An Introduction to Barenblatt Solutions for Anisotropic *p*-Laplace Equations



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To celebrate the 60th genethliac of Massimo Cicognani and Michael Reissig.

Abstract We introduce Fundamental solutions of Barenblatt type for the equation

$$u_{t} = \sum_{i=1}^{N} \left(|u_{x_{i}}|^{p_{i}-2} u_{x_{i}} \right)_{x_{i}}, \qquad p_{i} > 2 \quad \forall i = 1, .., N, \qquad \text{on} \quad \Sigma_{T} = \mathbb{R}^{N} \times [0, T],$$
(1)

and we prove their importance for the regularity properties of the solutions.

Keywords Degenerate orthotropic parabolic equations $\cdot p$ -Laplace \cdot Anisotropic \cdot Barenblatt fundamental solution \cdot Self-similarity

1 Introduction

Consider the Cauchy problem

$$\begin{cases} u_t = \operatorname{div} A(x, u, Du), & \text{in } \Sigma_T = \mathbb{R}^N \times (0, T), \\ u(x, 0) = M\delta(x), \end{cases}$$
(2)

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[©] The Author(s), under exclusive license to Springer Nature Switzerland AG 2021 M. Cicognani et al. (eds.), *Anomalies in Partial Differential Equations*, Springer INdAM Series 43, https://doi.org/10.1007/978-3-030-61346-4_5

where M > 0, initial datum is the Dirac function $\delta(x)$, the field $A : \Sigma_T \times \mathbb{R} \times \mathbb{R}^N \to \mathbb{R}^N$ is only measurable and has an anisotropic behavior

$$\begin{cases} A_i(x, s, z)z_i \ge \Lambda^* |z_i|^{p_i} \\ |A_i(x, s, z)| \le \Lambda_* |z_i|^{p_i - 1}, \end{cases}$$
(3)

for some constants Λ^* , $\Lambda_* > 0$ and $p_i > 2$ for any $i \in \{1, ..., N\}$. We recall that when all p_i s are greater than 2 the equation is called degenerate. In order to have the existence of solutions, we require the following monotonicity property to the field *A*:

$$[A(x, s, \xi) - A(x, s, \zeta)] \cdot [\xi - \zeta] > 0, \qquad \forall \quad \xi \neq \zeta \quad \text{in} \quad \mathbb{R}^N.$$
(4)

When $p_i \equiv p$ Eq. (2) is named the orthotropic *p*-Laplace, and has nevertheless a different behavior from the classic *p*-Laplace, as its principal part evolves in a way dictated only by the growth in the *i*-th direction. The problem (2) reflects the modeling of many materials that reveal different diffusion rates along different directions, such as liquid crystals, wood or earth's crust (see [26]). Moreover, as shown in [14] the solution to this equation have finite speed of propagation. Note that this is a more reasonable assumption than the usual infinite-speed typical of heat equation, for most of the physical phenomena.

1.1 The Open Problem of Regularity

The strong nonlinear character and in particular the anisotropy which is prescribed by Eq. (2) has proved to be a hard challenge from the regularity point of view. The main difference with standard non linear regularity theory is the growth (3) of the operator A, usually referred to as *non standard growth* (see [1, 5]). This opens the way to a new class of function spaces, called anisotropic Sobolev spaces (see next Section), and whose study is still open and challenging. Even in the elliptic case, the regularity theory for such equations requires a bound on the sparseness of the powers p_i . For instance in the general case the weak solution can be unbounded, as proved in [16, 20]. However, the boundedness of solutions was proved in [5] under the assumption that

$$\overline{p} < N, \quad \max\{p_1, ..., p_N\} < \overline{p}^*, \tag{5}$$

where

$$\overline{p} := \left(\frac{1}{N} \sum_{i=1}^{N} \frac{1}{p_i}\right)^{-1}, \qquad \overline{p}^* := \frac{N\overline{p}}{N - \overline{p}}.$$
(6)

Regularity properties are proved only on strong assumptions on the regularity of the coefficients (see [15, 21, 22]). Even in the elliptic case, when the coefficients are rough, Hölder continuity remains still nowadays an open problem. Indeed, continuity conditioned to boundedness has been proved in [13] by means of intrinsic scaling method, but with a condition of stability on the exponents p_i which is only qualitative. Removability of singularities has been considered in [28]. We refer to [15] and [24] for a complete survey on the subject and related bibliography.

1.2 Aim of the Note

We will consider the homogeneous prototype problem

$$\begin{cases} u_t = \sum_{i=1}^{N} \left(|u_{x_i}|^{p_i - 2} u_{x_i} \right)_{x_i}, & \text{in } \Sigma_T = \mathbb{R}^N \times (0, T), \\ u(x, 0) = \delta_o. \end{cases}$$

The purpose of this note is to show the importance of a Barenblatt Fundamental solution \mathcal{B} to this equation, paralleling the construction of Fundamental solutions for the *p*-Laplace equation. We will show a fundamental connection between the previous equation and a particular Fokker-Planck equation, as proved for the porous medium equation by Carrillo and Toscani [7]. The achievement of such Fundamental solution would provide important tools for the study of regularity of parabolic anisotropic problems as (2). As we will see in the sequel, the problem is more delicate than in the isotropic case, because of the lack of radial solutions. In the isotropic case the adoption of radial symmetry brings the equation, set in a proper scale, to a solvable ODE. In the doubly nonlinear case, a non-explicit Barenblatt Fundamental solution has been found with this approach in [23], using a Leray-Schauder technique. Also in mathematical physics, the use of radial solution is usual. For instance this strategy can be used for the Navier Stokes equation (see [17]). In our case, as already stated, the anisotropy does not allow the use of radial solutions, and this fact compels us to look for new ideas.

2 Preliminaries

2.1 Self-Similar Fundamental solutions, Motivations and Historical Perspectives

The issue of finding Fundamental solutions to elliptic and parabolic equations is one of paramount importance in the study of linear elliptic and parabolic equations (see [11]). In nonlinear theory their role is not so evident, and yet the epithet "Fundamental" is iconic, because representation in terms of kernels usually fails. But they are a tool of extraordinary importance in the existence and regularity theory as well as very important to describe the asymptotic behaviour, that's why the name Fundamental Solutions is deserved. Much more information about techniques to be employed, sharp-condition examples and counterexamples can be extracted from the knowledge of a Fundamental solution. A typical example is the Barenblatt Fundamental Solution

$$\mathcal{B}(x,t) = t^{-\frac{N}{\lambda}} \left\{ 1 - \gamma_p \left(\frac{|x|}{t^{\frac{1}{\lambda}}} \right)^{\frac{p}{p-1}} \right\}_+^{\frac{p-1}{p-2}}, \quad t > 0,$$

for the *p*-Laplace equation

$$u_t = \operatorname{div}(|\nabla u|^{p-2} \nabla u), \quad \text{in} \quad [0, T] \times \mathbb{R}^N, \quad p > 1.$$
(7)

These special solutions can be used to reveal a gap between the elliptic theory and the corresponding parabolic one for *p*-Laplace type equations. Indeed solutions to

$$\operatorname{div}(|\nabla u|^{p-2}\nabla u) = 0, \quad u \in W_{loc}^{1,p}(\Omega), \quad p > 1,$$
(8)

do obey to a Harnack inequality (see [27]), while the corresponding solutions to the parabolic version of (8) do not in general. We show this briefly. Let (x_0, t_0) be a point of the boundary of the support of \mathcal{B} , the free boundary $\{t = |x|^{\lambda}\}$, and let $\rho > 0$. The ball $B_{\rho}(x_0)$ intersects at the time level $t_0 - \rho^p$ the support of $x \to \mathcal{B}(x, t_0 - \rho^p)$ in an open set, hence

$$\mathcal{B}(x_0, t_0) = 0$$
, but $\sup_{B_{\rho}(x_0)} \mathcal{B}(x, t_0 - \rho^p) > 0$.

Generalizing the classical heat equation to nonlinear versions, another chief example in evolution theories is the Porous Medium Equation

$$u_t - \Delta(u^m) = 0, \quad m > 1.$$
 (9)

This equation, introduced in the last century in connection with a number of physical applications, has been extensively studied (see the monograph [31]) in parallel to the *p*-Laplace as another prototype of nonlinear diffusive evolution equation, with interest also in the geometry of free boundaries. Fundamental solutions were discovered in 1950's by Zeldovich and Kompanyeets in [32] and Barenblatt [2], and later a complete description has been brought by Pattle in [25]. The discovery of these explicit solutions, usually called Barenblatt solutions since then, has been the starting point of the rigorous mathematical theory that has been gradually developed since then.

The surprising relation between existence and uniqueness of Fundamental solutions and precise asymptotic behaviour relies on the existence of a scaling group under whose action the solutions to the equation are invariant. This implies that a Fundamental solution is self-similar: this is what we call a *Barenblatt solution*. Self-similarity has big relevance for the understanding of Fundamental processes in mathematics and physics, as described in [4]. Self-similar phenomena got in mathematical physics quite early, perhaps with the famous work of Fourier in 1822 on the analytical theory of heat conduction. In this memoir he performed a construction of a *source-type* solution

$$u(x,t) = \frac{A}{\sqrt{t}} f\left(\frac{x}{\sqrt{t}}\right), \text{ for } f(\zeta) = e^{-\frac{\zeta^2}{A}}, A > 0,$$

to the heat conduction equation

$$u_t = \Delta u. \tag{10}$$

Subsequently the phenomena under consideration and their mathematical models became increasingly complicated and very often nonlinear. To obtain self-similar solutions was considered a success in the pre-computer era. Indeed, the construction of such solutions always reduces the problem to solving the boundary value problems for an ODE, which is a substantial simplification, as we will see in [3]. Furthermore, in 'self-similar' coordinates (as $u\sqrt{t}$, x/\sqrt{t} for (10)), self-similar phenomena become time independent. This enlightens a certain type of stabilization. Thus during the pre-computer era, the achievement of a self-similar solution was the only way to understand the qualitative features of the phenomena, and the exponents of the independent variables x, t in self-similar variables were obtained often by dimensional analysis. Dimensional analysis is merely a simple sequence of rules based on the Fundamental covariance principle of physics: all physical laws can be represented in a form which is equally valid for all observers.

The very idea of self-similarity is connected with the *group of transformations* of solutions (see [3]). These groups are already present in the differential equations of the process and are determined by the dimensions of the variables appearing in them: the transformations of the units of time, length, mass, etc. are the simplest examples. This kind of self-similarity is obtained by power laws with exponents that are simple fractions defined in an elementary way from dimensional considerations. Such a course of argument has led to results of immense and permanent importance, as the theory of turbulence and the Reynolds number, of linear and nonlinear heat propagation from a point source, and of a point explosion. Moreover it has enlightened the way toward to a nonlinear theory developed by DiBenedetto [10] with the nowadays well-known method of intrinsic scaling (see also [29]).

The Group of Transformations for the *p*-Laplace Equation

Let us examine the group of transformations under scaling of the p-Laplace equation

$$u_t = \operatorname{div}(|\nabla u|^{p-2} \nabla u).$$

We apply the following dilation in all variables

$$u' = Ku, \qquad x' = Lx, \qquad t' = Tt,$$

and impose that the function u' so defined

$$u'(x',t') = Ku\left(\frac{x'}{L},\frac{t'}{T}\right),\tag{11}$$

is again a solution to the *p*-Laplace equation above. Then by the simple calculations

$$u_{t'} = \frac{K}{T} u_t \left(\frac{x'}{L}, \frac{t'}{T} \right), \quad |\nabla_{x'} u'| = \frac{K}{L} |\nabla u|$$

we arrive to the conclusion that u' is a solution to the *p*-Laplace equation if and only if

$$TK^{p-2} = L^p.$$

So we obtain a two-parametric transformation group $\mathcal{T}(L, T)$ acting on the set of solutions of the *p*-Laplace equation:

$$(\mathcal{T}u)(x,t) = \left(\frac{L^p}{T}\right)^{\frac{1}{p-2}} u\left(\frac{x}{L}, \frac{t}{T}\right).$$
(12)

and we can conclude the following Lemma.

Lemma 1 If u is a solution to the p-Laplace equation in a certain class of solutions S which is closed under dilation in x, t, u, then (Tu) given by (12) is again a solution to the equation in the same class S.

Those special solutions that are themselves invariant under the scaling group are called *self similar-solutions*: this means that $(\mathcal{T}u)(x, t) = u(x, t)$ for all (x, t) in the domain of definition, which has to be itself scale-invariant.

Suppose now that we have an important information, such as (27) or conservation of mass. We want to use some of the free parameters to force \mathcal{T} to preserve this important behaviour of the orbit. Analytically it consists in imposing a new relation between two independent parameters, as *K* and *L* for instance, and in reducing the

transformation to a one-parameter family of scaled functions. Thus we set

$$K = L^{-\chi},\tag{13}$$

and consequently

$$K = T^{-\alpha}, \qquad L = T^{\beta},$$

with α , β , χ linked by conserving the equation:

$$\alpha(p,\chi) = \frac{\chi}{\chi(p-2)+2}, \qquad \beta(p,\chi) = \frac{1}{\chi(p-2)+2}, \quad \text{unless} \quad \chi = \frac{-2}{(p-2)}.$$

Observing that $\chi = \alpha/\beta$, the equation changes into

$$(\mathcal{T}u)(x,t) = T^{-\alpha}u(x/T^{\beta},t/T), \qquad (14)$$

where α , β are linked by $\alpha(p-2) + \beta = 1$. The condition of preserving the initial mass is

$$\int_{\mathbb{R}^N} K u_0\left(\frac{x}{L}\right) dx = \int_{\mathbb{R}^N} (\mathcal{T} u_0)(x) dx = \int_{\mathbb{R}^N} u_0(x) dx \tag{15}$$

which obliges $KL^N = 1$, so that the one parameter family \mathcal{T} will be given by

$$\alpha = \frac{N}{N(p-2)+2}, \qquad \beta = \frac{1}{N(p-2)+2}, \qquad p > 2.$$
(16)

Observe the formula for the transformation of the initial data (which obviously must satisfy the same transformation) must be

$$(\mathcal{T}u_0)(x) = T^{-\frac{N}{\lambda}} u_0\left(\frac{x}{T^{\frac{1}{\lambda}}}\right), \qquad \lambda = N(p-2) + p.$$
(17)

In the case of Barenblatt Fundamental solution (24) the couple (x, t) is fixed as a single variable so that

$$u(x,t) = t^{-\alpha} u(xt^{-\beta}, 1) = t^{-\alpha} F(xt^{-\beta}),$$
(18)

where $F(\eta) = u(\eta, 1)$ is the *profile* of the solution.

Remark 1 A complete theory of existence and uniqueness for the main equation would allow us to obtain self-similar solutions almost for free. Indeed we can consider the solution to the Cauchy problem for scale invariant data, and then use uniqueness to show that this must be self-similar. Let the initial data for instance be

of the form

$$u'(x) = \frac{G(\xi)}{|x|^{\chi}}, \quad \chi \in \mathbb{R}, \ \xi = \frac{x}{|x|}, \text{ and } G : \mathbb{S}^{N-1} \to \mathbb{R}.$$

Let us suppose that we are able to solve with uniqueness the Cauchy problem for our equation with this initial data, say the solution is u. We produce another solution to the same equation by $\mathcal{T}(u)$ given by (11) and if $K = L^{-\chi}$ then the transformed initial data is the same one:

$$(\mathcal{T}u)(x,0) = KG(\xi) \left| \frac{x}{L} \right|^{-\chi} = u(x,0)$$

and so u and $\mathcal{T}(u)$ solve the same Cauchy problem and u is self-similar.

2.2 Notation and Settings

Given $\mathbf{p} := (p_1, ..., p_N)$, $\mathbf{p} > 1$ with the usual meaning, we assume that the harmonic mean is smaller than the dimension of the space variables

$$\overline{p} := \left(\frac{1}{N} \sum_{i=1}^{N} \frac{1}{p_i}\right)^{-1} < N,$$
(19)

and we define the Sobolev exponent of the harmonic mean \overline{p} ,

$$\overline{p}^* := \frac{N\overline{p}}{N-\overline{p}}.$$
(20)

We will suppose without loss of generality along this note that the p_i s are ordered increasingly. Next we introduce the natural parabolic anisotropic spaces. Given T > 0 and a bounded open set $\Omega \subset \mathbb{R}$ we define

$$\begin{split} W_{o}^{1,\mathbf{p}}(\Omega) &:= \{ u \in W_{o}^{1,1}(\Omega) | \ D_{i}u \in L^{p_{i}}(\Omega) \} \\ W_{loc}^{1,\mathbf{p}}(\Omega) &:= \{ u \in L_{loc}^{1}(\Omega) | \ D_{i}u \in L_{loc}^{p_{i}}(\Omega) \} \\ L^{\mathbf{p}}(0,T; W_{o}^{1,\mathbf{p}}(\Omega)) &:= \{ u \in L^{1}(0,T; W_{o}^{1,1}(\Omega)) | \ D_{i}u \in L^{p_{i}}(0,T; L_{loc}^{p_{i}}(\Omega)) \} \\ L^{\mathbf{p}}_{loc}(0,T; W_{o}^{1,\mathbf{p}}(\Omega)) &:= \{ u \in L_{loc}^{1}(0,T; W_{o}^{1,1}(\Omega)) | \ D_{i}u \in L_{loc}^{p_{i}}(0,T; L_{loc}^{p_{i}}(\Omega)) \} \end{split}$$

Now let *A* be a measurable vector field satisfying the growth conditions (3). By a *local weak solution* of

$$u_t = \operatorname{div} A(x, u, Du), \quad (x, t) \in \Sigma_T,$$

we understand a function $u \in C^0_{loc}(0, T; L^2_{loc}(\mathbb{R}^N)) \cap L^{\mathbf{p}}_{loc}(0, T; W^{1,\mathbf{p}}(\mathbb{R}^N))$ such that for all $0 < t_1 < t_2 < T$ and any test function $\varphi \in C^{\infty}_{loc}(0, T; C^{\infty}_o(\mathbb{R}^N))$ satisfies

$$\int u\varphi \, dx \Big|_{t_1}^{t_2} + \int_{t_1}^{t_2} \int (-u\,\varphi_t + A(x, u, Du) \cdot D\varphi) \, dx \, dt = 0, \tag{21}$$

where the integral is assumed to be in \mathbb{R}^N when no domain has been specified. By a density and approximation argument this actually holds for any test function of the kind $\varphi \in W_{loc}^{1,2}(0, T; L_{loc}^2(\mathbb{R}^n)) \cap L_{loc}^{\mathbf{p}}(0, T; W_o^{1,\mathbf{p}}(\Omega))$ for any semirectangular domain $\Omega \subset \mathbb{R}^N$ (see [18] for a discussion on anisotropic embeddings and semirectangular domains).

Remark 2 We further give the definition of solution to the prototype equation (1) with L^1 initial data, to be used during the development of our work.

A measurable function $(x, t) \rightarrow u(x, t)$ defined in Σ_T is a *weak solution* to the Cauchy Problem (2) with L^1 initial data if for every bounded open set $\Omega \subset \mathbb{R}$, if

$$u \in C(0, T; L^{1}(\Omega)) \cap L^{\mathbf{p}}(0, T; W^{1, \mathbf{p}}(\Omega)),$$
 and

$$\int_{\Omega} u(x,t)\varphi(x,t)dx + \int_{0}^{t} \int_{\Omega} \{-u\varphi_{t} + \sum_{i=1}^{N} |D_{i}u|^{p_{i}-2} D_{i}uD_{i}\varphi\}dxd\tau$$

$$= \int_{\Omega} u_{0}(x)\varphi(x,0)dx,$$
(22)

for all 0 < t < T and all test functions $\varphi \in C^{\infty}(0, T; C_o^{\infty}(\Omega))$.

Weak subsolutions (resp. supersolutions) are defined as above except that in (22) equality is replaced by \leq (resp. \geq) and test functions $\varphi \geq 0$ are taken to be nonnegative.

3 A Self-Similar Solution to the *p*-Laplace Equation

Consider the equation

$$\begin{cases} u \in C_{loc}(0, T; L^{2}_{loc}(\mathbb{R}^{N})) \cap L^{p}_{loc}(0, T; W^{1, p}_{loc}(\mathbb{R}^{N}), \\ u_{t} - \operatorname{div}(|\nabla u|^{p-2} \nabla u) = 0, \quad \text{in} \quad \Sigma_{T} = \mathbb{R}^{N} \times (0, T). \end{cases}$$
(23)

In this case we recover the classic p-Laplace equation, and we can write explicitly its self-similarity source-solution since the work of Barenblatt [2] as

$$\mathcal{B}(x,t) = t^{-\frac{N}{\lambda}} \left\{ 1 - \gamma_p \left(\frac{|x|}{t^{\frac{1}{\lambda}}} \right)^{\frac{p}{p-1}} \right\}_+^{\frac{p-1}{p-2}}, \quad t > 0$$
(24)

with

$$\lambda = N(p-2) + p, \qquad \gamma_p = \left(\frac{1}{\lambda}\right)^{\frac{1}{p-1}} \frac{p-2}{p}.$$
 (25)

We observe that $\mathcal B$ satisfies the self-similar transformation (18). This function $\mathcal B$ solves the Cauchy problem

$$\begin{cases} u_t - \operatorname{div}(|\nabla u|^{p-2}\nabla u) = 0, & \text{in } \mathbb{R}^N \times (0, \infty), \\ \mathcal{B}(\cdot, 0) = M\delta_o, \end{cases}$$
(26)

where δ_o is the Dirac measure concentrated at the origin and for every t > 0 the mass $M = \|\mathcal{B}(\cdot, t)\|_{L^1(\mathbb{R}^N)}$ is conserved. The initial datum is taken in the sense of measures, which is, for every $\varphi \in C_o(\mathbb{R}^N)$

$$\int_{\mathbb{R}^N} \mathcal{B}(x,t)\varphi\,dx \to M\varphi(0), \quad \text{as} \quad t \downarrow 0.$$

For t > 0 and every $\rho > 0$ we have the important bound

$$\|\mathcal{B}(\cdot,t)\|_{L^{\infty}(K_{\rho})} = t^{-\frac{N}{\lambda}},$$
(27)

being K_{ρ} the cube of edge ρ . The explicit function \mathcal{B} is classically named Fundamental solution in literature, because it converges pointwise in Σ_T to the heat kernel $\Gamma(x, t)$ when p approaches 2,

$$\mathcal{B}(x,t) \to (4\pi)^{N/2} \Gamma(x,t) = \frac{1}{t^{N/2}} e^{-\frac{|x|^2}{4t}}, \text{ if } p \downarrow 2,$$

but the name does not refer to the kernel property i.e. solutions to (23) are not representable as convolutions of \mathcal{B} with initial data. Nevertheless all non-negative solutions to (23) behave as $t \downarrow 0$ like the Fundamental solution \mathcal{B} , and as $|x| \rightarrow \infty$ they grow no faster than $|x|^{p/(p-2)}$. Barenblatt Fundamental solutions \mathcal{B} are useful, together with the comparison principle, for proving an intrinsic Harnack estimate (see further Sect. 5), uniqueness in existence with L^1 data (as in [19]), and more generally to understand the behavior of solutions from the point of view of the physics. In this way, a suitable revisiting of the linear theory had been shaped to face nonlinear equations as the *p*-Laplace. It is possible to build Barenblatt Fundamental solutions centered in \bar{x} with initial datum at a time \bar{t} in the following way

$$\mathcal{B}_{k,\rho}(x,t,\bar{x},\bar{t}) = \frac{k\rho^N}{S^{\frac{N}{\lambda}}(t)} \left\{ 1 - \left(\frac{|x-\bar{x}|}{S^{\frac{1}{\lambda}}(t)}\right)^{\frac{p}{p-1}} \right\}_+^{\frac{p-1}{p-2}}, \qquad \lambda = N(p-2) + p, \quad (28)$$

with

$$S(t) = \lambda \left(\frac{p}{p-2}\right)^{p-1} k^{p-2} \rho^{N(p-2)} (t-\bar{t}) + \rho^{\lambda}.$$
 (29)

These functions enjoy the following important properties.

- 1. They are weak solutions to (23) in $\mathbb{R}^N \times \{t > \overline{t}\}$.
- 2. If we fix $t = \bar{t}$ then $B_{k,\rho} \equiv 0$ for all $x \in \left(\mathbb{R}^N B_\rho(\bar{x})\right)$ and for $t > \bar{t}$ the function $x \to B_{k,\rho}$ vanishes, in a C^1 fashion, across the boundary of the ball $\{|x \bar{x}| < S^{\frac{1}{\lambda}}(t)\}$.

Their support evolves compactly:

$$\operatorname{supp}\left(B_{k,\rho}(x,t,\bar{x},\bar{t})\right) = \left\{|x-\bar{x}| \le S^{\frac{1}{\lambda}}(t)\right\} \times [\bar{t},t^*],\tag{30}$$

thus

$$\sup\left(B_{k,\rho}(x,t,\bar{x},\bar{t})\right) \subseteq B_{S^{1/\lambda}(t^*)}(\bar{x}) \times [\bar{t},t^*].$$
(31)

3. They are bounded for fixed ρ and $k \in \mathbb{R}^+$:

$$B_{k,\rho}(x,t,\bar{x},\bar{t}) \le k, \qquad x \in \mathbb{R}^N.$$
(32)

In the sequel when no explicit formula for a solution as (28) (as in (1)), we will refer to a Barenblatt Fundamental Solution as a function (resp. to (1)) satisfying properties analogous to 1–3 above.

3.1 The Construction of B: Reduction to an Isotropic Fokker-Planck Equation

As far as we know if we look for a Barenblatt Fundamental solution as \mathcal{B} , we have to impose the condition (27), because this is the behaviour that non-negative solutions to the *p*-Laplace Cauchy problem with the right decay of the initial datum

do satisfy (see [10] Theorem 4.5). This motivates us to apply the following (formal) transformations to Eq. (23) and

$$\begin{cases} u(x,t) = t^{-\frac{N}{\lambda}} v(xt^{\alpha},t) = v(y,t), \\ y = xt^{\alpha}, \qquad \alpha = -\frac{1}{\lambda}, \end{cases} \implies \begin{cases} u_x = t^{-\frac{N}{\lambda}} v_y y_x = t^{\alpha - \frac{N}{\lambda}} v_y, \\ \frac{\partial}{\partial x} = t^{\alpha} \frac{\partial}{\partial y}. \end{cases}$$
(33)

Remark 3 We notice that the applied transformation does not belong to the group of transformations (12), so we expect that Eq. (23) turns into another one. This is what is called in [30] the continuous rescaling: as the change of variables (33) belongs to the transformation group only for the fixed time t = 1, source-type solutions transform into stationary profiles of the transformed equation.

By direct calculation we obtain

$$u_t = -\frac{N}{\lambda} t^{-\frac{N}{\lambda} - 1} v + t^{-\frac{N}{\lambda}} \left[\sum_{i=1}^N v_{y_i}(y_i)_t + v_t \right] = -\frac{N}{\lambda} t^{-\frac{N}{\lambda} - 1} v + t^{-\frac{N}{\lambda}} \left[\nabla_y v \cdot \frac{\alpha y}{t} + v_t \right]$$

and

$$\nabla_x u = t^{\alpha - \frac{N}{\lambda}} \nabla_y v. \tag{34}$$

We set

$$\tilde{v}(y,\tilde{t}) = \tilde{v}(y,\ln(t)) = v(y,t), \quad \Rightarrow \quad \tilde{v}_t = \tilde{v}_{\tilde{t}}t^{-1} = v_t$$
(35)

and Eq. (23) becomes, by multiplying it for $t^{\frac{N}{\lambda}+1}$

$$\begin{split} \tilde{v}_{\tilde{t}} &= \frac{N}{\lambda} v - \frac{N}{\lambda} \nabla_{y} \tilde{v} \cdot y + t^{\alpha} \nabla_{y} \cdot \left[t^{(\alpha - \frac{N}{\lambda})(p-1)} |\nabla_{y} \tilde{v}|^{p-2} \nabla_{y} \tilde{v} \right] t^{\frac{N}{\lambda} + 1} = \\ & \frac{N}{\lambda} v - \frac{N}{\lambda} \nabla_{y} \tilde{v} \cdot y + \nabla_{y} \cdot \left[|\nabla_{y} \tilde{v}|^{p-2} \nabla_{y} \tilde{v} \right] t^{\alpha + (\alpha - \frac{N}{\lambda})(p-1) + \frac{N}{\lambda} + 1} = \\ & \frac{N}{\lambda} v - \frac{N}{\lambda} \nabla_{y} \tilde{v} \cdot y + \nabla_{y} \cdot \left[|\nabla_{y} \tilde{v}|^{p-2} \nabla_{y} \tilde{v} \right], \end{split}$$

being $\alpha = -\frac{1}{\lambda}$. So we obtain the isotropic Fokker-Planck equation

$$\tilde{v}_{\tilde{t}} = \nabla_{y} \cdot \left(|\nabla_{y} \tilde{v}|^{p-2} \nabla_{y} \tilde{v} + \frac{y \tilde{v}}{\lambda} \right).$$
(36)

3.2 Barenblatt Solution Solves the Isotropic Fokker Planck Equation

Consider the Barenblatt function $\mathcal{B}(x, t)$, with explicitly scaled space variables

$$\mathcal{B}(x,t) = t^{-\frac{N}{\lambda}} \left\{ 1 - \gamma_p \left(\sqrt{\sum_{i=1}^{N} \left(\frac{x_i}{t^{\frac{1}{\lambda}}} \right)^2} \right)^{\frac{p}{p-1}} \right\}_+^{\frac{p-1}{p-2}}.$$
 (37)

We claim that $\mathcal B$ solves the stationary version of (36), by taking the flux to be zero, i.e.

$$|\nabla_{\mathbf{y}}\tilde{v}|^{p-2}\nabla_{\mathbf{y}}\tilde{v}+\frac{\mathbf{y}\tilde{v}}{\lambda}=0.$$

We have, by setting $y_i = x_i t^{-\frac{1}{\lambda}}$, that

$$\mathcal{B}(y,t) = t^{-\frac{N}{\lambda}} \left\{ 1 - \gamma_p |y|^{\frac{p}{p-1}} \right\}_{+}^{\frac{p-1}{p-2}} = t^{-\frac{N}{\lambda}} \left\{ 1 - \gamma_p \left(\frac{\sqrt{\sum_{i=1}^{N} x_i^2}}{t^{\frac{1}{\lambda}}} \right)^{\frac{p}{p-1}} \right\}_{+}^{\frac{p-1}{p-2}} = \mathcal{B}(x,t)$$

and thus the function

$$C(y,t) = \left\{ 1 - \gamma_p |y|^{\frac{p}{p-1}} \right\}_{+}^{\frac{p-1}{p-2}}$$

is independent from t, and

$$\nabla_{y}\mathcal{C} = -\gamma_{p}\left(\frac{p}{p-2}\right)\left\{1-\gamma_{p}|y|^{\frac{p}{p-1}}\right\}_{+}^{\frac{1}{p-2}}|y|^{\frac{2-p}{p-1}}y = -\gamma_{p}\left(\frac{p}{p-2}\right)\mathcal{C}^{\frac{1}{p-1}}|y|^{\frac{2-p}{p-1}}y.$$

Thus by calculation we have that $C(y) = t^{\frac{N}{\lambda}} \mathcal{B}(y, t)$ solves the zero flux equation

$$\begin{split} |\nabla_{\mathbf{y}}\mathcal{C}|^{p-2}\nabla_{\mathbf{y}}\mathcal{C} + \frac{\mathcal{y}\mathcal{C}}{\lambda} &= \\ & \left[\gamma_p \left(\frac{p}{p-2}\right)\mathcal{C}^{\frac{1}{p-1}}\right]^{p-2} |y|^{\frac{2-p}{p-1}(p-2)}|y|^{p-2} \left[-\gamma_p \left(\frac{p}{p-1}\right)\mathcal{C}^{\frac{1}{p-1}}|y|^{\frac{2-p}{p-1}}y\right] + \frac{\mathcal{y}\mathcal{C}}{\lambda} &= \\ & \mathcal{C}\left[\frac{1}{\lambda} - \gamma_p \left(\frac{p}{p-2}\right)^{p-1}\right]y = 0, \quad \text{for} \quad \gamma = \left(\frac{p-2}{p}\right)^{p-1}\frac{1}{\lambda}. \end{split}$$

Consequently, so does $\mathcal{B}(x, t)$. Now we show that the converse reasoning holds too, in order to show how the whole calculation is in fact reduced to a ODE solution.

3.3 Function C Solves a Particular ODE

Consider

$$C(\eta) = \left\{ 1 - \gamma_p \eta^{\frac{p}{p-1}} \right\}_+^{\frac{p-1}{p-2}} = C(|y|), \quad \eta > 0.$$
(38)

In $0 \le \eta < \left(\frac{1}{\gamma_p}\right)^{\frac{p-1}{p}}$ we have

$$\mathcal{C}(\eta)^{\frac{p-2}{p-1}} = 1 - \gamma_p \eta^{\frac{p}{p-1}}.$$

We derive the equation to obtain

$$\left(\frac{p-1}{p-2}\right)\mathcal{C}(\eta)^{-\frac{1}{p-1}}\mathcal{C}'(\eta)d\eta = -\left(\frac{p-2}{p}\right)\frac{1}{\lambda^{1/(p-1)}}\left(\frac{p}{p-1}\right)\eta^{\frac{1}{p-1}}d\eta$$

Now, we manipulate the equation with $C'(\eta) \leq 0$, because

$$\mathcal{C}'(\eta) = \left(\frac{p-1}{p-2}\right) \left\{ 1 - \gamma_p \eta^{\frac{p}{p-1}} \right\}_+^{-\frac{1}{p-2}} \left(-\gamma\left(\frac{p}{p-1}\right) \eta^{\frac{1}{p-1}} \right) \le 0$$

so that

$$\left(\frac{(-\mathcal{C}'(\eta))^{p-1}}{\mathcal{C}(\eta)}\right)^{\frac{1}{p-1}} = \left(\frac{\eta}{\lambda}\right)^{\frac{1}{p-1}}$$

and so the desired mono-dimensional Fokker-Planck equation is obtained

$$|\mathcal{C}'(\eta)|^{p-2}\mathcal{C}'(\eta) + \frac{\eta \mathcal{C}(\eta)}{\lambda} = 0.$$
(39)

If one reads conversely from the end to the beginning of these calculations, it is clear how to arrive to a solution to the isotropic Fokker Planck equation (36) by imposing radial symmetry.

4 Solving the Isotropic Cauchy Problem with Measure Data

Suppose now that we are not able to solve by radial symmetry the isotropic Fokker-Planck equation (36). If we look for a solution to (26) that exhibits the properties (30)–(32), we may adopt the following strategy. First we find a general solution *u* to (26) with datum the Dirac measure δ_o , we show that it is positive by the maximum principle, and then we use the transformation (33) to get a solution *w* to (36). Observe that a comparison principle for subsolutions to the *p*-Laplace equation can be transported to a comparison principle for subsolutions to the isotropic Fokker-Planck equation. But we need a solution to the stationary Fokker-Planck equation to recover the self-similarity (see Remark 3), so that we can control the behavior for all times by scaling, and we gain for free the correct evolution of its support. More generally speaking, if the initial data in (22) is given by

$$u_0(\cdot, 0) = \mu, \tag{40}$$

where μ is a σ —finite Borel measure in \mathbb{R}^N , then we say that u is a *weak solution* of (22) *with measura data* if for every bounded open set $\Omega \subset \mathbb{R}^N$ and $\forall t \in (0, T)$, u satisfies the above integral equality (22) with the right-hand side replaced by

$$\int_{\Omega}\varphi(x,0)d\mu,$$

 $\forall \varphi \in C^1(\overline{\Omega_T})$ such that $x \to \varphi(x, t)$ is compactly supported in $\Omega \forall t \in [0, T]$.

In the pioneering work [12] for the isotropic *p*-Laplace, the authors consider a way of measuring the growth of a function $f \in L^1_{loc}(\mathbb{R}^N)$ as $|x| \to \infty$ by setting

$$|||f|||_{r} := \sup_{\rho \ge r} \rho^{-\lambda/(p-2)} \int_{B_{\rho}} |f| dx, \quad r > 0, \quad \lambda = N(p-2) + p$$

Note that if $f \in L^1(\mathbb{R}^N)$ then $|||f|||_r < \infty$, $\forall r > 0$. Similarly, if μ is a σ -finite Borel measure in \mathbb{R}^N , we set

$$|\|\mu\||_r := \sup_{\rho \ge r} \rho^{-\lambda/(p-2)} \int_{B_{\rho}} |d\mu|_r$$

where $|d\mu|$ is the variation of μ .

In that Fundamental work, the authors demonstrate the existence of a weak solution to the problem (22) in its isotropic configuration, within $\Sigma_T = \Sigma_T(\mu)$, where

$$T(\mu) = \begin{cases} C_0(N, p) \bigg[\lim_{r \to \infty} |\|\mu\||_r \bigg]^{(2-p)}, & \text{if } \lim_{r \to \infty} |\|\mu\||_r > 0 \\ +\infty & \text{if } \lim_{r \to \infty} |\|\mu\||_r = 0. \end{cases}$$
(41)

So the existence is proved in a cylindrical domain whose last time *T* is dictated by the behavior at infinity of the initial measure μ . The method relies on suitable estimates and compactness, which permit a standard limiting process. Indeed, given a σ —finite Borel measure μ in \mathbb{R}^N satisfying $|||\mu|||_r < \infty$ for some r > 0, there exists a sequence of regular functions $\{u_{0,n}\}_{n\in\mathbb{N}} \in C_o^{\infty}(\mathbb{R}^N)$ such that $\forall \varphi \in C_o(\mathbb{R}^N)$ we have

$$\int_{\mathbb{R}^N} u_{0,n} \varphi \, dx \to \int_{\mathbb{R}^N} \varphi d\mu, \quad \& \quad |||u_{0,n}|||_r \to |||\mu|||_r, \quad r > 0.$$

The Cauchy Problem

$$\begin{cases} u_t - \operatorname{div}(|Du|^{p-2}Du) = 0 & \text{in } \Sigma_T, \quad p > 2, \\ u(\cdot, 0) = u_{0,n}. \end{cases}$$
(42)

has a unique solution u_n , global in time (see [6]). Next, the authors prove the following estimates, for all $0 < t < T_r(\mu) := C_0[|||\mu||_r]^{(2-p)}, \forall \rho \ge r > 0$:

$$\||u(\cdot,t)\||_{r} \le C_{1}(N,p)\||\mu\||_{r},$$
(43)

$$\|u(\cdot,t)\|_{L^{\infty}(B_{\rho})} \le C_{2}(N,p)t^{-N/\lambda}\rho^{p/(p-2)}\|\|\mu\|\|_{r}^{p/\lambda},$$
(44)

$$\|Du(\cdot,t)\|_{L^{\infty}(B_{\rho})} \le C_{3}(N,p)t^{-(N+1)/\lambda}\rho^{2/(p-2)}\||\mu\||_{r}^{2/\lambda},$$
(45)

$$\int_0^T \int_\Omega |Du|^q dx d\tau \le C_4(N, P, \epsilon, \operatorname{diam}\Omega) |||\mu|||_r^{C_5(N, p, \epsilon)}, \quad q = p - (N + \epsilon)/(N + 1),$$
(46)

and in particular with $\epsilon = 1$ we obtain

$$\int_{0}^{t} \int_{B_{\rho}} |Du|^{p-1} dx d\tau \le C_{5}(N.p) t^{1/\lambda} \rho^{1+\lambda/(p-2)} |\|\mu\||_{r}^{1+(p-2)/\lambda}$$
(47)

Moreover the function $(x, t) \rightarrow Du(x, t)$ is Hölder continuous in $\overline{\Omega} \times [\eta, T(\mu) - \eta]$, $0 < \eta < T(\mu)$, with Hölder constants and exponents depending upon $N, p, C_1, ..., C_4$, diam $\Omega, \eta, |||\mu|||_r$. It can be shown that their estimates are sharp, by means of Barenblatt solutions. Finally, the estimates above (43)–(45) with a monotonicity property as (4), permit to pass to the limit in the approximating problems (42).

5 An Application of \mathcal{B} to Intrinsic Harnack Estimates

In this section we outline the importance of the construction of a Barenblatt Fundamental solution for the aim of proving regularity. Indeed the rough idea is that once that we have a solution of (23) whose support and positivity can be easily manipulated, by means of a comparison argument is possible to expand the positivity set of a whatever solution that is bigger than the Fundamental one in the parabolic boundary. More precisely we will review the proof of the following Theorem of [10].

Theorem 1 Let u be a non-negative weak solution of Eq. (23) in $\Omega_T = \Omega \times [0, T]$ where $\Omega \subset \mathbb{R}^N$ bounded open set. Fix a point $(x_0, t_0) \in \Omega_T$ and assume $u(x_0, t_0) > 0$. There exist constants $\gamma > 1$ and C > 1, depending only on N, p, such that

$$u(x_0, t_0) \le \gamma \inf_{B_{\rho}(x_0)} u(\cdot, t_0 + \theta), \quad \theta = \frac{C\rho^p}{[u(x_0, t_0)]^{p-2}},$$
(48)

provided the cylinder

$$Q_{4\rho}(\theta) = \{ |x - x_0| < 4\rho \} \times \{ t_0 - 4\theta, t_0 + 4\theta \}$$
(49)

is contained in Ω_T .

Remark 4 As we can see, the geometry is intrinsically defined by the value of the solution in (x_0, t_0) . This brings to light a difficulty in exposition, as a priori weak solutions to (23) are not meant to be well defined in every point. Nonetheless by standard regularity theory we know that local weak solutions to (23) are locally Hölder continuous, and so they are well defined pointwise as elements of $C(0, T; W_{loc}^{1,p}(\Omega))$.

Remark 5 The constants γ and C in previous Theorem tend to infinity as p tend to infinity, but they are stable as $p \downarrow 2$ in the following meaning

$$\lim_{p \downarrow 2} \gamma(N, p) = \gamma(N, p), \quad \text{and} \quad \lim_{p \downarrow 2} C(N, p) = C(N, p).$$
(50)

5.1 Outline of the Proof of Theorem 1

For the sake of conciseness ad to the aim of highlighting the importance of Barenblatt Fundamental solutions, we will demonstrate only the case when p is not too close to 2. The proof for $p \in (2, 5/2]$ uses local comparison functions built especially to do the same job of \mathcal{B} , being subsolutions of (23) and observing the same ordering imposed by the following Lemma.

Lemma 2 Let u, v be two solutions of (23) in $\Omega_T = \Omega \times [0, T]$ such that $u, v \in C(0, T; L^2(\Omega)) \cap L^p(0, T; W^{1,p}(\Omega)) \cap C(\overline{\Omega_T})$. If $u \ge v$ in the parabolic boundary of Ω_T , then $u \ge v$ in Ω_T .

STEP 1. Transforming the problem by scaling.

Let $(x_0, t_0) \in \Omega_T$, $\rho > 0$ to be fixed a posteriori, assume that $u(x_0, t_0) > 0$ and for a constant *C* to be determined later let $Q_{4\rho}$ be the box

$$Q_{4\rho} = \{ |x - x_0| < 4\rho \} \times \left\{ t_0 - \frac{4C\rho^p}{[u(x_0, t_0)]^{p-2}}, t_0 + \frac{4C\rho^p}{[u(x_0, t_0)]^{p-2}} \right\}.$$
 (51)

Now introduce the change of variables

$$\Phi(x,t) = \left(\frac{x-x_0}{\rho}, \frac{(t-t_0)[u(x_0,t_0)]^{p-2}}{\rho^p}\right), \qquad \Phi(Q_{4\rho}) = B_4 \times (-4C, 4C) =: Q$$
(52)

Let us denote again with x, t the new variables $\Phi(x, t)$, and observe that the function

$$v(x,t) = \frac{1}{u(x_0,t_0)} u\left(x_0 + \rho x, \frac{t\rho^p}{[u(x_0,t_0]^{p-2})}\right),$$
(53)

is a bounded non-negative solution to the Cauchy problem

$$\begin{cases} v_t - \operatorname{div}(|Dv|^{p-2}Dv) = 0, \quad (x,t) \in Q\\ v(0,0) = 1. \end{cases}$$
(54)

Theorem 1 will be proved, as shown by a simple converse rescaling, if we are able to find constants $\gamma_o \in (0, 1], C > 1$ depending only upon *N*, *p* holding the inequality

$$\inf_{B_1} v(x, C) \ge \gamma_o. \tag{55}$$

The constant γ_o defined successively in (62) tends to zero as $p \downarrow 2$. STEP 2. *Finding qualitatively a point where v equals a power-like function of time.* We consider the family of nested and expanding boxes

 $Q_{\tau} = \{ |x| < \tau \} \times (-\tau^{p}, 0], \qquad \tau \in (0, 1]$ (56)

and for each of these boxes we consider the numbers

$$M_{\tau} = \sup_{Q_{\tau}} v, \qquad N_{\tau} = (1 - \tau)^{-b}, \tag{57}$$

where the number b > 0 will be suitably defined later to render quantitative the following estimate. As $M_0 = N_0$ and considering that M_{τ} remains a bounded

function of τ (because v is a *bounded* solution) while $N_{\tau} \to +\infty$ when τ tends to 1, we can choose a number τ_o to be the largest root of the equation

$$M_{\tau} = N_{\tau}$$

This implies by construction

$$\sup_{Q_{\tau}} v \le N_{\tau}, \qquad \forall \tau > \tau_o.$$
⁽⁵⁸⁾

Since v is continuous in Q there exists at least one point $(\bar{x}, \bar{t}) \in \overline{Q_{\tau_0}}$ such that

$$v(\bar{x}, \bar{t}) = N_{\tau_0} = (1 - \tau_0)^{-b}.$$
(59)

STEP 3. Ordering v and $(1 - \tau_o)^{-b}$ within a small ball centered in \bar{x} . Let

$$R=\frac{1-\tau_o}{2},$$

and consider the cylinder $[(\bar{x}, \bar{t}) + Q(R^p, R)] = \{|x - \bar{x}| < R\} \times \{\bar{t} - R^p, \bar{t}\}$. As $\tau_o \in (0, 1]$ we have the inclusion $[(\bar{x}, \bar{t}) + Q(R^p, R)] \subset Q_{\frac{1+\tau_o}{2}}$ which implies

$$\sup_{[(\bar{x},\bar{t})+Q(R^{p},R)]} v \le N_{\frac{1+\tau_{o}}{2}} = 2^{b}(1-\tau_{o})^{-b} =: \omega.$$

Now we use Hölder continuity of the function v in the fashion of Proposition 3.1 of Chap. III of [10], choosing b > 0 so large that the starting one of the family of shrinking cylinders is contained in $[(\bar{x}, \bar{t}) + Q(R^p, R)]$. Hence there exist $\gamma > 1$ and $a, \varepsilon_o \in (0, 1)$ such that for all $r \in (0, R]$ we have

$$\sup_{[(\bar{x},\bar{t})+Q(R^{p},R)]} v(\cdot,\bar{t}) \leq \gamma(\omega+R^{\varepsilon_{o}}) \left(\frac{r}{R}\right)^{a}$$

$$\leq 2^{b+1} \gamma (1-\tau_{o})^{-b} \left(\frac{r}{R}\right)^{a}$$

$$(60)$$

We let $r = \sigma R$ and we choose σ so small that for all $\{|x - \bar{x}| < \sigma R\}$ we obtain

$$v(x,\bar{t}) \ge v(\bar{x},\bar{t}) - 2^{b+1}\gamma(1-\tau_o)^{-b}\sigma^a$$

$$(1-2^{b+1})\gamma\sigma^a)(1-\tau_o)^{-b}$$

$$\frac{1}{2}(1-\tau_o)^{-b}, \quad \forall \{|x-\bar{x}|\} < \sigma R, \quad R = \frac{1}{2}(1-\tau_o)$$
(61)

STEP 5. Expansion of the positivity set and conclusion.

In this last step we will choose the constants b > 1 and C > 1 so that the qualitative largeness of $v(\cdot, \bar{t})$ in the small ball $B_{\sigma R}(\bar{x})$ turns into a quantitative bound below over the full sphere B_1 at some later time level *C*. This will be carried on by means of the comparison with the functions $\mathcal{B}_{k,\rho}$ defined in (28) by

$$\mathcal{B}_{k,\rho}(x,t,\bar{x},\bar{t}) = \frac{k\rho^{N}}{S^{\frac{N}{\lambda}}(t)} \left\{ 1 - \left(\frac{|x-\bar{x}|}{S^{\frac{1}{\lambda}}(t)}\right)^{\frac{p}{p-1}} \right\}_{+}^{\frac{p-1}{p-2}},$$
$$S(t) = \lambda \left(\frac{p}{p-2}\right)^{p-1} k^{p-2} \rho^{N(p-2)}(t-\bar{t}) + \rho^{\lambda}.$$

Indeed, we choose appropriately

$$k = \frac{1}{2}(1 - \tau_o)^{-b}, \qquad \rho = \sigma R,$$

and we observe that at the time level t = C the support of $\mathcal{B}_{k,\rho}(\cdot, C, \bar{x}, \bar{t})$ is the ball

$$|x - \bar{x}|^{\lambda} < S(t) = \{ d\gamma^{p-2} (1 - \tau_o)^{(N-b)/(p-2)} (C - \bar{t}) + (\sigma R)^{\lambda} \}$$

for

$$\gamma(N, b) = \frac{1}{2} \left(\frac{\sigma}{2}\right)^N$$
, and $d = \lambda \left(\frac{p}{p-2}\right)^{p-1}$.

Now choose

$$b = N, \qquad C = \frac{3^{\lambda}}{d\gamma^{p-2}}, \tag{62}$$

so that the support of $\mathcal{B}_{k,\rho}(\cdot, C, \bar{x}, \bar{t})$ contains B_2 and we can use the comparison principle with v as we have in B_{ρ}

$$v(\cdot, \bar{t}) \ge \frac{1}{2} (1 - \tau_o)^{-N} = k \ge B_{k,\rho}(\cdot, \bar{t}).$$
(63)

Thence

$$\inf_{x \in B_{1}} v(x, C) \ge \inf_{x \in B_{1}} B_{k,\rho}(x, C, \bar{x}, \bar{t})
\ge 2^{-(1+2N/\lambda)} \left(\frac{\sigma}{2}\right)^{N} \left\{ 1 - \left(\frac{2}{3}\right)^{\frac{p}{p-1}} \right\}^{\frac{p-1}{p-2}} =: \gamma_{o},$$
(64)

and the proof is concluded.

6 Looking for a Barenblatt-Type Solution to (1)

In this section we calculate the right exponents for the transformation of Eq. (1) into an anisotropic Fokker-Planck equation. Next we observe that the impossibility of using radial solutions does not allow us to obtain an ODE from the Fokker-Planck equation. Finally we show a strategy to find a non-explicit Barenblatt Fundamental solution.

Remark 6 Observe initially that we can construct a source-type solution, but that unfortunately has not a compact support. Indeed, consider the following solution to (1). Let $i \in \{1, ..., N\}$ and

$$f_i(x_i, t, T_i) = \kappa_i \left(\frac{|x_i|^{p_i}}{(T_i - t)}\right)^{\frac{1}{p_i - 2}}, \quad \kappa_i = \kappa_i(p_i) > 0, \quad p_i > 2,$$
(65)

be solutions of the equations

$$u_t - (|u_{x_i}|^{p_i - 2} u_{x_i})_{x_i} = 0, \quad x_i \in \mathbb{R}, \quad t > 0.$$
(66)

Then the function

$$\mathcal{F}(x,t) = \sum_{i=1}^{N} f_i(x_i, t, T_i)$$

= $\sum_{i=1}^{N} \kappa_i \left(\frac{|x_i|^{p_i}}{(T_i - t)}\right)^{\frac{1}{p_i - 2}}$ (67)

solves the prototype equation (1). The same can be done by choosing $f_i \equiv B_i$ the mono-dimensional Barenblatt solutions solving (66). These functions reveal some of the physical aspects of Eq. (1): for instance they can be used to show that the lifetime of solutions is dictated by the largest exponent p_N in the case of large initial mass (see Remark 3 in [8]). Unfortunately solutions so-built do not have a compactly supported evolution and we cannot use them to expand the positivity by comparison as done in Sect. 5.

6.1 Finite Speed of Propagation

Consider the Cauchy problem

$$\begin{cases} u_t = \operatorname{div}(\mathbf{A}(t, x, u, \nabla u)), & \text{in } \Sigma_T = \mathbb{R}^N \times (0, T), \\ u(x, 0) = u_0(x) \in L^2(\mathbb{R}^N), \end{cases}$$
(68)

where $\mathbf{A}(t, x, u, \nabla u) = (A_i(x, t, u, \nabla u))_{i=1,...,N}$ is a Caratheodory vector field satisfying the growth conditions (3). In [14] the authors proved the following decay properties, that will be useful to us to intercept the right exponents in the scaling transformation leading to the Fokker-Planck equation for solutions to (1).

Theorem 2 Suppose that $p_i > 2$ for all $i \in \{1, ..., N\}$. Let u be a local weak solution to (68) in Σ_T under the growth conditions (3) with

$$u_0 \in L^2(\mathbb{R}^N), \qquad \emptyset \neq supp(u_0) \subseteq [-R_0, R_0]^N$$
(69)

Then there is a solution $\tilde{u} \neq 0$ such that

$$supp(\tilde{u}(\cdot,t)) \subseteq \prod_{i=1}^{N} [-R_j(t), R_j(t)],$$
(70)

for any t < T, where

$$R_{j}(t) = 2R_{0} + Ct^{\frac{N(\bar{p}-p_{j})+\bar{p}}{\lambda p_{j}}} ||u_{0}||_{1}^{\frac{\bar{p}}{p_{j}}\frac{p_{j}-2}{\lambda}}, \qquad \lambda = N(\bar{p}-2) + \bar{p}.$$
(71)

Moreover, they proved the following L^{∞} - L^{1} estimates of the decay for the solution.

Theorem 3 Let $\bar{p} < N$ and let $u \in \bigcap_{i=1}^{N} \mathcal{L}^{p_i}(\Sigma_T)$ solve (68) for $u_0 \in L^1(\mathbb{R}^N) \cap L^2(\mathbb{R}^N)$. Then if $p_i > 2$, $\forall i = 1, ..., N$ the following estimate holds true for any $\tau \in [0, T]$

$$||u(\cdot,t)||_{L^{\infty}(\mathbb{R}^{N})} \leq Ct^{-\frac{N}{\lambda}}||u_{0}||_{L^{1}(\mathbb{R}^{N})}^{\frac{\bar{p}}{\lambda}}.$$
(72)

.

6.2 The Anisotropic Fokker-Planck Equation

We consider a similar continuous transformation as (17), owing the choice of the right exponent to the decay of a solution to (68), and we perform the following formal calculations.

$$u(x,t) = t^{-\beta} v \left(x_1 t^{\alpha_1}, \dots, x_N t^{\alpha_N}, t \right) = t^{-\beta} v(y_1, \dots, y_N, t), \qquad \begin{cases} y_i = x_i t^{\alpha_i}, \\ \frac{\partial}{\partial x_i} = t^{\alpha_i} \frac{\partial}{\partial y_i}. \end{cases}$$
(73)

We calculate formally

$$u_t = -\beta t^{-\beta-1} v + t^{-\beta} \bigg[\sum_{i=1}^N \bigg(\frac{\partial}{\partial y_i} v \bigg) \frac{\partial y_i}{\partial t} + v_t \bigg] = -\beta t^{-\beta-1} v + t^{-\beta} \sum_{i=1}^N \bigg(\frac{\partial}{\partial y_i} v \bigg) \bigg[\frac{\alpha_i x_i t^{\alpha_i}}{t} \bigg] + t^{-\beta} v_t,$$

being

$$\frac{\partial}{\partial x_i}u = t^{\alpha_i - \beta} \frac{\partial}{\partial y_i}v.$$

We substitute these into (1) to get

$$-\beta t^{-\beta-1}v + t^{-\beta} \sum_{i=1}^{N} \frac{\alpha_i y_i}{t} \left(\frac{\partial}{\partial y_i}v\right) + t^{-\beta} v_i = \sum_{i=1}^{N} t^{\alpha_i} \frac{\partial}{\partial y_i} \left(t^{(\alpha_i-\beta)(p_i-1)} \left|\frac{\partial}{\partial y_i}v\right|^{p_i-2} \frac{\partial}{\partial y_i}v\right).$$

Re-ordering and multiplying each term for $t^{\beta+1}$ we get

$$tv_{t} = \beta v - \sum_{i=1}^{N} \alpha_{i} y_{i} \frac{\partial}{\partial y_{i}} v + \sum_{i=1}^{N} t^{(\alpha_{i} - \beta)(p_{i} - 1) + \alpha_{i} + \beta + 1} \frac{\partial}{\partial y_{i}} \left(\left| \frac{\partial}{\partial y_{i}} v \right|^{p_{i} - 2} \frac{\partial}{\partial y_{i}} v \right) = \beta v + \sum_{i=1}^{N} \alpha_{i} v + \sum_{i=1}^{N} \frac{\partial}{\partial y_{i}} \left[\left(\left| \frac{\partial}{\partial y_{i}} v \right|^{p_{i} - 2} \frac{\partial}{\partial y_{i}} v \right) - \alpha_{i} y_{i} v \right],$$

by choosing

$$(\alpha_i - \beta)(p_i - 1) + \alpha_i + \beta + 1 = 0,$$

which means

$$\alpha_i = \beta - \frac{1+2\beta}{p_i} < 0. \tag{74}$$

This is an Euler equation. So, by redefining $v(y, t) = w(y, \ln(t))$ Eq. (1) becomes the non-homogeneous Fokker-Planck equation

$$w_{t} = \left(\beta + \sum_{i=1}^{N} \alpha_{i}\right)w + \sum_{i=1}^{N} \frac{\partial}{\partial y_{i}} \left[\left(\left| \frac{\partial}{\partial y_{i}} w \right|^{p_{i}-2} \frac{\partial}{\partial y_{i}} w \right) - \alpha_{i} y_{i} w \right].$$
(75)

If, according to (72), we consider

$$\beta = \frac{N}{N(\bar{p}-2) + \bar{p}},\tag{76}$$

then the equation reduces to

$$w_t = \sum_{i=1}^{N} \frac{\partial}{\partial y_i} \left[\left(\left| \frac{\partial}{\partial y_i} w \right|^{p_i - 2} \frac{\partial}{\partial y_i} w \right) - \alpha_i y_i w \right].$$
(77)

Remark 7 Equation (77) conserves the $L^1(\Omega)$ -norm in time.

Moreover, a solution to the stationary version of (77) would give us the wanted Barenblatt Fundamental solution to (1).

This anisotropic Fokker-Planck type equation is deeply different from its isotropic counterpart (36). Anisotropy does not permit the identification of a single variable ODE as in (39), and this is physically evident and due to the lack of radial symmetry of the diffusion process in consideration: there is no homogeneous flux here to be vanished. Moreover the steady equation

$$\sum_{i=1}^{N} \frac{\partial}{\partial y_i} \left[\left(\left| \frac{\partial}{\partial y_i} w \right|^{p_i - 2} \frac{\partial}{\partial y_i} w \right) - \alpha_i y_i w \right], \quad \text{in} \quad \Omega \subset \mathbb{R}^N,$$
(78)

is not a variational one i.e. it is not known if it can be written as the Euler Lagrange equation of an energy functional. Moreover, its monotonicity and coercivity properties suffer heavily the second term influence relatively to the length in the *i*-th direction of the medium Ω . These considerations leading to the difficulty of an explicit formula as in the previous case (24), the existence and the main properties characterizing a Barenblatt Fundamental solution may be derived by the simpler original equation (1) and then defining a suitable function which solves the steady Fokker-Planck equation (78). This would ensure that the solution to (1) found has the properties of Theorem 2, which characterize a Barenblatt Fundamental Solution.

6.3 On the Solvability of the Anisotropic Cauchy Problem with Measure Initial Data

We consider the prototype problem with measure initial data, i.e

$$\begin{cases} u_t - \sum_{i=1}^{N} (|u_{x_i}|^{p_i - 2} u_{x_i})_{x_i} = 0, \quad (x, t) \in \mathbb{R}^N \times [0, T], \\ u(x, 0) = u_0(x), \quad x \in \mathbb{R}^N. \end{cases}$$
(79)

We begin the study of a weak solution to (79) i.e. a function $u \in C(0, T; L^1(\mathbb{R}^N)) \cap L^{\mathbf{p}}(0, T; W^{1,\mathbf{p}}(\mathbb{R}^N))$ such that for each open bounded $\Omega \subset \mathbb{R}^N$ and for all $t \in [0, T)$ satisfies for all test function $\varphi(x, t) \in W^{1,\infty}([0, T, L^{\infty}(\Omega)) \cap L^{\infty}([0, T], W_o^{1,\infty}(\Omega))$ the equality

$$\int_{\Omega} u\varphi(x,t)dx + \sum_{i=1}^{N} \int_{0}^{t} \int_{\Omega} |u_{x_{i}}|^{p_{i}-2} u_{x_{i}}\varphi_{x_{i}}dxd\tau$$
$$= \int_{\Omega} \varphi(x,0)du_{0} + \int_{0}^{t} \int_{\Omega} u\varphi_{\tau}(x,\tau)dxd\tau.$$
(80)

This has been done in [8, 9] for more general doubly nonlinear anisotropic equations. We recall the notation $\lambda = N(\overline{p} - 2) + \overline{p}$. In [8] the authors prove a generalised version of the following a priori estimates.

Theorem 4 Consider the problem (79) with $2 < p_i \le \bar{p}\left(1 + \frac{1}{N}\right)$, $u_0(x) \ge 0$ and

$$\||u_0\||_r := \sup_{\rho \ge r} \rho^{-\frac{\lambda}{N}} \int_{B_\rho} u_0(x) dx < \infty, \quad r > 0,$$
(81)

being

$$B_{\rho} := \left\{ x \in \mathbb{R}^{N} | |x_{i}| \leq \frac{\rho^{\frac{\tilde{p}(p_{i}-2)}{p_{i}(\tilde{p}-2)}}}{2} \right\}$$

Define by monotonicity $M_{\infty} := \lim_{r \to \infty} |||u_0|||_r$ and for a $\gamma > 0$ to be specified later

$$T_* := \begin{cases} \infty, & \text{if } M_{\infty} = 0, \\ \left(\frac{M_{\infty}}{\gamma}\right)^{\frac{N(\overline{p} - p_N) + \overline{p}}{\overline{p}(p_N - 2)}}, & \text{if } M_{\infty} \ge \gamma, \\ \left(\frac{M_{\infty}}{\gamma}\right)^{\frac{N(\overline{p} - p_1) + \overline{p}}{\overline{p}(p_1 - 2)}}, & \text{if } M_{\infty} < \gamma. \end{cases}$$
(82)

Then there exists a positive constant $\gamma(p_i, N)$ such that every nonnegative weak solution to (79) defined on $[0, T_*]$ must satisfy the following estimates for all $t, \bar{t} \in (0, T_*)$:

$$|||u(\cdot,t)|||_{r} \le C|||u_{0}|||_{r}, \tag{83}$$

$$\|u(\cdot,t)\|_{L^{\infty}(B_r)} \le Cr^{\frac{\overline{p}}{N}}t^{-\frac{N}{\lambda}}\||u_0\||_r^{\frac{\overline{p}}{\lambda}},$$
(84)

$$\sum_{i=1}^{N} \int_{0}^{t} \int_{B_{r}} |u_{x_{i}}|^{p_{i}-1} dx d\tau < C(r, t),$$
(85)

$$\sum_{i=1}^{N} \int_{\overline{t}}^{t} \int_{B_{r}} |u_{x_{i}}|^{p_{i}} dx d\tau < C(r, t, \overline{t}).$$

$$(86)$$

Remark 8 For $p_i = p$, $\forall i = 1, ..., N$ estimates (83), (84), (85), (86) and the number $T_* > 0$ do coincide with the ones of Sect. 4 for the isotropic equation found in [12]. Secondly, it is interesting to observe that the lifetime of the solution is determined

by the largest exponent p_N in case of large initial mass $||u_0|||_r$ while it is determined by the smaller p_1 in case of a modest initial mass.

7 Future Strategy and Conclusion

In this note we have proven the strong connection between the Barenblatt Fundamental solution and the solutions to the stationary equation (78). We have shown the existence of solutions to (77) thanks to a recent result in [9]. However, this is not enough to use this result to prove regularity results. Indeed, we can invoke the previous Theorem to find a solution u to (1). We already know that there exists a solution of u that satisfies the growths (70), (72). But what is missing, to repeat the same ideas of Sect. 1, is a nice description *from below* of the support of u. The aim of our next papers is to carry on a deep analysis of the interplay between these two equations and to develop the necessary tools for deriving regularity results and Harnack inequalities for nonnegative solutions to (1).

Acknowledgments Both authors wish to acknowledge to Sunra Mosconi his valuable advice. We would like to thank Andrea Dall'Aglio for helpful conversation on the existence for the Cauchy problem with measure data, and Matias Vestberg for information about the construction of Barenblatt solutions for doubly-nonlinear equations. Moreover, both authors are partially founded by INdAM (GNAMPA).

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