\left|\frac{\partial \varphi}{\partial s}\right|<C ; \quad 0 \leq \frac{\partial^{2} \varphi}{\partial t^{2}}<C ; \quad \frac{\partial^{2} \varphi}{\partial s^{2}}<C .
$$

(3) Fixed any $s$, the limit in $C_{\beta}^{1,1}$ of $C(s, \epsilon)$ as $\epsilon \rightarrow 0$ is the unique geodesic arc from $\varphi_{1}(s)$ to $\varphi_{2}(s)$.
(4) There exists an uniform constant $C$ such that, about the energy $E(t, s, \epsilon)$ along the curve $C(s, \epsilon)$, there holds

$$
\sup _{t, s}\left|\frac{\partial E}{\partial t}\right| \leq \epsilon \cdot C \cdot \mathrm{Vol}
$$

With the geodesic approximation lemma above, the triangular inequality and the differentiability property of the distance function follow immediately.

Theorem 6.3. Suppose that $\phi=\varphi(s):[0,1] \rightarrow \mathcal{H}_{\beta}$ is a smooth curve, and let $p$ be a base point of $\mathcal{H}$. Then, the length of the geodesic arc between $p$ and $\varphi$ is less than the sum of the length of the geodesic arc between from $p$ to $\phi(0)$ and the length of the curve from $\phi(0)$ to $\phi(s)$.

Theorem 6.4. The distance function given by the length of the geodesic arc is a differentiable function.

## References

[1] Claudio Arezzo and Gang Tian. Infinite geodesic rays in the space of Kähler potentials. Ann. Sc. Norm. Super. Pisa Cl. Sci. (5), 2(4):617-630, 2003.
[2] Shigetoshi Bando and Toshiki Mabuchi. Uniqueness of Einstein Kähler metrics modulo connected group actions. In Algebraic geometry, Sendai, 1985, volume 10 of Adv. Stud. Pure Math., pages 11-40. North-Holland, Amsterdam, 1987.
[3] Eric Bedford and B. A. Taylor. The Dirichlet problem for a complex Monge-Ampère equation. Invent. Math., 37(1):1-44, 1976.
[4] Robert J. Berman. A thermodynamical formalism for monge-ampere equations, mosertrudinger inequalities and kahler-einstein metrics. 112010.
[5] Robert J. Berman, Sébastien Boucksom, Philippe Eyssidieux, Vincent Guedj, and Ahmed Zeriahi. Kähler-einstein metrics and the kähler-ricci flow on log fano varieties. 112011.
[6] Bo Berndtsson. Curvature of vector bundles associated to holomorphic fibrations. Ann. of Math. (2), 169(2):531-560, 2009.
[7] Zbigniew Blocki. Interior regularity of the complex Monge-Ampère equation in convex domains. Duke Math. J., 105(1):167-181, 2000.
[8] Zbigniew Blocki. A gradient estimate in the Calabi-Yau theorem. Math. Ann., 344(2):317327, 2009.
[9] Zbigniew Blocki. On geodesics in the space of Kähler metrics. Advanced Lectures in Mathematics, 21(1):3-20, 2012.
[10] S. Brendle. Ricci flat kahler metrics with edge singularities. 032011.
[11] L. Caffarelli, J. J. Kohn, L. Nirenberg, and J. Spruck. The Dirichlet problem for nonlinear second-order elliptic equations. II. Complex Monge-Ampère, and uniformly elliptic, equations. Comm. Pure Appl. Math., 38(2):209-252, 1985.
[12] Frédéric Campana, Henri Guenancia, and Mihai Păun. Metrics with cone singularities along normal crossing divisors and holomorphic tensor fields. 042011.
[13] X. X. Chen and G. Tian. Geometry of Kähler metrics and foliations by holomorphic discs. Publ. Math. Inst. Hautes Études Sci., (107):1-107, 2008.
[14] Xiu-Xiong Chen, Simon Donaldson, and Song Sun. Kahler-einstein metrics and stability. 10 2012.
[15] Xiu-Xiong Chen, Simon Donaldson, and Song Sun. Kahler-einstein metrics on fano manifolds, i: approximation of metrics with cone singularities. 112012.
[16] Xiuxiong Chen. The space of Kähler metrics. J. Differential Geom., 56(2):189-234, 2000.
[17] Xiuxiong Chen. Space of Kähler metrics. III. On the lower bound of the Calabi energy and geodesic distance. Invent. Math., 175(3):453-503, 2009.
[18] Xiuxiong Chen, Simon Donaldson, and Song Sun. Kahler-einstein metrics on fano manifolds, ii: limits with cone angle less than 2.122012.
[19] Xiuxiong Chen, Simon Donaldson, and Song Sun. Kahler-einstein metrics on fano manifolds, iii: limits as cone angle approaches 2 and completion of the main proof. 022013.
[20] Xiuxiong Chen and Weiyong He. The space of volume forms. Int. Math. Res. Not. IMRN, (5):967-1009, 2011.
[21] Xiuxiong Chen and Yudong Tang. Test configuration and geodesic rays. Astérisque, (321):139-167, 2008. Géométrie différentielle, physique mathématique, mathématiques et société. I.
[22] S. S. Chern, Harold I. Levine, and Louis Nirenberg. Intrinsic norms on a complex manifold. In Global Analysis (Papers in Honor of K. Kodaira), pages 119-139. Univ. Tokyo Press, Tokyo, 1969.
[23] Shiing-shen Chern. On holomorphic mappings of hermitian manifolds of the same dimension. In Entire Functions and Related Parts of Analysis (Proc. Sympos. Pure Math., La Jolla, Calif., 1966), pages 157-170. Amer. Math. Soc., Providence, R.I., 1968.
[24] Pascal Cherrier. Équations de Monge-Ampère sur les variétés hermitiennes compactes. Bull. Sci. Math. (2), 111(4):343-385, 1987.
[25] Tamás Darvas and László Lempert. Weak geodesics in the space of kähler metrics. 052012.
[26] Wei Yue Ding. Remarks on the existence problem of positive Kähler-Einstein metrics. Math. Ann., 282(3):463-471, 1988.
[27] S. K. Donaldson. Symmetric spaces, Kähler geometry and Hamiltonian dynamics. In Northern California Symplectic Geometry Seminar, volume 196 of Amer. Math. Soc. Transl. Ser. 2, pages 13-33. Amer. Math. Soc., Providence, RI, 1999.
[28] S. K. Donaldson. Holomorphic discs and the complex Monge-Ampère equation. J. Symplectic Geom., 1(2):171-196, 2002.
[29] S. K. Donaldson. Kähler metrics with cone singularities along a divisor. In Essays in mathematics and its applications, pages 49-79. Springer, Heidelberg, 2012.
[30] Avron Douglis and Louis Nirenberg. Interior estimates for elliptic systems of partial differential equations. Comm. Pure Appl. Math., 8:503-538, 1955.
[31] Lawrence C. Evans. Classical solutions of fully nonlinear, convex, second-order elliptic equations. Comm. Pure Appl. Math., 35(3):333-363, 1982.
[32] Lawrence C. Evans. Classical solutions of the Hamilton-Jacobi-Bellman equation for uniformly elliptic operators. Trans. Amer. Math. Soc., 275(1):245-255, 1983.
[33] David Gilbarg and Neil S. Trudinger. Elliptic partial differential equations of second order. Classics in Mathematics. Springer-Verlag, Berlin, 2001. Reprint of the 1998 edition.
[34] Bo Guan. The Dirichlet problem for complex Monge-Ampère equations and regularity of the pluri-complex Green function. Comm. Anal. Geom., 6(4):687-703, 1998.
[35] Bo Guan and Qun Li. Complex Monge-Ampère equations and totally real submanifolds. Adv. Math., 225(3):1185-1223, 2010.
[36] Bo Guan and Joel Spruck. Boundary-value problems on $S^{n}$ for surfaces of constant Gauss curvature. Ann. of Math. (2), 138(3):601-624, 1993.
[37] Pengfei Guan. The extremal function associated to intrinsic norms. Ann. of Math. (2), 156(1):197-211, 2002.
[38] Pengfei Guan and Xi Zhang. Regularity of the geodesic equation in the space of Sasakian metrics. Adv. Math., 230(1):321-371, 2012.
[39] Abdellah Hanani. Équations du type de Monge-Ampère sur les variétés hermitiennes compactes. J. Funct. Anal., 137(1):49-75, 1996.
[40] David Hoffman, Harold Rosenberg, and Joel Spruck. Boundary value problems for surfaces of constant Gauss curvature. Comm. Pure Appl. Math., 45(8):1051-1062, 1992.
[41] Thalia D. Jeffres. Uniqueness of Kähler-Einstein cone metrics. Publ. Mat., 44(2):437-448, 2000.
[42] Thalia D. Jeffres, Rafe Mazzeo, and Yanir A. Rubinstein. Kähler-einstein metrics with edge singularities. 052011.
[43] Slawomir Kolodziej. The complex Monge-Ampère equation. Acta Math., 180(1):69-117, 1998.
[44] N. V. Krylov. Boundedly inhomogeneous elliptic and parabolic equations in a domain. Izv. Akad. Nauk SSSR Ser. Mat., 47(1):75-108, 1983.
[45] László Lempert and Liz Vivas. Geodesics in the space of kähler metrics. 052011.
[46] Yung-chen Lu. Holomorphic mappings of complex manifolds. J. Differential Geometry, 2:299312, 1968.
[47] Toshiki Mabuchi. Some symplectic geometry on compact Kähler manifolds. I. Osaka J. Math., 24(2):227-252, 1987.
[48] Rafe Mazzeo. Elliptic theory of differential edge operators. I. Comm. Partial Differential Equations, 16(10):1615-1664, 1991.
[49] Robert C. McOwen. Point singularities and conformal metrics on Riemann surfaces. Proc. Amer. Math. Soc., 103(1):222-224, 1988.
[50] Richard B. Melrose. Pseudodifferential operators, corners and singular limits. ICM-90. Mathematical Society of Japan, Tokyo, 1990. A plenary address presented at the International Congress of Mathematicians held in Kyoto, August 1990.
[51] Roberto Moriyón. Regularity of the Dirichlet problem for the degenerate complex MongeAmpère equation. Comm. Pure Appl. Math., 35(1):1-27, 1982.
[52] D. H. Phong and Jacob Sturm. The Monge-Ampère operator and geodesics in the space of Kähler potentials. Invent. Math., 166(1):125-149, 2006.
[53] D. H. Phong and Jacob Sturm. Regularity of geodesic rays and Monge-Ampère equations. Proc. Amer. Math. Soc., 138(10):3637-3650, 2010.
[54] Duong H. Phong and Jacob Sturm. Test configurations for K-stability and geodesic rays. J. Symplectic Geom., 5(2):221-247, 2007.
[55] B.-W. Schulze. Pseudo-differential operators on manifolds with singularities, volume 24 of Studies in Mathematics and its Applications. North-Holland Publishing Co., Amsterdam, 1991.
[56] Stephen Semmes. Complex Monge-Ampère and symplectic manifolds. Amer. J. Math., 114(3):495-550, 1992.
[57] Yum Tong Siu. Lectures on Hermitian-Einstein metrics for stable bundles and KählerEinstein metrics, volume 8 of DMV Seminar. Birkhäuser Verlag, Basel, 1987.
[58] Yum Tong Siu. The existence of Kähler-Einstein metrics on manifolds with positive anticanonical line bundle and a suitable finite symmetry group. Ann. of Math. (2), 127(3):585-627, 1988.
[59] Jian Song and Steve Zelditch. Convergence of Bergman geodesics on $\mathbf{C P}^{1}$. Ann. Inst. Fourier (Grenoble), 57(7):2209-2237, 2007. Festival Yves Colin de Verdière.
[60] Jian Song and Steve Zelditch. Bergman metrics and geodesics in the space of Kähler metrics on toric varieties. Anal. PDE, 3(3):295-358, 2010.
[61] Jian Song and Steve Zelditch. Test configurations, large deviations and geodesic rays on toric varieties. Adv. Math., 229(4):2338-2378, 2012.
[62] Gang Tian. Kähler-Einstein metrics on algebraic manifolds. In Transcendental methods in algebraic geometry (Cetraro, 1994), volume 1646 of Lecture Notes in Math., pages 143-185. Springer, Berlin, 1996.
[63] Gang Tian. K-stability and kähler-einstein metrics. 112012.
[64] Marc Troyanov. Metrics of constant curvature on a sphere with two conical singularities. In Differential geometry (Peni scola, 1988), volume 1410 of Lecture Notes in Math., pages 296-306. Springer, Berlin, 1989.
[65] Marc Troyanov. Prescribing curvature on compact surfaces with conical singularities. Trans. Amer. Math. Soc., 324(2):793-821, 1991.
[66] Hajime Tsuji. Stability of tangent bundles of minimal algebraic varieties. Topology, 27(4):429442, 1988.
[67] Shing Tung Yau. A general Schwarz lemma for Kähler manifolds. Amer. J. Math., 100(1):197203, 1978.
[68] Shing Tung Yau. On the Ricci curvature of a compact Kähler manifold and the complex Monge-Ampère equation. I. Comm. Pure Appl. Math., 31(3):339-411, 1978.

Scuola Normale Superiore di Pisa - Piazza dei Cavalieri, 7 - 56126 Pisa, Italy
E-mail address: simocala@gmail.com
Institut Fourier, Université Joseph Fourier (Grenoble I), UMR 5582 CNRS-UJF, BP 74, 38402 Saint-Martin-d'Hères, France

E-mail address: zheng@math.uni-hannover.de


[^0]:    The first named author is partially supported by INdAM grants. The second named author is partially supported by ANR project "Flots et Opérateurs Géométriques" (ANR-07-BLAN-025101).

