Proceedings of the 35th International Symposium on Automation and Robotics in Construction (ISARC 2018)

Berlin, Germany, July 20-25, 2018



Jochen Teizer, Markus König (Hrsg.) Ruhr-Universität Bochum Deutschland

ISBN 978-3-00-060855-1

Die Deutsche Nationalbibliothek verzeichnet diese Publikation in der Deutschen Nationalbibliografie; detaillierte bibliografische Daten sind im Internet über http://dnb.d-nb.de abrufbar.

1. Auflage 2018

Alle Rechte vorbehalten

© 2018 International Association on Automation and Robotics in Construction

Das Werk einschließlich aller seiner Teile ist urheberrechtlich geschützt. Jede Verwertung außerhalb der engen Grenzen des Urheberrechtsgesetzes ist ohne Zustimmung der einzelnen Autoren unzulässig und strafbar. Das gilt insbesondere für Vervielfältigungen, Übersetzungen, Mikroverfilmungen und die Einspeicherung und Verarbeitung in elektronischen Systemen.

Die Wiedergabe von Gebrauchsnamen, Handelsnamen, Warenbezeichnungen usw. in diesem Werk berechtigt auch ohne besondere Kennzeichnung nicht zu der Annahme, dass solche Namen im Sinne der Warenzeichen- und Markenschutz-Gesetzgebung als frei zu betrachten wären und daher von jedermann benutzt werden dürften.

Umschlaggestaltung: Jochen Teizer, Bochum

Technical Committee

Bryan Adey Pär Ahman Burcu Akinci Mohamed Al-Hussein Alex Albert Tatsuo Arai **Carlos Balaguer** Burcin Becerik-Gerber Thomas Bock André Borrmann Frédéric Bosché Ioannis Brilakis Tobias Bruckmann Alexey Bulgakov Carlos Caldas Alessandro Carbonari Daniel Castro Hung-Ming Chen Po-Han Chen Jack C P Cheng Min-Yuan Cheng Yong Cho Moon Young Cho Angelo L.C. Ciribini Sigrid brell-cokcan Maximimlian Dichtl Kristina Doycheva Esin Ergen Behzad Esmaeili Henk Freimuth Raul Fuentes Hiroshi Furuva Borja Garcia de Soto Ernesto Gambao Jozef Gasparik Olga Golovina Mani Golparvar-Fard Quang Ha Carl Haas Amin Hammad Chang-Soo Han Ferri Hassani Rauno Heikkilä Patrick Herbers Thomas Hilfert Daehie Hong Korea Kepa Iturralde Vineet Kamat Christian K. Karl

ETH Zurich, Switzerland Swedish Construction Fed. Carnegie Mellon Univ., USA Univ.of Alberta, Canada North Carolina State Univ., USA Osaka University, Japan Univ. Carlos III de Madrid, Spain Univ. of Southern California, USA Tech. Univ. Munich, Germany Tech. Univ. Munich, Germany Heriot-Watt Universitz University of Cambridge, UK Univ. Duisburg-Essen, Germany Ministry Edu.& Science, Russia Univ. of Texas at Austin, USA Univ. Polit. Marche Ancona, Italy Georgia Tech, USA Ntl. Taiwan Univ. Science & Tech. Ntl. Taiwan Univ., Taiwan R.O.C. Hong Kong Univ. Science & Tech. Ntl. Taiwan Univ. Science & Tech. Georgia Tech, USA Korea Inst. of Construction Tech. Univ. degli Studi di Brescia, Italy **RWTH Aachen** Ruhr-Universität Bochum, Germany Ruhr-Universität Bochum, Germany Istanbul Technical Univ., Turkey George Mason Univ., USA Ruhr-Universität Bochum, Germany Leeds Univ., United Kingdom Obavashi Corporation, Japan New York Univ. Abu Dhabi, UAE Univ. Politecnica de Madrid, Spain Slovak Univ. Technology, Slovakia Ruhr-Universität Bochum, Germany Illinois Institute of Technology, USA Univ. of Tech. Sydney, Australia University of Waterloo, Canada Concordia University, Canada Hanyang Univ., Republic of Korea McGill University, Canada Oulu University, Finland Ruhr-Universität Bochum, Germany Ruhr-Universität Bochum, Germany Univ. Seoul, Rep. Korea Tech. Univ.of Munich, Germany The Univ.of Michigan, USA Univ. Duisburg-Essen, Germany

Angelika Kelz Changwan Kim Huoungkwan Kim Iva Kovacic Soonwook Kwon Ghang Lee Jin-Kook Lee Junbok Lee Sanghoon Lee Karlheinz Lehner Christian Leifgen Nanli **Thomas Linner** Ming Lu Gunnar Lucko Elham Mahmoudi Jürgen Melzner Silvia M. Ventura Hannah Mattern Carol Manassa Osama Moselhi Mohammad Nahangi Ronie Navon Marcel Neuhausen Jens Otto Nipesh Pradhananga Benny Raphael Javad M. Sardroud Anoop Sattineni Markus Scheffer Kevin Schwabe Zevnep Seckin JongWon Seo Isaac Shabtai **Xuesong Shen** Kateryna Sigalov Miroslaw Skibniewski Arnim Spengler Univ. Piotr Szynkarczyk Meysam Taghavi Lavinia C. Tagliabue Koshy Varghese Xiangyu Wang Jan Weber **Trefor Williams** Józef W. Wajskova Frans van Gassel Ningshuang Zeng

Ruhr-Universität Bochum, Germany Chung-Ang Univ., Rep.of Korea Yonsei Univ., Republic of Korea Technical University Vienna, Austria Sungkyunkwan Univ., Rep of Korea Yonsei Univ., Republic of Korea Hanyang Univ., Republic of Korea Kyung Hee Univ., Republic of Korea Kyung Hee Univ., Republic of Korea Ruhr-Universität Bochum, Germany University of Darmstadt, Germany Tsinghua University. China Technical Univ. Munich, Germany University of Alberta, Canada Catholic University of America, USA Ruhr-Universität Bochum, Germany W. MARKGRAF GmbH & Co KG Politecnico di Milano, Italy Ruhr-Universität Bochum, Germany University of Michigan, USA Concordia University, Canada University of Toronto, Canada Technion, Israel Ruhr-Universität Bochum, Germany Tech. Univ. of Dresden, Germany Florida Intl. University, USA I.I.T. Madras, India Azad Univ. Central Tehran., Iran Auburn University, USA Ruhr-Universität Bochum, Germany Ruhr-Universität Bochum, Germany Ruhr-Universität Bochum, Germany Hanyang Univ. Seoul, Rep of Korea Israel Institute of Technology, Israel Univ. New South Wales, Australia Ruhr-Universität Bochum, Germany University of Maryland, USA Duisburg-Essen, Germany Industry Inst. Automation, Poland Technical Univ. Munich, Germany Univ. degli Studi di Brescia, Italy I.I.T. Madras, India Curtin Universit, y Australia Ruhr-Universität Bochum, Germany Rutgers University, USA Technical Academia, Poland Eindhoven Univ. Tech., Netherlands Ruhr-Universität Bochum, Germany

Program Schedule

	Friday July 20	Saturday July 21	Sunday July 22	Monday July 23	Tuesday Jul 24	Wednesday July 25
		Intl. AEC/FM Hackathon				
				ISARC 2018		
						Technical Tour
08:00 a.m.						
			Hacking			Construction
		Hacking	&	Keynotes	Keynotes	Site
Noon	Opening &	&	Team	&	&	Visits
	Workshops	Industry	Presentations	Academic	Academic	
		Dresentations		Drecentations	Drecentations	
06.00 m m	Decention 9	Presentations		Presentations	Presentations	
06:00 p.m.	Team		Prizes a			
	Building		ISARC		Awards &	
10.00 n m	Banding		Pacantian		Gala Dinnor	
10.00 p.m.			Reception		Gala Dinner	

Process of Verification of Earthworks Execution using Terrestrial Laser Scanning
A Data-driven Framework to Estimate Saving Potential of Buildings in Demand Response Events
Gaussian Markov Random Fields for Localizing Reinforcing Bars in Concrete Infrastructure
Influence of Upper Body with Dual Arms on Posture Control of Independently Driven Quadruped Crawler Robot
Multi-View Matching for Onsite Construction Resources with Combinatorial Optimization 1076 B. Zhang, Z. Zhu, A. Hammad and W. Aly 1076
Parametric BIM Façade Module Development For Diagrid Twisted Structures
Motion Data Based Construction Worker Training Support Tool: Case Study of Masonry Work
Radio-Frequency Identification Based Process Management for Production Line Balancing
Designing LiDAR-equipped UAV Platform for Structural Inspection
Research Trend Analysis for Construction Automation
Reassigning Construction Laborers based on Body Motion Analysis
Gaming Approach to Designing for Maintainability: A light Fixture Example
Computational Workspaces Management: A Workflow to Integrate Workspaces Dynamic Planning with 4D BIM
End-to-end Image-based Indoor Localization for Facility Operation and Management
The Module of Rebar Modeling for Chinese Building Standard Detailing Drawings by BIM-based Methods 1144 M. Yang, IC. Wu, C. J. Ku and L. Allan
Construction Process Simulation in Tunnel Construction – A Prerequisite for Automation
Trajectory-Based Worker Task Productivity Monitoring
Applying Object-oriented Analysis and Design to Digital Construction Logistics Planning from a Material Flow Perspective 1162 Z. Ningshuang, M. König and M. Chao
Construction Worker Detection and Tracking in Bird's-Eye View Camera Images
RobotEye Technology for Thermal Target Tracking Using Predictive Control
Using Wearable Devices to Explore the Relationship among the Work Productivity, Psychological State,

Computational workspaces management: a workflow to integrate workspaces dynamic planning with 4D BIM

V. Getuli^{a,b} and P. Capone^a

^{*a*}Department of Civil and Environmntal Engineering, University of Florence, Italy ^{*b*}Department of Architecture, Civil Engineering and Environmental Sciences, University of Braunschweig E-mail: <u>vito.getuli@unifi.it</u>, <u>pietro.capone@unifi.it</u>

Abstract

An effective realization of a building construction project -without incurring in congested site areas or decline of productivity- tightly depends on the construction activities planning process that, should consider and manage site workspaces availabilities. In this context, in the past couple of decades many research efforts have been spent in BIM which represents the process of preparation and use of a computer-generated Building Information Model (BIM) even if effective integrated methodologies and models to assist construction workspaces management are still missing in the field.

This contribution proposes an integrated model that aims to automate the creation of a building digital prototype, BIM-based, in which real site condition, in terms of workspaces allocation, are fully simulated. The outputs of a built-in algorithm to define the on-site workspaces configuration pattern based on the space syntax analysis together with a second one to automatically model workspaces geometries with minimizes input work are presented. Those algorithm are integrated in a coherent construction workspaces management workflow and tested on a simplified BIM of an industrial building, succeeding to allocate and model 611 workspaces required to construct 98 building items the BIM is composed of.

Keywords -

4D BIM; Construction workspace management; Scheduling; computational design.

1 Introduction

Whatever the type of building project under consideration, there is a need to produce a construction schedule that is considered a challenging activity for construction managers due to the number of variables they should consider especially resulting from the dynamic nature of the construction site. Considering its nature, which consist of different activities in limited area, it can be stated that '*workspace*' is the leading factor that is frequently overlooked in construction scheduling. In this sense, researches developed until now are limited in their ability to generate the workspace digital model for all activities of the building project for which workspaces are required. Most of them are focused on static 2D-based workspace models.

A practical motivation is that, since a building project is composed of a huge number activities, it is difficult for construction managers as well as researchers to automatically create at a time the workspace digital model for all the activities, due to the fact that it is a tedious work to generate the workspaces for many activities in the project using a 3D tool.

Riding this problem, the theoretical scope of this study is to automate the creation of a building digital prototype in which all the required workspaces to construct the building objects will be planned and modelled. To achieve this purpose, the use of 4D BIM and computational design will be integrated.

2 Background

2.1 Construction workspace management

Incorporating workspace considerations from the spatial and temporal perspective, in construction planning and scheduling, plays a pivotal role in proactively preventing work-space problems and decline of site productivity. According to [1], construction workspace management includes the following three branches.

1. First, generation and allocation of workspaces. In this regard, most of studies such as [2],[3],[4],[5] and [6] support the workspaces modelling by using manual mark-up in a 2D or 3D modelling environment. But, considering the number of required spaces for each construction activity to multiply by the huge number of activities a building project is composed of, design automation in spatial modelling is suggested but still missing in literature.

- 2. Second, detection of spatial temporal conflicts. In this context, three research branches can be identified: (a) detection of physical conflicts between the site workspaces; (b) detection of schedule conflict which means the detection of a temporal overlap between tasks that is mainly taken into account by the models which use traditional representation of the construction process (i.e., Gantt Chart and Network Diagrams); (c) site congestions identification [7] that considers the ratio between the volume of resources occupying a workspace and the volume of the workspace which is available on site for a given activity or a set of activities. Often defined as 'scheduling overlapping ratio' [8].
- 3. Third, *resolution of identified conflicts*. Regarding this aspect, the methodologies -proposed in literature- reveal the predominant use of mathematical models that, on one hand, are able to manage only a small part of a given building project due to the computational load entrusted to not specific calculation environment (e.g. Matlab), on the other hand require an extremely knowledgeable of the mathematical model itself which cannot be used by construction managers. For these reasons the almost always go unused.

3 Need and justification

Prevailing *activity-oriented* construction scheduling techniques -e.g., Gantt Chart, Network Diagram, Critical Path Method- are not able to consider spatial requirements of activities and for this reason the generated construction schedule is limited in capturing real site conditions. Moreover, more complex techniques -such as Line of Balance- have likewise insufficient ability for workspaces planning because they assume that only one labor crew is able to occupy each work-zone at a time and they lack of a 3-Dimensional representation and planning of spaces as well as spatial conflicts among themselves [9].

More recently, a new research trend of utilizing Building Information Modelling (BIM) and BIM-related technologies to assist construction scheduling is arising. It represents the process of preparation and use of a computer-generated Building Information Model [10], which is data-rich parametric digital representation of a building, from which relevant data, needed to support planning and scheduling of construction activities, could be extracted and used. But, in spite of its growing implementation, the use of BIM to improve construction planning has involved many efforts focusing on its technological aspects (i.e., 4D BIM-based tools) rather than on the integration with site planning models for construction workspaces management. Therefore, an holistic workspaces planning model -BIM compliant- able to consider, simulate and analyze space availability and demand for each building object, included in a given BIM, is still missing and it could support construction managers in reasoning on the construction schedules that feature specific construction methods and concurrent execution of overlapping activities.

4 Methodology

4.1 Goal and Objectives

For the aforementioned reasons, the overall goal of this research is to define a BIM-based construction planning model that automates the creation of a building digital prototype in which real site condition, in terms of workspaces, are simulated and it should be able to guide an external user (i.e., construction manager) to define the construction sequence that guarantees the nonoverlapping condition of the workspaces. In particular, this research makes the following contributions:

- it defines of a construction planning model which acts, logically and technically, on a given Building Information Model (IFC-based);
- it introduces an automated process for geometric planning and modelling of workspaces, within a BIM environment, by means of two built-in algorithm;
- it defines of a tool sets that communicate through an external data-base in which a construction manager introduces his experience in terms of workspaces requirements of construction methods;
- it guides a construction manager in defining the earliest construction sequence -visualized in 4D BIM-based simulation environment- of a given BIM to be processed.

The paper is organized as follows. First, the practical motivation for this research is introduced by using a case study together with the explanation of the working prototype. Next, an overview of the planning model and specifications about its operational framework and its computerization are given. Finally, an evaluation of this approach is provided, followed by a brief discussion of the on-going and future research.

4.2 Motivating case study and working prototype

This section describes a simplified case study that illustrates the practical motivation for this research on which the proposed workflow has been tested. An Information Model of an industrial building, structured



according to the IFC-data schema, is the input of this research.

Figure 1. Building Object of the case study

Taking into account its structural subsystem but leaving aside the building finishing, the given BIM is composed of five objects types: (a) Foundation Plinth eighteen items-; (b) *Precast Column* -eighteen items-; (c) *Precast Beam* -fifteen products-; (d) *Truss* -nineteen items- and (e) *Roofing Beam* -twenty-two elements-. Figure 1 shows the BIM filtered by type of building objects.

Trying to be a construction manager who receives the aforementioned BIM in order to define the optimal construction sequence, the proposed approach seeks to respond to the following open issues:

- Which kind of workspaces are necessary to install those five types of building objects?
- How all those workspaces should be located in site with reference to building object of which they handle the installation?
- Is it possible to automatically generate a workspaces allocation pattern using the construction manager's experience and automatically sculpt geometries of workspaces in a BIM modelling environment?
- Could it be possible to find and simulate a construction sequence by using a 4D BIM which, solving the issues mentioned above, guarantee the non-overlapping condition of workspaces?

It is clear that, to make BIMs useful for construction, all these specific information for construction site must be planned and explicit in the given information model in a way that construction managers can easily work with to better understand and plan their specific schedule which cannot be against to all those condition established in the model itself.

The architecture of the proposed solution to generate the building digital prototype in in which all the required workspaces are planned and simulated is represented in Figure 2.

The architecture shows that the planning process starts with three elements: first of all, a BIM and a structural schedule -due to the fact the latter does not depend on specific consideration but it defines the first scheduling constraints (e.g., plinths before columns, columns before beams, etc.)-; then the experience of the construction manager which is stored within an external database. It works as repository of information relevant to the workspace management process (planning and modelling) according to a predefined structure later specified.

The result is a 4D BIM Model that simulates all the required workspaces allocated in their optimal position that satisfies the conditions specified by the user (Figure 7). The computerization of such a theoretical algorithm will be described in the next paragraphs.

4.3 Problem solving approach and computerization

The proposed design process that reaches the aforementioned objects is composed by a number of operational modules in a coherent data management flow. They are graphically described in Figure 2 and briefly specified step-by-step as follows.

- 1. **Data extrapolation from the BIM**. Having at our disposal the BIM we are able to extract the following information: *number and types of building objects*, their *local placement on X, Y and Z-axis* (relative to the building grid axis). Those data are stored in an external database.
- 2. Workspaces Database preparation. For each object type a *Construction Method* (CM) is generated in an external database where the user adds a list of workspaces required by the CM itself in terms of *Labor Crew, Equipment, Hazard, Protected and Safety Spaces* according to his experience. For each space the following information are required: *Dimensions, Topological Interaction* with the other spaces and *Interaction Value*.
- 3. Workspaces planning process. Defined workspaces properties for each construction



Figure 2. Data management flow to generate the building digital prototype with workspaces in Figure 7

method, it remains to find their optimal layout allocation with reference to the building objects. This is carried out by using a configurational analysis based on *Space Syntax Analysis*. The workspaces configuration pattern is generated in the form of a planar graph by using a bubble diagram which is deduced by Nourian's algorithm [11] and especially customized for our model. It read workspaces information and provides as output the workspaces allocation coordinates for each construction method (Figure 3).

4. **Workspaces modelling process**. Reading the allocation coordinates of workspaces referred to each building objects a Dynamo's script -an algorithm editing environment for computational

design linked to a BIM modelling environmentautomatically sculpts the geometries. By doing so each building objects is simulated with a cloud around itself that is the non-visible volume in the building needed for execution of works. As depicted in Figure 4 for each construction method and and fully in Figure 7, 611 workspaces have been automatically simulated.

5. Workspaces conflicts checking process. The BIM that now includes the building objects and all the needed spaces is loaded in a 4D BIM environment (*Autodesk Navisworks*) to carry out a time-bases clash test on the basis of the structural schedule. By doing so a clash report is extracted, an example in Figure 5, with the pair of conflicted workspaces.



Figure 3.Planning process to find the workspaces allocation pattern around the precast column



Figure 4. Graphical outputs of the workspaces configuration pattern for the five construction methods



Figure 5. Graphical output of the workspaces conflict detection (*Navisworks Environment*) In the same environment a scheduling rule is

computerized that converts each conflict in a temporal relationship (finish-to-start) among the building objects whose spaces are conflicting.

The generated schedule can be considered the earliest construction sequence in the sense that if one activity will be shifted backwards a workspaces conflict will be detected.

Due to not enough spaces, the proposed workflow as well as the built-in algorithms are basically described in this contribution even if the outputs are presented and a more detailed explanation of the workspaces planning process is presented in the next paragraphs and Figure 6.

4.3.1 Workspaces planning: algorithm to generate the workspaces spatial allocation patterns

The proposed planning workflow is about going from an abstract graph description of workspaces topological structure and their interactions to find their optimal planar allocation with reference to the building object those spaces are linked. The computerization of such a concept has been possible with a built-in algorithm able to manage a parametric design workflow developed in *Grasshopper*©, (a graphical algorithm editor tightly integrated with a 3-D modelling environment). The proposed one is a customization of the one presented in [11]. It main operating steps are below presented and the graphically visualized in Figure 6 for the construction method of precast column installation.

- Workspaces graph representation. As starting 1. point, a number of randomly located points, representing the barycenter of the workspaces, are generated in a CAD environment by using a first operator. At the same time, two dimension values (has_Lenght, has_Width) and the identification numbers (has_ID) are imported from the external data-base. At this point, a set of operators, first assign colours to the workspaces to make them more recognizable and then generate one circle around each workspaces' center point. Their dimensions are deduced by the rectangular areas of workspaces as suggested by the user in the database itself; they are equal. In this way, a first workspaces map representation is generated. This is carried out for each construction methods included in the given BIM.
- 2. Workspaces connectivity graph. Subsequently, the representation of relationships between workspaces is managed by an operator that draws connections -by using a red line- between those pair of points that have a topological interaction (*has_Topological_Interaction*) set by the user within the data-base. The interaction value can be

in a rank from 0 -*no interaction*- to 5 -*indispensable interaction*-.

- 3. Space Syntax Analysis. Having generated the connectivity graph, according to the space syntax analysis, an operator re-distributes the workspaces (circles) on deph-levels. A *depth* is the smallest number of syntactic steps (in topological meaning) that are needed to reach one space from another. Therefore, depending on the number of workspaces that each construction methods contains -e.g. five spaces for the column installationone configuration for each space by using depth levels is generated. It represents the point of view of a labourer getting in position in that workspace on 'depth-0'. The generated graphs are used for a visual validation from the construction manager who has defined the workspaces (user) requirements in the data-base itself.
- 4. Generation of the workspaces allocation pattern. Once the model is provided with workspaces connectivity values, the algorithm contains a forcedirected graph-drawing operator which is able to generate a bubble diagram representing the optimal workspaces allocation pattern based on userconstraints set in the data-base. This function works translating the interaction values between workspaces (has Interaction Value) in a set of attractive forces. The forces act recursively on the graph vertices, seek a 'relax' situation for a graph, and provide the system with a graphical representation of the given solution. The output is a bubble diagram -once again one for each construction method included in the modelcompliant with the specified workspaces dimensions and the connectivity values.
- 5. Extrapolation of workspaces spatial coordinates. Once a workspaces configuration pattern is deducted, the spatial allocation coordinates -on the X-axis and Y-axis- from the bubble diagram are extracted and stored in the external database. The model considers those workspaces as located at the same height (Z-axis) of their connected building object.

5 Discussion and future development

The obtained results show how the layout allocations of spaces cannot be considered never fixed but they strictly depend on both the chosen construction method and planning rules. Infact, the space syntax analysis, carried



Figure 6. Workspaces planning process: Construction method of precast column installation

out on five different construction methods, demonstrated that even if workspaces had the same dimensions, their layout allocations may be different depending on their relations as well as their interaction values.

Moreover, it demonstrates how important should be the integration of human experiences even in BIM-based scheduling models as well as the pretty unbreakable bond that exists between a construction schedule and the spatial allocation of workspaces and their topological interactions.

The proposed workflow, supported by the two integrated algorithm, was capable to plan and model 611 workspaces by binding the scheduling process to them (Figure 7). The same process would be unsustainable if manually managed or without a holistic and digitized planning process. This requirement increases if we think that if some changes occur (e.g., construction methods, workspaces, building product dimensions, etc.) all the entities should be modelled again. The presented construction scheduling workflow is a part of a wider research project the author are working on that aims to develop an *BIM-based Expert System* supported by an ontology based system architecture (for semantic modelling the construction process knowledge) integrated with a rule-based artificial intelligence (for workspaces management and schedule generation).

- [5] Guo, S., J. Identification and resolution of work space conflicts in building construction. *Journal of Construction Engineering and Management* (ASCE) (128): 287–295, 2002.
- [6] Dawood, N., D. Scott, E. Sriprasert, and Z. Mallasi. The virtual construction site (VIRCON) tools: An industrial evaluation. *Journal of Information Technology in Construction* (Special Issue: From 3D to nD modelling) (10): 43-54, 2005.
- [7] Zhang, S et al., Workforce location tracking to



Figure 7. BIM-based site digital prototype with all the required workspaces to construct the building objects

References

- [1] Kassem M., Dawood N., Chavada R., Construction workspace management within an Industry Foundation Class-Compliant 4D tool. *Automation in Construction*, (52):42-58, 2015.
- [2] Thabet W. and Beliveau Y., Modeling work space to schedule repetitive floors in multistory buildings. *Journal of Construction Engineering and Management* (1):96–116, 1994
- [3] Riley D., R., and Sanvido V., Space planning method for multistory building construction. *Journal of Construction Engineering and Management* (ASCE) 171–180, 1997.
- [4] Akinci, B., and J. Kunz, R. Levitt M. Fischer. Representing Work Spaces Generically in Construction Method Models. *CIFE Working paper* (Stanford University), 2000.

model, visualize and analyze workspace requirements in building information models for construction safety planning. *Automation in Construction* (60): 74-86, 2015.

- [8] Moon H., et al., BIM-based Construction Scheduling Method Using Optimization Theory for Reducing Activity Overlaps. *Journal of Computing in Civil Engineering* (ASCE) 29 (3), 2015.
- [9] Isaac S., Su Y. and Lucko G., Integrated Activity Scheduling and Site Layout Planning, *Proceeding* of 34th International Symposium on Automation and Robotics in Construction (ISARC 2017), 2017.
- [10] Azhar, S., M. Hein, and B. Sketo. Building Information Modeling (BIM): benefits, risks and challenger. *Proceedings of the 44th ASC Annual Conference*, 627-634, Alabama, 2008.
- [11] Nourian et al. A configurative approach to architectural layout, proposing a computational methodology, *Proceeding of eCAADe*, (31) 357-365, 2013